# Operations Research Problems in Power Engineering

Daniel Bienstock

Columbia University

2016

Bienstock

Columbia University

< □ > < 同 >

-

### References

Andersson: Modelling and Analysis of Electric Power SystemsBergen, Vittal: Power Systems AnalysisGlover, Sarma, Overbye: Power System Analysis and Design

Columbia University

### References

Columbia University

Andersson: Modelling and Analysis of Electric Power SystemsBergen, Vittal: Power Systems AnalysisGlover, Sarma, Overbye: Power System Analysis and Design

Rebours, Kirschen: What is spinning reserve?

▲□▶▲圖▶▲圖▶▲圖▶ 圖 のQ@

Bienstock

Columbia University



Columbia University

Operations Research Problems in Power Engineering



・ロト ・回 ト ・ヨト ・ヨト ・ ヨー うえぐ

Bienstock

Columbia University



▲口 ▶ ▲聞 ▶ ▲臣 ▶ ▲臣 ▶ ― 臣 … 釣��

Bienstock

Columbia University



Bienstock Operations Research Problems in Power Engineering Columbia University



Bienstock

Columbia University



A generator produces **current** at a certain **voltage**.

Bienstock

Columbia University

< A



< A

Columbia University

A generator produces **current** at a certain **voltage**. **Ohm's law:** power = current x voltage



Bienstock

Columbia University

(日)

### AC Power Flows

- \* ロ \* \* @ \* \* 注 \* \* 注 \* の < @

Bienstock

Columbia University



### **Real-time:**



Bienstock

Columbia University

### AC Power Flows

#### Real-time:



- Voltage at bus k:  $v_k(t) = V_k^{max} \cos(\omega t + \theta_k^V)$
- Current injected at k into km:  $i_{km}(t) = I_{km}^{max} \cos(\omega t + \theta_{km}^{I})$ .

Columbia University

\* ロ > \* 部 > \* 注 >

### AC Power Flows

#### Real-time:



- Voltage at bus k:  $v_k(t) = V_k^{max} \cos(\omega t + \theta_k^V)$
- Current injected at k into km:  $i_{km}(t) = I_{km}^{max} \cos(\omega t + \theta_{km}^{l})$ .
- Power injected at k into km:  $p_{km}(t) = v_k(t)i_{km}(t)$ .

Averaged over period T:

$$\bullet p_{km} \doteq \frac{1}{T} \int_0^T p(t) = \frac{1}{2} V_k^{max} I_{km}^{max} \cos(\theta_k^V - \theta_{km}^I).$$

A B A A B A A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A



$$p_{km} \doteq \frac{1}{T} \int_0^T p(t) = \frac{1}{2} V_k^{max} I_{km}^{max} \cos(\theta_k^V - \theta_{km}^I)$$

< ≣ ▶ ≣ ৵৭৫ Columbia University

イロン イヨン イヨン イヨン

Operations Research Problems in Power Engineering



イロン イヨン イヨン イヨン

Operations Research Problems in Power Engineering



$$V_k \doteq rac{V_k^{max}}{\sqrt{2}} e^{j heta_k^V}, \quad I_{km} \doteq rac{I_{km}^{max}}{\sqrt{2}} e^{j heta_{mk}^I}$$

・ロン ・回と ・ヨン ・ヨン

Operations Research Problems in Power Engineering



$$V_{k} \doteq \frac{V_{k}^{max}}{\sqrt{2}} e^{j\theta_{k}^{V}}, \quad I_{km} \doteq \frac{I_{km}^{max}}{\sqrt{2}} e^{j\theta_{mk}^{I}}$$

イロン イヨン イヨン イヨン

Bienstock



$$V_k \doteq rac{V_k^{max}}{\sqrt{2}} e^{j heta_k^V}, \quad I_{km} \doteq rac{I_{km}^{max}}{\sqrt{2}} e^{j heta_{mk}^I}$$

$$p_{km} = |V_k||I_{km}|\cos(\theta_k^V - \theta_{km}^I) = \mathcal{R}e(V_k I_{km}^*)$$
$$q_{km} \doteq Im(V_{km}I_{km}^*) \text{ and } S_{km} \doteq p_{km} + jq_{km}$$

< □ > < □ > < □ > < □ > < □ >

Bienstock

$$V_{k} \doteq \frac{V_{k}^{max}}{\sqrt{2}} e^{j\theta_{k}^{V}}, \quad I_{km} \doteq \frac{I_{km}^{max}}{\sqrt{2}} e^{j\theta_{mk}^{\prime}} \text{ (voltage, current)}$$

$$p_{km} = \mathcal{R}e(V_{k}I_{km}^{*}), \quad q_{km} = Im(V_{km}I_{km}^{*})$$

$$(1)$$

ে≣ ►িছি পি ৭০ Columbia University

イロン イヨン イヨン イヨン

Operations Research Problems in Power Engineering

$$V_{k} \doteq \frac{V_{k}^{max}}{\sqrt{2}} e^{j\theta_{k}^{V}}, \quad I_{km} \doteq \frac{I_{km}^{max}}{\sqrt{2}} e^{j\theta_{mk}^{I}} \text{ (voltage, current)}$$

$$p_{km} = \mathcal{R}e(V_{k}I_{km}^{*}), \quad q_{km} = Im(V_{km}I_{km}^{*}) \tag{1}$$

$$I_{km} = \mathbf{y}_{\{\mathbf{k},\mathbf{m}\}}(V_k - V_m),$$

ে≣ ►িছি পি ৭০ Columbia University

イロン イヨン イヨン イヨン

Operations Research Problems in Power Engineering

$$V_{k} \doteq \frac{V_{k}^{max}}{\sqrt{2}} e^{j\theta_{k}^{V}}, \quad I_{km} \doteq \frac{I_{km}^{max}}{\sqrt{2}} e^{j\theta_{mk}^{I}} \text{ (voltage, current)}$$

$$p_{km} = \mathcal{R}e(V_{k}I_{km}^{*}), \quad q_{km} = Im(V_{km}I_{km}^{*}) \tag{1}$$

$$I_{km} = \mathbf{y}_{\{k,m\}}(V_k - V_m), \ \mathbf{y}_{\{k,m\}} = admittance of \ km.$$
(2)

ে≣ ►িছি পি ৭০ Columbia University

イロン イヨン イヨン イヨン

Operations Research Problems in Power Engineering

$$V_{k} \doteq \frac{V_{k}^{max}}{\sqrt{2}} e^{j\theta_{k}^{V}}, \quad I_{km} \doteq \frac{I_{km}^{max}}{\sqrt{2}} e^{j\theta_{mk}^{I}} \text{ (voltage, current)}$$

$$p_{km} = \mathcal{R}e(V_{k}I_{km}^{*}), \quad q_{km} = Im(V_{km}I_{km}^{*}) \tag{1}$$

$$I_{km} = \mathbf{y}_{\{k,m\}}(V_k - V_m), \ \mathbf{y}_{\{k,m\}} = admittance \text{ of } km.$$
(2)

### **Network Equations**



Columbia University

A B + 
 A
 B + 
 A
 B
 A
 A
 B
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

Bienstock

$$V_{k} \doteq \frac{V_{k}^{max}}{\sqrt{2}} e^{j\theta_{k}^{V}}, \quad I_{km} \doteq \frac{I_{km}^{max}}{\sqrt{2}} e^{j\theta_{mk}^{I}} \text{ (voltage, current)}$$

$$p_{km} = \mathcal{R}e(V_{k}I_{km}^{*}), \quad q_{km} = Im(V_{km}I_{km}^{*})$$

$$(3)$$

$$I_{km} = \mathbf{y}_{\{k,m\}}(V_k - V_m), \ \mathbf{y}_{\{k,m\}} = admittance \text{ of } km.$$
(4)

### **Network Equations**

$$\sum_{km\in\delta(k)}p_{km} = \hat{P}_k, \quad \sum_{km\in\delta(k)}q_{km} = \hat{Q}_k \quad \forall k \qquad (5)$$

(日)

