

# Stochastic models and control for power line temperature

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- 2003 event: critical temperatures estimates were sometimes incorrect.

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- It also relies on the heat equation for a “static” calculation.
- Note: power lines can be more than 100 miles long.
- How can we account for data uncertainty, errors, unavailability?

## The heat equation on a 1-dimensional line

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$$\frac{\partial T(x, t)}{\partial t} = \kappa \frac{\partial^2 T(x, t)}{\partial x^2} + \alpha I^2(t) - \nu(T(x, t) - T^{\text{ext}}(x, t)),$$

where  $\kappa \geq 0$ ,  $\alpha \geq 0$  and  $\nu \geq 0$  are (line dependent) constants, and  $T^{\text{ext}}(x, t)$  is the ambient temperature at  $(x, t)$

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$\mathbf{h}(\mathbf{x})$  = a random variable, at  $x$ .

**This paper:** stochasticity in the spatial domain ( $x$ )

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**The goal:** algorithm- and data-driven estimates for “safe”  
current/temperature limits

## Back to the stochastic heat equation

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Recall:  $x \in [0, L]$ ,  $t \in [0, \tau]$

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Integrate and divide by  $L$ , get

$$\frac{1}{L} \int_0^L \frac{\partial T(x, t)}{\partial t} dx = \alpha l^2(t) - \frac{\nu}{L} \int_0^L T(x, t) dx + \frac{\nu}{L} \int_0^L G(\mathbf{h}(\mathbf{x})) dx.$$

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$$\frac{1}{L} \int_0^L \frac{\partial T(x, t)}{\partial t} dx = \frac{d}{dt} \frac{1}{L} \int_0^L T(x, t) dx = \frac{d\mathbf{H}(t)}{dt}.$$

$$\mathbf{H}(t) \triangleq \frac{1}{L} \int_0^L T(x, t) dx \quad (\text{average internal line temperature at } t)$$

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$$\mathbf{R} \triangleq \frac{1}{L} \int_0^L G(\mathbf{h}(\mathbf{x})) dx \quad (\text{average ambient temperature,})$$



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**Solution:**

$$\mathbf{H}(t) = \int_0^t e^{-\nu(t-s)} \alpha l^2(s) ds + \mathbf{R}(1 - e^{-\nu t}) + C e^{-\nu t},$$

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# Adaptive control

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- (b)  $l_1 \leq L(\tau/2)$ .

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- (b)  $l_1 \leq L(\tau/2)$ .
- (c) What about performance?

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**$F(I_1, I_2)$**  : a monotonely increasing function of  $I_1, I_2$

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- (a)  $P(\mathbf{H}(\tau) > k) < \epsilon$ .  $k$  **smaller than** critical temperature
- (b)  $l_1 \leq L(\tau/2)$ .
- (c) Maximize:

$$\sum_{i=1}^n F(l_1, l_{2,i}) p_i$$



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So chance constraint is of the form:

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So chance constraint s of the form:

$$\sum_{i=1}^n \mathbb{I} \left\{ \underbrace{v_1 l_1^2}_{z_1} + \underbrace{v_2 l_2^2(i)}_{z_2(i)} > \underbrace{u - r_i(1 - e^{-\nu\tau}) - Ce^{-\nu\tau}}_{w_i} \right\} p_i \leq \epsilon.$$

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\max \quad & \sum_{i=1}^n \tilde{F}(z_1, z_2(i)) p_i \\
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$$z_1 + z_2(i) = w_i \text{ or } u_i, \quad \text{all } i$$

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→ Use **binary** variable

$$y_i = \begin{cases} 0 & \text{when } z_1 + z_2(i) = w_i \\ 1 & \text{when } z_1 + z_2(i) = u_i \end{cases}$$

## Continuous knapsack problem

$$\begin{aligned} \max \quad & \sum_{i=1}^n \tilde{F}(z_1, w_i - z_i) p_i (1 - y_i) + \tilde{F}(z_1, u_i - z_i) p_i y_i \\ \text{s.t.} \quad & \sum_{i=1}^n u_i p_i y_i \leq \epsilon \\ & 0 \leq z_1 \leq \bar{k} \\ & y_i = 0 \text{ or } 1, \quad \text{all } i. \end{aligned}$$

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**Practicable!**