Columbia University

Bienstock

$$V_{k} \doteq \frac{V_{k}^{max}}{\sqrt{2}} e^{j\theta_{k}^{V}}, \quad I_{km} \doteq \frac{I_{km}^{max}}{\sqrt{2}} e^{j\theta_{mk}^{I}} \text{ (voltage, current)}$$

$$p_{km} = \mathcal{R}e(V_{k}I_{km}^{*}), \quad q_{km} = Im(V_{km}I_{km}^{*})$$

$$(3)$$

$$I_{km} = \mathbf{y}_{\{k,m\}}(V_k - V_m), \ \mathbf{y}_{\{k,m\}} = admittance \text{ of } km.$$
(4)

#### **Network Equations**

$$\sum_{km\in\delta(k)}p_{km} = \hat{P}_k, \quad \sum_{km\in\delta(k)}q_{km} = \hat{Q}_k \quad \forall k \qquad (5)$$

A B + 
 A
 B + 
 A
 B
 A
 A
 B
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

Columbia University

**Generator:**  $\hat{P}_k$ ,  $|V_k|$  given. Other buses:  $\hat{P}_k$ ,  $\hat{Q}_k$  given.

Bienstock

#### Managing changing demands





Columbia University

< □ > < 同 >

#### Bienstock



Bienstock

Operations Research Problems in Power Engineering

Columbia University

(日) (四) (日) (日) (日)



Bienstock

Columbia University



▲日 ▶ ▲圖 ▶ ▲ 圖 ▶ ▲ 圖 → 今 ♀ ⊙

Bienstock

Columbia University



#### Frequency response:

- \* ロ > \* 個 > \* 注 > \* 注 > - 注 - うへで

Columbia University

Bienstock



# Frequency response:

mismatch  $\Delta P$ 

Bienstock

Columbia University



#### Frequency response:

mismatch  $\Delta P \Rightarrow$  frequency change  $\Delta \omega \approx -c \Delta P$ 

Bienstock

Columbia University

# Managing changing demands

Primary frequency control. Handles instantaneous (small) changes.

▲ロト ▲聞 と ▲臣 と ★臣 と 三臣 … のへ(

Bienstock

Columbia University

### Managing changing demands

Primary frequency control. Handles instantaneous (small) changes. Agent: physics.

▲ロ ▶ ▲圖 ▶ ▲ 圖 ▶ ▲ 圖 → ⑦ � @ ▶

Bienstock

Columbia University
- Primary frequency control. Handles instantaneous (small) changes. Agent: physics.
- 2 Secondary control. Handles changes that span more than a few seconds.

A B A A B A A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

- Primary frequency control. Handles instantaneous (small) changes. Agent: physics.
- Secondary control. Handles changes that span more than a few seconds. Agent: algorithms, pre-set controls.

< 17 >

- Primary frequency control. Handles instantaneous (small) changes. Agent: physics.
- Secondary control. Handles changes that span more than a few seconds. Agent: algorithms, pre-set controls.
- 3 "Tertiary" control: OPF (Optimal power flow). Manages longer lasting changes. Run every few minutes. Goal: economic generation that meets demands while maintaining feasibility (stability).

A (1) > A (1) > A

- Primary frequency control. Handles instantaneous (small) changes. Agent: physics.
- Secondary control. Handles changes that span more than a few seconds. Agent: algorithms, pre-set controls.
- "Tertiary" control: OPF (Optimal power flow). Manages longer lasting changes. Run every few minutes. Goal: economic generation that meets demands while maintaining feasibility (stability). Agent: algorithmic computations, humans.

Image: A math a math

- Primary frequency control. Handles instantaneous (small) changes. Agent: physics.
- Secondary control. Handles changes that span more than a few seconds. Agent: algorithms, pre-set controls.
- "Tertiary" control: OPF (Optimal power flow). Manages longer lasting changes. Run every few minutes. Goal: economic generation that meets demands while maintaining feasibility (stability). Agent: algorithmic computations, humans.
- 4 Once (?) a day: unit commitment problem. Chooses which generators will operate in the next day or half-day.

Image: A math a math

- Primary frequency control. Handles instantaneous (small) changes. Agent: physics.
- Secondary control. Handles changes that span more than a few seconds. Agent: algorithms, pre-set controls.
- "Tertiary" control: OPF (Optimal power flow). Manages longer lasting changes. Run every few minutes. Goal: economic generation that meets demands while maintaining feasibility (stability). Agent: algorithmic computations, humans.
- Once (?) a day: unit commitment problem. Chooses which generators will operate in the next day or half-day. Agent: algorithms, humans.

#### THE ENERGY CHALLENGE Wind Energy Bumps Into Power Grid's Limits



Mike Groll/Associated Press

The Maple Ridge Wind farm near Lowville, N.Y. It has been forced to shut down when regional electric lines become congested.

By MATTHEW L. WALD Published: August 26, 2008

When the builders of the Maple Ridge Wind farm spent \$320 million to put nearly 200 wind turbines in upstate New York, the idea was to get paid for producing electricity. But at times, regional electric lines have been so congested that Maple Ridge has been forced to shut down even with a brisk wind blowing.

	TWITTER
in	LINKEDIN
<b>무</b> (15	COMMENTS 1)
	SIGN IN TO E- MAIL OR SAVE THIS
_	

< □ > < 同 >

### CIGRE -International Conference on Large High Voltage Electric Systems '09

- Large unexpected fluctuations in wind power can cause additional flows through the transmission system (grid)
- Large power deviations in renewables must be balanced by other sources, which may be far away
- Flow reversals may be observed control difficult
- A solution expand transmission capacity! Difficult (expensive), takes a long time
- Problems already observed when renewable penetration high

Image: A math a math

### CIGRE -International Conference on Large High Voltage Electric Systems '09

- "Fluctuations" 15-minute timespan
- Due to turbulence ("storm cut-off")
- Variation of the same order of magnitude as mean
- Most problematic when renewable penetration starts to exceed 20 30%

< □ > < 同 >

Columbia University

Many countries are getting into this regime

### Optimal power flow (economic dispatch, tertiary control)



- Used periodically to handle the next time window (e.g. 15 minutes, one hour)
- Choose generator outputs
- Minimize cost (quadratic)
- Satisfy demands, meet generator and network constraints
- Constant load (demand) estimates for the time window

Columbia University

Bienstock

#### OPF:

s.t.

min c(p) (a quadratic)  $B\theta = p - d$  (6)

$$|y_{ij}(\theta_i - \theta_j)| \leq u_{ij}$$
 for each line  $ij$  (7)

$$P_g^{min} \leq p_g \leq P_g^{max}$$
 for each bus  $g$  (8)

#### Notation:

 $p = \text{vector of generations} \in \mathcal{R}^n, \quad d = \text{vector of loads} \in \mathcal{R}^n$  $B \in \mathcal{R}^{n \times n}, \quad (\text{bus susceptance matrix})$  $\forall i, j: \quad B_{ij} = \begin{cases} -y_{ij}, & ij \in \mathcal{E} \text{ (set of lines)} \\ \sum_{k; \{k, j\} \in \mathcal{E}} y_{kj}, & i = j \\ 0, & \text{otherwise} \end{cases}$ 

min c(p) (a quadratic)

s.t.

$$\begin{array}{ll} \mathcal{B}\theta = p - d \\ |y_{ij}(\theta_i - \theta_j)| &\leq u_{ij} \quad \text{for each line } ij \\ \mathcal{P}_g^{min} &\leq p_g &\leq \mathcal{P}_g^{max} \quad \text{for each bus } g \end{array}$$

ে≣ ►িছি পি ৭০ Columbia University

イロン イヨン イヨン イヨン

Operations Research Problems in Power Engineering

```
min c(p) (a quadratic)
```

s.t.

 $\begin{array}{lll} \mathcal{B}\theta = p - d \\ |y_{ij}(\theta_i - \theta_j)| &\leq u_{ij} \quad \text{for each line } ij \\ \mathcal{P}_g^{min} &\leq p_g &\leq \mathcal{P}_g^{max} \quad \text{for each bus } g \end{array}$ 

How does the grid handle short-term fluctuations in demand (d)? Secondary frequency control:

- Deployed a few seconds after ongoing change "minute-by-minute" control
- Generator output varies up or down **proportionally** to **aggregate** change

```
min c(p) (a quadratic)
```

s.t.

 $\begin{array}{lll} \mathcal{B}\theta = p - d \\ |y_{ij}(\theta_i - \theta_j)| &\leq u_{ij} \quad \text{for each line } ij \\ \mathcal{P}_g^{min} &\leq p_g &\leq \mathcal{P}_g^{max} \quad \text{for each bus } g \end{array}$ 

How does the grid handle short-term fluctuations in demand (d)? Secondary frequency control:

- Deployed a few seconds after ongoing change "minute-by-minute" control
- Generator output varies up or down proportionally to aggregate change

How does the grid handle short-term fluctuations in renewable output? **Answer:** Same mechanism, now used to handle aggregate wind power change

イロト イヨト イヨト イ

# "Participation factors"

For each generator *i*, a parameter  $\alpha_i$  with

$$\mathbf{I} \sum_{i} \alpha_{i} = \mathbf{1}$$

• 
$$\alpha_i \geq 0$$

•  $\alpha_i > 0$  only for selected generators

Assuming real-time generation/demand mismatch  $\Delta$ , real-time output of generator *i*:

$$p_i = \overline{p}_i - \alpha_i \Delta$$

where  $\overline{p}_i = OPF$  computed output for generator *i*.

**Note:** the  $\alpha_i$  are precomputed e.g. uniform or based on economic considerations.

# Experiment

Bonneville Power Administration data, Northwest US

- data on wind fluctuations at planned farms
- with standard OPF, 7 lines exceed limit  $\geq$  8% of the time



Need to model variation in wind power between dispatches Wind at farm attached to bus *i* of the form  $\mu_i + w_i$ . Weibull distribution?





Image: Image:

Operations Research Problems in Power Engineering



 Typical wind farm spans a significant geographical zone with many turbines

- Typical wind farm spans a significant geographical zone with many turbines
- Real-time variations due to turbulence

Columbia University

A B + 
 A B +
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

- Typical wind farm spans a significant geographical zone with many turbines
- Real-time variations due to turbulence
- Turbulence is local ( $\approx 50m$  radius) and arguably local effects are indepenent

< □ > < 同 >

- Typical wind farm spans a significant geographical zone with many turbines
- Real-time variations due to turbulence
- Turbulence is local ( $\approx 50m$  radius) and arguably local effects are indepenent

Image: A math a math

Columbia University

 Working model: real-time variations in a farm's output modeled as a normal variable If power flow in a line exceeds its limit, the line becomes compromised and may 'trip'. But process is complex and time-averaged:

- Thermal limit is most common
- Thermal limit may be in terms of terminal equipment, not line itself
- Wind strength and wind direction contributes to line temperature
- IEEE Standard 738 attempts to account for everything
- In 2003 U.S. blackout event, many critical lines tripped due to thermal reasons, but well short of their line limit

Image: A math a math



 When a power line overheats it becomes exposed to several risk factors



Columbia University

- When a power line overheats it becomes exposed to several risk factors
- If the line overheats enough, it may sag and experience a contact/arc, which will cause a trip
- If overheating is detected, and is deemed risky, the line will may be preemptively tripped

# Background

- When a power line overheats it becomes exposed to several risk factors
- If the line overheats enough, it may sag and experience a contact/arc, which will cause a trip
- If overheating is detected, and is deemed risky, the line will may be preemptively tripped
- What is risky?

Columbia University

- When a power line overheats it becomes exposed to several risk factors
- If the line overheats enough, it may sag and experience a contact/arc, which will cause a trip
- If overheating is detected, and is deemed risky, the line will may be preemptively tripped
- What is risky? What is a critical temperature?

- When a power line overheats it becomes exposed to several risk factors
- If the line overheats enough, it may sag and experience a contact/arc, which will cause a trip
- If overheating is detected, and is deemed risky, the line will may be preemptively tripped
- What is risky? What is a critical temperature?
- 2003 event: critical temperatures estimates were sometimes incorrect.

 A comprehensive method for determining the temperature of a power line,

Columbia University

-

 A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor

Columbia University

< □ > < 同 >

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for:

< 17 >

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for: wind, and ambient temperature,

< A

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for: wind, and ambient temperature, day of the year, latitude and longitude, angle between wind and conductor,

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for: wind, and ambient temperature, day of the year, latitude and longitude, angle between wind and conductor, altitude of sun (and time of day),

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for: wind, and ambient temperature, day of the year, latitude and longitude, angle between wind and conductor, altitude of sun (and time of day), density and viscosity of air,

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for: wind, and ambient temperature, day of the year, latitude and longitude, angle between wind and conductor, altitude of sun (and time of day), density and viscosity of air, several other factors.

Operations Research Problems in Power Engineering

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for: wind, and ambient temperature, day of the year, latitude and longitude, angle between wind and conductor, altitude of sun (and time of day), density and viscosity of air, several other factors.
- It also relies on the heat equation for a "static" calculation.
#### **IEEE Standard 738**

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for: wind, and ambient temperature, day of the year, latitude and longitude, angle between wind and conductor, altitude of sun (and time of day), density and viscosity of air, several other factors.
- It also relies on the heat equation for a "static" calculation.
- Note: power lines can be more than 100 miles long.

#### **IEEE Standard 738**

- A comprehensive method for determining the temperature of a power line, as a function of current and pause physical properties of the conductor.
- It attempts to account for: wind, and ambient temperature, day of the year, latitude and longitude, angle between wind and conductor, altitude of sun (and time of day), density and viscosity of air, several other factors.
- It also relies on the heat equation for a "static" calculation.

A (1) > A (1) > A

Columbia University

- Note: power lines can be more than 100 miles long.
- How can we account for data uncertainty, errors, unavailability?

summary: exceeding limit for too long is bad, but complicated want: "fraction time a line exceeds its limit is small" proxy: prob(violation on line i)  $< \epsilon$  for each line i



- simple control
- aware of limits
- not too conservative
- computationally practicable with a simple algorithm

Image: A matrix and a matrix

## Control

For each generator i, two parameters:

- $\overline{p_i}$  = risk-aware mean output
- $\alpha_i = \text{risk-aware participation factor}$

Real-time output of generator *i*:

$$p_i = \overline{p}_i - \alpha_i \sum_j \Delta \omega_j$$

where  $\Delta \omega_i$  = change in output of renewable *j* (from mean).

$$\sum_i \alpha_i = 1$$

< □ > < 同 >

Columbia University

Bienstock



Bienstock



Columbia University

A B + 
 A
 B + 
 A
 B
 A
 A
 B
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

wind power at bus *i*:  $\mu_i + \boldsymbol{w}_i$ 

DC approximation

$$B\theta = \overline{p} - d$$
  
+(\mu + \mu - \alpha \sum\_{i \in G} \mu\_i)  
$$\theta = B^+(\overline{p} - d + \mu) + B^+(I - \alpha e^T)$$

flow is a linear combination of bus power injections:

$$f_{ij} = y_{ij}(\theta_i - \theta_j)$$

)w

O > < 
 O >

Columbia University

Operations Research Problems in Power Engineering

## Computing line flows

$$f_{ij} = y_{ij} \left( (B_i^+ - B_j^+)^T (\bar{p} - d + \mu) + (A_i - A_j)^T \boldsymbol{w} \right),$$
$$A = B^+ (I - \alpha e^T)$$

Given distribution of wind can calculate moments of line flows:

A B > 4
 B > 4
 B

Columbia University

• 
$$E f_{ij} = y_{ij} (B_i^+ - B_j^+)^T (\bar{p} - d + \mu)$$

• 
$$var(f_{ij}) := s_{ij}^2 \ge y_{ij}^2 \sum_k (A_{ik} - A_{jk})^2 \sigma_k^2$$
  
(assuming independence)

Bienstock

## Chance constraints to deterministic constraints

• chance constraint:  $P(\mathbf{f}_{ij} > f_{ij}^{max}) < \epsilon_{ij}$  and  $P(\mathbf{f}_{ij} < -f_{ij}^{max}) < \epsilon_{ij}$ 

 from moments of *f<sub>ij</sub>*, can get conservative approximations using e.g. Chebyshev's inequality

Image: A math a math

## Chance constraints to deterministic constraints

• chance constraint:  $P(\mathbf{f}_{ij} > f_{ij}^{max}) < \epsilon_{ij}$  and  $P(\mathbf{f}_{ij} < -f_{ij}^{max}) < \epsilon_{ij}$ 

- from moments of *f<sub>ij</sub>*, can get conservative approximations using e.g. Chebyshev's inequality
- for Gaussian wind, can do better, since  $f_{ij}$  is Gaussian :

$$|E f_{ij}| + var(f_{ij})\phi^{-1}(1-\epsilon_{ij}) \leq f_{ij}^{max}$$

Operations Research Problems in Power Engineering

#### Formulation:

Choose mean generator outputs and control to minimize expected cost, with the probability of line overloads kept small.

$$\begin{split} \min_{\overline{p},\alpha} \mathbb{E}[c(\overline{p})] \\ \text{s.t.} \sum_{i \in G} \alpha_i &= 1, \ \alpha \ge 0 \\ B\delta &= \alpha, \delta_n = 0 \\ \sum_{i \in G} \overline{p}_i + \sum_{i \in W} \mu_i &= \sum_{i \in D} d_i \\ \overline{f}_{ij} &= y_{ij}(\overline{\theta}_i - \overline{\theta}_j), \\ B\overline{\theta} &= \overline{p} + \mu - d, \ \overline{\theta}_n &= 0 \\ s_{ij}^2 &\ge y_{ij}^2 \sum_{k \in W} \sigma_k^2 (B_{ik}^+ - B_{jk}^+ - \delta_i + \delta_j)^2 \\ |\overline{f}_{ij}| &+ s_{ij} \phi^{-1} (1 - \epsilon_{ij}) \le f_{ij}^{max} \end{split}$$

Operations Research Problems in Power Engineering

Polish 2003-2004 winter peak case

- 2746 buses, 3514 branches, 8 wind sources
- 5% penetration and  $\sigma = .3\mu$  each source

CPLEX: the optimization problem has

- 36625 variables
- 38507 constraints, 6242 conic constraints

Columbia University

128538 nonzeros, 87 dense columns

Polish 2003-2004 winter peak case

- 2746 buses, 3514 branches, 8 wind sources
- 5% penetration and  $\sigma = .3\mu$  each source

CPLEX: the optimization problem has

- 36625 variables
- 38507 constraints, 6242 conic constraints

Columbia University

128538 nonzeros, 87 dense columns

## Big cases

#### CPLEX:

- total time on 16 threads = 3393 seconds
- "optimization status 6"
- solution is wildly infeasible

#### Gurobi:

- time: 31.1 seconds
- "Numerical trouble encountered"

Image: Image:

## Big cases

#### CPLEX:

- total time on 16 threads = 3393 seconds
- "optimization status 6"
- solution is wildly infeasible

#### Gurobi:

- time: 31.1 seconds
- "Numerical trouble encountered"
- $\rightarrow$  basic cutting-plane algorithm works well

Image: Image:

Columbia University

## Experiment: Polish grid, 20% wind penetration, 50 farms



Bienstock, Chertkov, Harnett, SIAM Review '15

Operations Research Problems in Power Engineering

Account for errors in estimations of distribution

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - のへで

Bienstock

Columbia University

- Account for errors in estimations of distribution
- Account for correlations (spatial and timewise)

Bienstock

Columbia University

< □ > < 同 >

- Account for errors in estimations of distribution
- Account for correlations (spatial and timewise)

< □ > < 同 >

Columbia University

Extension to unit commitment problem

Bienstock

- Account for errors in estimations of distribution
- Account for correlations (spatial and timewise)
- Extension to unit commitment problem
- Better risk model for line temperature Bienstock, Blanchet and Li '15

Operations Research Problems in Power Engineering

- Line modeled as one-dimensional object parameterized by x, 0 ≤ x ≤ L.
- Time domain:  $[0, \tau]$



・ロト ・回 ト ・ ヨト ・

Operations Research Problems in Power Engineering

- Line modeled as one-dimensional object parameterized by x, 0 ≤ x ≤ L.
- Time domain:  $[0, \tau]$  (for example: OPF intervals)

・ロト ・回ト ・ヨト ・

- Line modeled as one-dimensional object parameterized by x, 0 ≤ x ≤ L.
- Time domain: [0, *τ*] (for example: OPF intervals)
- I(t) = current at time t, T(x, t) = temperature at x at time t.

Columbia University

メロト メロト メヨト メ

Operations Research Problems in Power Engineering

- Line modeled as one-dimensional object parameterized by x, 0 ≤ x ≤ L.
- Time domain: [0, *τ*] (for example: OPF intervals)
- I(t) = current at time t, T(x, t) = temperature at x at time t.
- Heat equation:

$$\frac{\partial T(x,t)}{\partial t} = \kappa \frac{\partial^2 T(x,t)}{\partial x^2} + \alpha I^2(t) - \nu (T(x,t) - T^{ext}(x,t)),$$

where  $\kappa \ge 0$ ,  $\alpha \ge 0$  and  $\nu \ge 0$  are (line dependent) constants, and  $T^{ext}(x, t)$  is the ambient temperature at (x, t)

Image: A math the second se

Columbia University

Bienstock

Heat equation:

$$\frac{\partial T(x,t)}{\partial t} = \kappa \frac{\partial^2 T(x,t)}{\partial x^2} + \alpha I^2(t) - \nu (T(x,t) - T^{ext}(x,t)).$$

Columbia University

Operations Research Problems in Power Engineering

Heat equation:

$$\frac{\partial T(x,t)}{\partial t} = \kappa \frac{\partial^2 T(x,t)}{\partial x^2} + \alpha I^2(t) - \nu (T(x,t) - T^{ext}(x,t)).$$

IEEE 738, other authors:

$$\frac{\partial T(x,t)}{\partial t} = \alpha I^2(t) - \nu (T(x,t) - T^{ext}(x,t)).$$

Us:

$$\frac{\partial T(x,t)}{\partial t} = \alpha l^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

Columbia University

・ロン ・日子・ ・ ヨン

Bienstock

Heat equation:

$$\frac{\partial T(x,t)}{\partial t} = \kappa \frac{\partial^2 T(x,t)}{\partial x^2} + \alpha I^2(t) - \nu (T(x,t) - T^{ext}(x,t)).$$

IEEE 738, other authors:

$$\frac{\partial T(x,t)}{\partial t} = \alpha I^2(t) - \nu (T(x,t) - T^{ext}(x,t)).$$

Us:

$$\frac{\partial T(x,t)}{\partial t} = \alpha l^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

・ロト ・回ト ・目ト

Columbia University

h(x) = a random variable, at x.

Bienstock

$$\frac{\partial T(x,t)}{\partial t} = \alpha I^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

Recall:  $x \in [0, L], t \in [0, \tau]$ 



Bienstock

Columbia University

$$\frac{\partial T(x,t)}{\partial t} = \alpha I^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

Recall:  $x \in [0, L]$ ,  $t \in [0, \tau]$ 

Integrate and divide by L, get

$$\frac{1}{L}\int_0^L\frac{\partial T(x,t)}{\partial t}dx = \alpha l^2(t) - \frac{\nu}{L}\int_0^L T(x,t)dx + \frac{\nu}{L}\int_0^L G(\boldsymbol{h}(\boldsymbol{x}))dx.$$

Columbia University

(日)

Bienstock

$$\frac{\partial T(x,t)}{\partial t} = \alpha I^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

Recall:  $x \in [0, L]$ ,  $t \in [0, \tau]$ 

Integrate and divide by L, get

$$\frac{1}{L}\int_0^L \frac{\partial T(x,t)}{\partial t} dx = \alpha l^2(t) - \frac{\nu}{L}\int_0^L T(x,t) dx + \frac{\nu}{L}\int_0^L G(h(x)) dx.$$
$$\frac{1}{L}\int_0^L \frac{\partial T(x,t)}{\partial t} dx =$$

Columbia University

(日)

Bienstock

$$\frac{\partial T(x,t)}{\partial t} = \alpha I^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

Recall:  $x \in [0, L]$ ,  $t \in [0, \tau]$ 

Integrate and divide by L, get

$$\frac{1}{L} \int_0^L \frac{\partial T(x,t)}{\partial t} dx = \alpha I^2(t) - \frac{\nu}{L} \int_0^L T(x,t) dx + \frac{\nu}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) dx.$$
$$\frac{1}{L} \int_0^L \frac{\partial T(x,t)}{\partial t} dx = \frac{d}{dt} \frac{1}{L} \int_0^L T(x,t) dx = \frac{d\boldsymbol{H}(t)}{dt}.$$
$$\boldsymbol{H}(t) \triangleq \frac{1}{L} \int_0^L T(x,t) dx \quad (\text{average internal line temperature at t})$$

Bienstock

Columbia University

A B + 
 A
 B + 
 A
 B
 A
 A
 B
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

$$\frac{\partial T(x,t)}{\partial t} = \alpha l^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

Recall:  $x \in [0, L]$ ,  $t \in [0, \tau]$ 

Integrate and divide by L, get

$$\frac{d\boldsymbol{H}(\boldsymbol{t})}{dt} = \alpha l^2(t) - \nu \boldsymbol{H}(\boldsymbol{t}) + \frac{\nu}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x}.$$

 $m{R} riangleq rac{1}{L} \int_0^L G(m{h}(m{x})) dx$  (average ambient temperature,

Columbia University

・ロン ・回 と ・ ヨン ・

Bienstock

$$\frac{\partial T(x,t)}{\partial t} = \alpha l^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

Recall:  $x \in [0, L]$ ,  $t \in [0, \tau]$ 

Integrate and divide by L, get

$$\frac{d\boldsymbol{H}(\boldsymbol{t})}{dt} = \alpha l^2(t) - \nu \boldsymbol{H}(\boldsymbol{t}) + \frac{\nu}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x}.$$

 $\boldsymbol{R} \triangleq \frac{1}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x}$  (average ambient temperature, random!)

Columbia University

・ロト ・回ト ・目ト ・目

Bienstock

$$\frac{\partial T(x,t)}{\partial t} = \alpha l^2(t) - \nu (T(x,t) - G(\boldsymbol{h}(\boldsymbol{x}))).$$

Recall:  $x \in [0, L]$ ,  $t \in [0, \tau]$ 

Integrate and divide by L, get

$$\frac{d\boldsymbol{H}(\boldsymbol{t})}{dt} = \alpha l^2(t) - \nu \boldsymbol{H}(\boldsymbol{t}) + \frac{\nu}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x}.$$

 $\boldsymbol{R} \triangleq \frac{1}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x}$  (average ambient temperature, **random**!)

$$\frac{d\boldsymbol{H}(\boldsymbol{t})}{dt} = \alpha l^2(t) - \nu \boldsymbol{H}(\boldsymbol{t}) + \nu \boldsymbol{R}.$$

・ロト ・回ト ・目ト ・目

Columbia University

Bienstock

#### Once more

$$\frac{d\boldsymbol{H}(\boldsymbol{t})}{d\boldsymbol{t}} = \alpha I^2(\boldsymbol{t}) - \nu \boldsymbol{H}(\boldsymbol{t}) + \nu \boldsymbol{R}.$$
$$\boldsymbol{H}(\boldsymbol{t}) \triangleq \frac{1}{L} \int_0^L T(\boldsymbol{x}, \boldsymbol{t}) d\boldsymbol{x}, \quad \boldsymbol{R} \triangleq \frac{1}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x},$$

ে≣ ►িছি পি ৭০ Columbia University

・ロン ・回と ・ヨン ・ヨン

Operations Research Problems in Power Engineering

#### **Once more**

$$\frac{d\boldsymbol{H}(\boldsymbol{t})}{dt} = \alpha l^2(\boldsymbol{t}) - \nu \boldsymbol{H}(\boldsymbol{t}) + \nu \boldsymbol{R}.$$
$$\boldsymbol{H}(\boldsymbol{t}) \triangleq \frac{1}{L} \int_0^L T(\boldsymbol{x}, t) d\boldsymbol{x}, \quad \boldsymbol{R} \triangleq \frac{1}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x},$$

#### Solution:

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha I^2(s) ds + R(1-e^{-\nu t}) + Ce^{-\nu t},$$

where

$$C=\boldsymbol{H}(\boldsymbol{0})=\frac{1}{L}\int_{0}^{L}T(x,0)dx.$$

æ Columbia University

ъ

・ロト ・回 ト ・ ヨト ・

Bienstock
## Once more

$$\frac{d\boldsymbol{H}(\boldsymbol{t})}{dt} = \alpha I^2(\boldsymbol{t}) - \nu \boldsymbol{H}(\boldsymbol{t}) + \nu \boldsymbol{R}.$$
$$\boldsymbol{H}(\boldsymbol{t}) \triangleq \frac{1}{L} \int_0^L T(\boldsymbol{x}, \boldsymbol{t}) d\boldsymbol{x}, \quad \boldsymbol{R} \triangleq \frac{1}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x},$$

## Solution:

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha I^2(s) ds + R(1-e^{-\nu t}) + Ce^{-\nu t},$$

where

Bienstock

$$C = \boldsymbol{H}(\boldsymbol{0}) = \frac{1}{L} \int_0^L T(x,0) dx.$$

**Control goal:** make I(t) "large",

Columbia University

・ロン ・日子・ ・ ヨン

#### Once more

$$\frac{d\boldsymbol{H}(\boldsymbol{t})}{dt} = \alpha l^2(\boldsymbol{t}) - \nu \boldsymbol{H}(\boldsymbol{t}) + \nu \boldsymbol{R}.$$
$$\boldsymbol{H}(\boldsymbol{t}) \triangleq \frac{1}{L} \int_0^L T(\boldsymbol{x}, t) d\boldsymbol{x}, \quad \boldsymbol{R} \triangleq \frac{1}{L} \int_0^L G(\boldsymbol{h}(\boldsymbol{x})) d\boldsymbol{x},$$

## Solution:

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha I^2(s) ds + R(1-e^{-\nu t}) + Ce^{-\nu t},$$

where

$$C = \boldsymbol{H}(\boldsymbol{0}) = \frac{1}{L} \int_0^L T(x,0) dx.$$

**Control goal:** make I(t) "large", but with  $P\left(\max_{t \in [0,\tau]} \boldsymbol{H}(t) > k\right) \leq \epsilon$ 

Columbia University

<ロ> < 回> < 回> < 回>

Bienstock

Columbia University

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha \bar{I}^2(s) ds + R(1-e^{-\nu t}) + C e^{-\nu t},$$

where

Bienstock

$$C = \boldsymbol{H}(\boldsymbol{0}) = \frac{1}{L} \int_0^L T(x, 0) dx.$$

Constant current  $\Rightarrow \boldsymbol{H}(\boldsymbol{t}) = (\frac{\alpha}{\nu} \vec{I}^2 + \boldsymbol{R})(1 - e^{-\nu t}) + C e^{-\nu t}$ 

Columbia University

・ロ・・ (日・・) (日・・)

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha \vec{I}^2(s) ds + R(1-e^{-\nu t}) + Ce^{-\nu t},$$

where

Bienstock

$$C = \boldsymbol{H}(\boldsymbol{0}) = \frac{1}{L} \int_0^L T(x, 0) dx.$$

Constant current  $\Rightarrow \boldsymbol{H}(\boldsymbol{t}) = (\frac{\alpha}{\nu}\vec{I}^2 + \boldsymbol{R})(1 - e^{-\nu t}) + Ce^{-\nu t}$ 

So, H'(t) > 0 for  $\overline{I}$  large enough,

Columbia University

・ロト ・回ト ・ヨト ・

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha \bar{I}^2(s) ds + R(1-e^{-\nu t}) + Ce^{-\nu t},$$

where

$$C = \boldsymbol{H}(\boldsymbol{0}) = \frac{1}{L} \int_0^L T(x, 0) dx.$$

・ロト ・回ト ・ヨト ・

Columbia University

Constant current  $\Rightarrow \boldsymbol{H}(\boldsymbol{t}) = (\frac{\alpha}{\nu} \vec{I}^2 + \boldsymbol{R})(1 - e^{-\nu t}) + C e^{-\nu t}$ 

So, H'(t) > 0 for  $\overline{I}$  large enough, (and of constant sign for any  $\overline{I}$ ).

Bienstock

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha \bar{I}^2(s) ds + R(1-e^{-\nu t}) + Ce^{-\nu t},$$

where

$$C = \boldsymbol{H}(\boldsymbol{0}) = \frac{1}{L} \int_0^L T(x, 0) dx.$$

Constant current  $\Rightarrow \boldsymbol{H}(t) = (\frac{\alpha}{\nu}\bar{I}^2 + \boldsymbol{R})(1 - e^{-\nu t}) + Ce^{-\nu t}$ 

So, H'(t) > 0 for  $\overline{I}$  large enough, (and of constant sign for any  $\overline{I}$ ).

So,  $P(\max_{t \in [0,\tau]} \boldsymbol{H}(t) > k) \leq \epsilon$  equivalent to  $P(\boldsymbol{H}(\tau) > k) \leq \epsilon$ .

・ロト ・回ト ・ヨト ・

Operations Research Problems in Power Engineering

Bienstock

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha \bar{l}^2(s) ds + R(1-e^{-\nu t}) + C e^{-\nu t},$$

where

$$C = \boldsymbol{H}(\boldsymbol{0}) = \frac{1}{L} \int_0^L T(x, 0) dx.$$

・ロト ・回ト ・目ト ・目

Columbia University

Constant current  $\Rightarrow \boldsymbol{H}(t) = (\frac{\alpha}{\nu}\bar{I}^2 + \boldsymbol{R})(1 - e^{-\nu t}) + Ce^{-\nu t}$ 

So, H'(t) > 0 for  $\overline{I}$  large enough, (and of constant sign for any  $\overline{I}$ ).

So,  $P\left(\max_{t\in[0,\tau]} \boldsymbol{H}(t) > k\right) \leq \epsilon$  equivalent to  $P(\boldsymbol{H}(\tau) > k) \leq \epsilon$ .

#### Solution:

$$\overline{l}^2 \leq \frac{\nu}{\alpha} \frac{k - C e^{-\nu\tau} - \rho_{\epsilon} (1 - e^{-\nu\tau})}{1 - e^{-\nu\tau}}$$

Bienstock

$$H(t) = \int_0^t e^{-\nu(t-s)} \alpha \bar{l}^2(s) ds + R(1-e^{-\nu t}) + C e^{-\nu t},$$

where

$$C = \boldsymbol{H}(\boldsymbol{0}) = \frac{1}{L} \int_0^L T(x, 0) dx.$$

Constant current  $\Rightarrow \boldsymbol{H}(t) = (\frac{\alpha}{\nu} \vec{I}^2 + \boldsymbol{R})(1 - e^{-\nu t}) + Ce^{-\nu t}$ 

So, H'(t) > 0 for  $\overline{I}$  large enough, (and of constant sign for any  $\overline{I}$ ).

So,  $P\left(\max_{t\in[0,\tau]} \boldsymbol{H}(t) > k\right) \leq \epsilon$  equivalent to  $P(\boldsymbol{H}(\tau) > k) \leq \epsilon$ .

#### Solution:

$$\overline{I}^2 \leq \frac{\nu}{\alpha} \frac{k - C e^{-\nu\tau} - \rho_{\epsilon} (1 - e^{-\nu\tau})}{1 - e^{-\nu\tau}} = L(\tau, k)$$

Bienstock

Columbia University

・ロト ・回 ト ・ ヨト ・

▲□▶▲圖▶▲圖▶▲圖▶ 圖 のQC

Bienstock

Columbia University

### Simplification:

**R** is a discrete random variable.  $P(\mathbf{R} = r_i) = p_i, i = 1, 2, ..., n$  (known).

Bienstock

Columbia University

#### Simplification:

**R** is a discrete random variable.  $P(\mathbf{R} = r_i) = p_i, i = 1, 2, ..., n$  (known).

1. At time  $\tau = 0$ , we compute values  $I_1$ , and  $I_{2,i}$  for i = 1, 2, ..., n. These values are used as follows:

#### Simplification:

**R** is a discrete random variable.  $P(\mathbf{R} = r_i) = p_i, i = 1, 2, ..., n$  (known).

- 1. At time  $\tau = 0$ , we compute values  $I_1$ , and  $I_{2,i}$  for i = 1, 2, ..., n. These values are used as follows:
- 2. For all  $t \in [0, \tau/2]$ , we set  $I(t) = I_1$ .

Bienstock

Columbia University

Image: A math a math

#### Simplification:

**R** is a discrete random variable.  $P(\mathbf{R} = r_i) = p_i, i = 1, 2, ..., n$  (known).

- 1. At time  $\tau = 0$ , we compute values  $I_1$ , and  $I_{2,i}$  for i = 1, 2, ..., n. These values are used as follows:
- 2. For all  $t \in [0, \tau/2]$ , we set  $I(t) = I_1$ .
- 3. At time  $\tau/2$ , we observe the value of  $\mathbf{R}$ . Assuming  $\mathbf{R} = r_i$ , then for all  $t \in [\tau/2, \tau]$ , we set  $I(t) = I_{2,i}$ .

・ロン ・日子・ ・ ヨン

Columbia University

## Goals:

(a) 
$$P(\boldsymbol{H}(\boldsymbol{\tau}) > k) < \epsilon$$
.

Bienstock

#### Simplification:

**R** is a discrete random variable.  $P(\mathbf{R} = r_i) = p_i, i = 1, 2, ..., n$  (known).

- 1. At time  $\tau = 0$ , we compute values  $I_1$ , and  $I_{2,i}$  for i = 1, 2, ..., n. These values are used as follows:
- 2. For all  $t \in [0, \tau/2]$ , we set  $I(t) = I_1$ .
- 3. At time  $\tau/2$ , we observe the value of  $\mathbf{R}$ . Assuming  $\mathbf{R} = r_i$ , then for all  $t \in [\tau/2, \tau]$ , we set  $I(t) = I_{2,i}$ .

Image: A math a math

Columbia University

### **Goals:**

(a) P(H(τ) > k) < ε. k smaller than critical temperature</li>
(b) l<sub>1</sub> ≤ L(τ/2).

#### Simplification:

**R** is a discrete random variable.  $P(\mathbf{R} = r_i) = p_i, i = 1, 2, ..., n$  (known).

- 1. At time  $\tau = 0$ , we compute values  $I_1$ , and  $I_{2,i}$  for i = 1, 2, ..., n. These values are used as follows:
- 2. For all  $t \in [0, \tau/2]$ , we set  $I(t) = I_1$ .
- 3. At time  $\tau/2$ , we observe the value of  $\mathbf{R}$ . Assuming  $\mathbf{R} = r_i$ , then for all  $t \in [\tau/2, \tau]$ , we set  $I(t) = I_{2,i}$ .

Columbia University

## **Goals:**

- (a) P(H(τ) > k) < ε. k smaller than critical temperature</li>
  (b) I<sub>1</sub> ≤ L(τ/2).
- (c) What about performance?

We want to maximize:

• "Total" current: 
$$\frac{\tau}{2} I_1 + \frac{\tau}{2} I_{2,i}$$
 ?

Bienstock

Columbia University

Э

We want to maximize:

• "Total" current: 
$$\frac{\tau}{2} I_1 + \frac{\tau}{2} I_{2,i}$$
 ?

• "Average" current? Square current?

Columbia University

A B + 
 A
 B + 
 A
 B
 A
 A
 B
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

Operations Research Problems in Power Engineering

Bienstock

We want to maximize:

• "Total" current: 
$$\frac{\tau}{2} I_1 + \frac{\tau}{2} I_{2,i}$$
 ?

"Average" current? Square current?

 $F(l_1, l_2)$ : a monotonely increasing function of  $l_1, l_2$ 

Bienstock

Columbia University

Image: A mathematical states and a mathem

## Simplification:

**R** is a discrete random variable.  $P(\mathbf{R} = r_i) = p_i, i = 1, 2, ..., n$  (known).

- 1. At time  $\tau = 0$ , we compute values  $l_1$ , and  $l_{2,i}$  for i = 1, 2, ..., n. These values are used as follows:
- 2. For all  $t \in [0, \tau/2]$ , we set  $I(t) = I_1$ .
- 3. At time  $\tau/2$ , we observe the value of  $\mathbf{R}$ . Assuming  $\mathbf{R} = r_i$ , then for all  $t \in [\tau/2, \tau]$ , we set  $I(t) = I_{2,i}$ .

### Goals:

(a) P(H(τ) > k) < ε. k smaller than critical temperature</li>
(b) I<sub>1</sub> ≤ L(τ/2).
(c) Maximize:

$$\sum_{i=1}^n F(I_1,I_{2,i})p_i$$

Image: A math a math

Columbia University

 $\begin{array}{ll} \max & \sum_{i=1}^{n} F(I_1, I_{2,i}) p_i \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \end{array}$ 

Bienstock

Columbia University

A B + 
 A
 B + 
 A
 B
 A
 A
 B
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

 $\begin{array}{ll} \max & \sum_{i=1}^{n} F(l_{1}, l_{2,i}) p_{i} \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \\ & \boldsymbol{H}(\boldsymbol{\tau}) \leq u \end{array}$ 

ヘロア ヘロア ヘビア ヘビア ビー う

Bienstock

Columbia University

$$\begin{array}{ll} \max & \sum_{i=1}^{n} F(l_{1}, l_{2,i}) p_{i} \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \\ & \boldsymbol{H}(\boldsymbol{\tau}) \leq u \quad (k < u < \text{ critical temp}) \end{array}$$

Bienstock

æ Columbia University

ъ

・ロ・・ (日・・ (日・・)

$$\begin{array}{ll} \max & \sum_{i=1}^{n} F(l_{1}, l_{2,i}) p_{i} \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \\ & \boldsymbol{H}(\boldsymbol{\tau}) \leq u \quad (k < u < \text{ critical temp}) \\ & l_{1} \leq L(\tau/2, k) \end{array}$$

Bienstock

ে≣ ►ি ছি পি ৭০ Columbia University

イロン イヨン イヨン イヨン

$$\begin{array}{ll} \max & \sum_{i=1}^{n} F(l_{1}, l_{2,i}) p_{i} \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \\ & \boldsymbol{H}(\boldsymbol{\tau}) \leq u \quad (k < u < \text{ critical temp}) \\ & l_{1} \leq L(\tau/2, k) \\ & \text{other constraints.} \end{array}$$

Bienstock

ে≣ ►িছি পি ৭০ Columbia University

・ロン ・回と ・ヨン ・ヨン

$$\begin{array}{ll} \max & \sum_{i=1}^{n} F(l_{1}, l_{2,i}) p_{i} \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \\ & \boldsymbol{H}(\boldsymbol{\tau}) \leq u \quad (k < u < \text{ critical temp}) \\ & l_{1} \leq L(\tau/2, k) \\ & \text{other constraints.} \end{array}$$

Bienstock

$$H(\tau) = \int_0^{\tau} e^{-\nu(\tau-s)} \alpha l^2(s) ds + R(1-e^{-\nu\tau}) + Ce^{-\nu\tau},$$

ि≣ । ≣ •ी २.( Columbia University

・ロト ・回 ト ・ヨト ・ヨ

$$\begin{array}{ll} \max & \sum_{i=1}^{n} F(l_{1}, l_{2,i}) p_{i} \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \\ & \boldsymbol{H}(\boldsymbol{\tau}) \leq u \quad (k < u < \text{ critical temp}) \\ & l_{1} \leq L(\tau/2, k) \\ & \text{other constraints.} \end{array}$$

Bienstock

$$\begin{aligned} \boldsymbol{H}(\tau) &= \int_0^\tau e^{-\nu(\tau-s)} \alpha l^2(s) ds + \boldsymbol{R}(1-e^{-\nu\tau}) + C e^{-\nu\tau}, \\ &= v_1 l_1^2 + v_2 l_2^2(i) + r_i(1-e^{-\nu\tau}) + C e^{-\nu\tau} & \text{in state i} \end{aligned}$$

ि≣ । ≣ •ी २.( Columbia University

・ロト ・回 ト ・ヨト ・ヨ

$$\begin{array}{ll} \max & \sum_{i=1}^{n} F(l_{1}, l_{2,i}) p_{i} \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \\ & \boldsymbol{H}(\boldsymbol{\tau}) \leq u \quad (k < u < \text{ critical temp}) \\ & l_{1} \leq L(\tau/2, k) \\ & \text{other constraints.} \end{array}$$

$$H(\tau) = \int_0^\tau e^{-\nu(\tau-s)} \alpha l^2(s) ds + R(1-e^{-\nu\tau}) + Ce^{-\nu\tau},$$
  
=  $v_1 l_1^2 + v_2 l_2^2(i) + r_i(1-e^{-\nu\tau}) + Ce^{-\nu\tau}$  in state i

So chance constraint is of the form:

$$\sum_{i=1}^{n} \mathbb{I}\{v_1 \ l_1^2 + v_2 \ l_2^2(i) > u - r_i(1 - e^{-\nu\tau}) - Ce^{-\nu\tau}\}p_i \leq \epsilon.$$

Columbia University

Bienstock

$$\begin{array}{ll} \max & \sum_{i=1}^{n} F(l_{1}, l_{2,i}) p_{i} \\ \text{s.t.} & P(\boldsymbol{H}(\boldsymbol{\tau}) > k) \leq \epsilon \\ & \boldsymbol{H}(\boldsymbol{\tau}) \leq u \quad (k < u < \text{ critical temp}) \\ & l_{1} \leq L(\tau/2, k) \\ & \text{other constraints.} \end{array}$$

$$H(\tau) = \int_0^\tau e^{-\nu(\tau-s)} \alpha l^2(s) ds + R(1-e^{-\nu\tau}) + Ce^{-\nu\tau},$$
  
=  $v_1 l_1^2 + v_2 l_2^2(i) + r_i(1-e^{-\nu\tau}) + Ce^{-\nu\tau}$  in state i

So chance constraint s of the form:

$$\sum_{i=1}^{n} \mathbb{I}\{\underbrace{v_{1} \ l_{1}^{2}}_{z_{1}} + \underbrace{v_{2} \ l_{2}^{2}(i)}_{z_{2}(i)} > \underbrace{u \ - \ r_{i}(1 - e^{-\nu\tau}) \ - \ Ce^{-\nu\tau}}_{w_{i}}\}p_{i} \leq \epsilon.$$

#### Bienstock

Columbia University

$$\max \qquad \sum_{i=1}^{n} \tilde{F}(z_1, z_2(i)) p_i$$
  
s.t. 
$$\sum_{i=1}^{n} \mathbb{I}\{z_1 + z_2(i) > w_i\} p_i \leq \epsilon$$
$$z_1 + z_2(i) \leq u_i \quad (w_i < u_i)$$
$$z_1 \leq \bar{k}$$

other constraints.

ে≣ ►িছি পি ৭০ Columbia University

(日) (四) (日) (日) (日)

Operations Research Problems in Power Engineering

Bienstock

$$\max \qquad \sum_{i=1}^{n} \tilde{F}(z_{1}, z_{2}(i)) p_{i}$$
  
s.t. 
$$\sum_{i=1}^{n} \mathbb{I}\{z_{1} + z_{2}(i) > w_{i}\}p_{i} \leq \epsilon$$
$$z_{1} + z_{2}(i) \leq u_{i} \quad (w_{i} < u_{i})$$
$$z_{1} \leq \bar{k}$$

other constraints.

Lemma: At optimality,

$$z_1 + z_2(i) = w_i$$
 or  $u_i$ , all  $i$ 

ে≣ ► ≣ ৵৭০ Columbia University

・ロト ・回ト ・目と

Operations Research Problems in Power Engineering

Bienstock

$$\begin{array}{ll} \max & \sum_{i=1}^{n} \tilde{F}(z_{1}, z_{2}(i)) \ p_{i} \\ \text{s.t.} & \sum_{i=1}^{n} \mathbb{I}\{z_{1} + z_{2}(i) > w_{i}\} p_{i} \ \leq \ \epsilon \\ & z_{1} + z_{2}(i) \ \leq \ u_{i} \quad (w_{i} < u_{i}) \\ & z_{1} \ \leq \ \bar{k} \end{array}$$

other constraints.

Lemma: At optimality,

$$z_1 + z_2(i) = w_i$$
 or  $u_i$ , all  $i$ 

 $\rightarrow$  Use **binary** variable

$$y_i = \begin{cases} 0 & \text{when } z_1 + z_2(i) = w_i \\ 1 & \text{when } z_1 + z_2(i) = u_i \end{cases}$$

・ロン ・日子・ ・ ヨン

Columbia University

Bienstock

$$\max \sum_{i=1}^{n} \tilde{F}(z_{1}, w_{i} - z_{i})p_{i}(1 - y_{i}) + \tilde{F}(z_{1}, u_{i} - z_{i})p_{i}y_{i}$$
  
s.t. 
$$\sum_{i=1}^{n} u_{i}p_{i}y_{i} \leq \epsilon$$
$$0 \leq z_{1} \leq \bar{k}$$
$$y_{i} = 0 \text{ or } 1, \text{ all } i.$$

Columbia University

・ロト ・回ト ・目と

Operations Research Problems in Power Engineering

Bienstock

 $\max_{z_1\in[0,\bar{k}]}M(z_1)$ 



Bienstock

Columbia University

$$M(z_1) \triangleq \sum_{i=1}^{n} \tilde{F}(z_1, w_i - z_i) p_i (1 - y_i) + \tilde{F}(z_1, u_i - z_i) p_i y_i$$
  
s.t. 
$$\sum_{i=1}^{n} u_i p_i y_i \leq \epsilon$$
$$y_i = 0 \text{ or } 1, \quad \text{all } i.$$

Columbia University

・ロト ・回ト ・目と

Bienstock

$$\begin{array}{rcl} \max_{z_1 \in [0,\bar{k}]} M(z_1) \\ M(z_1) & \triangleq & \sum_{i=1}^n \tilde{F}(z_1,w_i-z_i)p_i(1-y_i) + \tilde{F}(z_1,u_i-z_i)p_iy_i \\ & \text{s.t.} & \sum_{i=1}^n u_ip_iy_i \leq \epsilon \\ & y_i = 0 \text{ or } 1, \quad \text{all } i. \end{array}$$

・ロト ・回ト ・目と

Columbia University

## Practicable!

Bienstock
## Identifying Risky Contingencies of Transmission Systems

(Joint with S. Harnett, T. Kim and S. Wright)

- **N 1** criterion widely used. But is it enough?
- How about **N K**, for **K** "larger"? Everybody knows that:
  - It is *too* slow. A very difficult combinatorial problem.

N	<i>K</i> = 2	K = 3	K = 4
1000	499500	166167000	41417124750
4000	7998000	10658668000	10650673999000
8000	31996000	85301336000	170538695998000
10000	49995000	166616670000	416416712497500

- It is too conservative. It is not conservative enough.
  - (T. Boston) during Hurricane Sandy, N 142 was observed.

Columbia University

Perhaps N - K does not necessarily capture all interesting events?

# Example: August 14 2003

U.S. - Canada report on blackout:

"Because it had been hot for several days in the Cleveland-Akron area, more air conditioners were running to overcome the persistent heat, and consuming relatively high levels of reactive power – further straining the area's limited reactive generation capabilities."

A system-wide condition that impedes the system

# Example: August 14 2003

U.S. - Canada report on blackout:

"Because it had been hot for several days in the Cleveland-Akron area, more air conditioners were running to overcome the persistent heat, and consuming relatively high levels of reactive power – further straining the area's limited reactive generation capabilities."

- A system-wide condition that impedes the system
- Not a cause, but a contributor

# Example: August 14 2003

U.S. - Canada report on blackout:

"Because it had been hot for several days in the Cleveland-Akron area, more air conditioners were running to overcome the persistent heat, and consuming relatively high levels of reactive power – further straining the area's limited reactive generation capabilities."

- A system-wide condition that impedes the system
- Not a cause, but a contributor
- Look for events that combine both effects?

## A continuous interdiction model

- A fictitious adversary is trying to interdict the transmission system.
- This adversary negatively alters the physical parameters of equipment, e.g. transmission lines, so as to impede transmission.
- The adversary has a budget available (both system-wide and per-line).
  - On line km, reactance  $x_{km}$  increased to  $(1 + \lambda_{km})x_{km}$

#### A blast from the past: Bienstock and Verma 2007

- **DC** approximation to power flows.
- Adversary increases reactances of lines.
- Limit on total percentage-increase of reactances, and on per-line increase.
- Adversary maximizes the maximum line overload:

$$\begin{array}{ll} \max_{\mathbf{x},\theta} & \max_{km} \left\{ \frac{|\theta_k - \theta_m|}{u_{km} \ \mathbf{x}_{km}} \right\} & = \max_{km} \frac{|\text{flow on line } km|}{|\text{limit of line } km|} \\ \text{s.t.} & \mathbf{B}_{\mathbf{x}}\theta = d \\ & \mathbf{x} \text{ within budget} \end{array}$$

< □ > < 同 >

Columbia University

Continuous, but non-smooth problem.

Bienstock

#### A blast from the past: Bienstock and Verma, 2007

- **DC** approximation to power flows.
- Adversary increases reactances of lines.
- Limit on total percentage-increase of reactances, and on per-line increase.

A B > A B >

Columbia University

Adversary maximizes the maximum line overload:

$$\begin{split} \max_{\substack{\textbf{x},\theta,\alpha\\\textbf{x},\theta,\alpha}} & \sum_{\substack{km}} (\alpha_{km}^+ - \alpha_{km}^-) \frac{(\theta_k - \theta_m)}{u_{km} \ \textbf{x}_{km}} \\ \text{s.t.} & \begin{array}{l} \textbf{B}_{\textbf{x}}\theta &= d \\ \textbf{x} \text{ within budget} \\ & \sum_{\substack{km}} (\alpha_{km}^+ + \alpha_{km}^-) &= 1, \quad \alpha^+, \alpha^- \geq 0. \end{split} \end{split}$$

Continuous, smooth, **nonconvex**.

Bienstock

## And what happens?

- Efficient computation of gradient and Hessian of objective
- Local optimization algorithm implemented using LOQO
- Algorithm scales well (2007): CPU times of ~ 1 hour for studying systems with thousands of lines.

Image: A math a math

- Optimal \* attack concentrated on a handful of lines
- Plus system-wide attack impacting many lines

single = 20	total = 60	single $= 10$	total = 30	single $= 10$	total = 40
Range	Count	Range	Count	Range	Count
[1, 1]	8	[1, 1]	1	[1, 1]	14
(1,2]	72	(1,2]	405	(1,2]	970
(2,3]	4	(2,9]	0	(2,5]	3
(5,6]	1	(9, 10]	3	(5,6]	0
(6,7]	1			(6, 7]	1
(7,8]	4			(7, 9]	0
(8,20]	0			(9, 10]	2

"single" = max multiplicative increase of a line's reactance "total" = max total multiplicative increase of line reactances

Image: A mathematical states and a mathem

∃ >

Columbia University

## Today: the AC power flows setting

Adversary increases impedances, so as to maximize:

- Phase angle differences across ends of a lines
- Voltage deviations (loss)
- Lost load following recourse actions

Generically:

max	$\mathcal{F}(\mathbf{x})$		
s.t.	$\mathbf{x} \in \mathcal{B}$		

- **x** = impedances,  $\mathcal{B}$  = budget constraints
- F(x)= meausure of phase angle differences, voltage loss, load loss

Columbia University

Challenge: *F*(*x*) is implicitly defined (bilevel optimization problem)

Bienstock

# Voltage attack on 2383-bus Polish "Double the reactance of at most three lines"

Voltage Magnitude



4 同

Columbia University

## → Primarily 4 lines interdicted

Bienstock

Sat.Feb.20.102859.2016@rockadoodle



Bienstock

Columbia University