# **Dealing with NP-Completeness**

**Note:** We will resume talking about optimization problems, rather than yes/no questions.

### What to do?

- Give up
- Solve small instances
- Look for special structure that makes your problem easy (e.g. planar graphs, each variable in at most 2 clauses, ...)
- Run an exponential time algorithm that might do well on some instances (e.g. branch-and-bound, integer programming, constraint programming)
- Heuristics algorithms that run for a limited amount of time and return a solution that is hopefully close to optimal, but with no guarantees
- Approximation Algorithms algorithms that run in polynomial time and give a guarantee on the quality of the solution returned

## **Heuristics**

- Simple algorithms like "add max degree vertex to the vertex cover"
- Local search
- Metaheuristics are popular
  - simulated annealing
  - $-\operatorname{tabu}\,\operatorname{search}$
  - genetic algorithms
  - $-\operatorname{GRASP}$
  - $-\operatorname{Greedy}$

### **Approximation Algorithms**

Set up: We have a minimization problem X, inputs I, algorithm A.

- $\bullet \ OPT(I) \$  is the value of the optimal solution on input  $\ I$  .
- A(I) is the value returned when running algorithm A on input I.

**Def:** Algorithm A is an  $\rho$  -approximation algorithm for Problem X if, for all inputs I

- A runs in polynomial time
- $\bullet \; A(I) \leq \rho OPT(I)$  .

Note:  $\rho \ge 1$ , small  $\rho$  is good.

## Methodology

**Lower bound:** Given an instance I, a lower bound, LB(I) is an "easily-computed" value such that  $LB(I) \leq OPT(I)$ .

### Methodology

- Compute a lower bound LB(I).
- Give an algorithm A, that computes a solution to the optimization problem on input I with a guarantee that  $A(I) \leq \rho LB(I)$  for some  $\rho \geq 1$ .
- $\bullet$  Conclude that  $\ A(I) \leq \rho OPT(I)$  .

## Matching

- A matching M of a graph G is a subset of the edges  $M \subseteq E$ , such that each vertex  $v \in V$  is incident to at most one edge in M.
- A maximum matching can be computed in polynomial time
- A maximum matching in a bipartite graph can be computed via maximum flow.

### A 2-approximation for Vertex Cover

First find a good lower bound: A matching!

Given a graph G, let

- $\bullet \ MM(I) \$  be the size of the maximum matching on  $\ I$  .
- OPT(I) be the size of the minimum-sized vertex cover on I
- VC(I) be the size of the vertex cover returned by the algorithm below

Claim:  $MM(I) \leq OPT(I)$ 

**Proof:** Look at each edge in the maximum matching M. Each vertex in a vertex cover covers at most one edge in M.

### Algorithm

- 1. Compute A maximum matching M.
- 2. For each edge  $(v, w) \in M$ , add both v and w to C.

## Analysis

C is a vertex cover: .

**Proof:** Assume not. Then some edge (v, w) has neither v nor w in C. But then neither v nor w is incident to an edge in M, which means that you could add (v, w) to M, contradicting the fact that M is a maximum matching.

Solution value:

 $VC(I) = 2MM(I) \leq 2OPT(I)$ 

Therefore we have a 2-approximation algorithm.

### **Euler Tour**

- $\bullet$  Give an even-degree graph  $\ G$  , an Euler Tour is a (non-simple) cycle that visits each edge exactly once.
- Every even-edgee graph has an Euler tour.
- You can find one in linear time.

## **Travelling Salesman Problem**

Variant: We will consider the symmetric TSP with triangle-inequality.

- $\bullet \ w(a,b) = w(b,a)$
- $\bullet \ w(a,b) \leq w(a,c) + w(c,b)$

### Notes:

- Without triangle inequality, you cannot approximate TSP (unless P=NP)
- Assymetric version is harder to approximate.

# Approximating TSP

- A minimum spanning tree is a lower bound on the TSP.  $MST(I) \leq OPT(I)$
- A minimum spanning tree doubled is an even degree graph GG, and therefore has an Euler tour of total length GG(I), with GG(I) = 2MST(I)
- Because of triangle inequality, we can "shortcut" the Euler tour GG to find a tour with  $TSP(I) \leq GG(I)$

Combining, we have

 $TSP(I) \le GG(I) = 2MST(I) \le 2OPT(I)$ 

- 2-approximation for TSP
- 3/2-approximation is possible.
- If points are in the plane, there exists a polynomial time approximation scheme, an algorithm that, for any fixed  $\epsilon > 0$  returns a tour of length at most  $(1 + \epsilon)OPT(I)$  in polynomial time. (The dependence on  $\epsilon$  can be large).

### $\underline{MAX-3-SAT}$

**Definition** Given a boolean CNF formula with 3 literals per clause. We want to satisfy the maximum possible number of clauses.

**Note:** We have to invert definiton of approximation, want to find  $A(I) \ge \rho OPT(I)$ 

#### Algorithm

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• Randomly set each variable to true with probability 1/2.

## Analysis

- Let Y be the number of clauses satisfied.
- Let m be the number of clauses. ( $m \ge OPT(I)$ ).
- Let  $Y_i$  be the i.r.v representing the *i* th clause being satisfied.
- $Y = \sum_{i=1}^m Y_i$  .
- $E[Y] = \sum_{i=1}^{m} E[Y_i]$ .
- What is  $E[Y_i]$ , the probability that the *i* th clause is true?
  - The only way for a clause to be false is for all three literals to be false
  - The probability a clause is false is therefore  $(1/2)^3 = 1/8$
  - Probability a clause is true is therefore 1 1/8 = 7/8.
- Finishing,  $E[Y_i] = 7/8$ .
- E[Y] = (7/8)m
- $\bullet \ E[Y] = (7/8)m \geq (7/8)OPT(I)$

### ${\bf Conclusion} \quad 7/8 \ {\bf -approximation} \ {\bf algorithm}.$

### Set Cover

An instance  $(X, \mathcal{F})$  of the set-covering problem consists of a finite set X and a family  $\mathcal{F}$  of subsets of X, such that every element of X belongs to at least one subset in  $\mathcal{F}$ :

$$X = \bigcup_{S \in \mathcal{F}} S \; .$$

We say that a subset  $S \in \mathcal{F}$  covers its elements. The problem is to find a minimum-size subset  $\mathcal{C} \subseteq \mathcal{F}$  whose members cover all of X:

 $X = \bigcup_{S \in \mathcal{C}} S$ 

## **Greedy Algorithm**

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\begin{array}{ll} & \frac{\operatorname{Greedy-Set-Cover}(X,\mathcal{F})}{U \leftarrow X} \\ \mathbf{2} & \mathcal{C} \leftarrow \emptyset \\ \mathbf{3} & \text{while } U \neq \emptyset \\ \mathbf{4} & \text{do select an } S \in \mathcal{F} \text{ that maximizes } |S \cap U| \\ \mathbf{5} & U \leftarrow U - S \\ \mathbf{6} & \mathcal{C} \leftarrow \mathcal{C} \cup \{S\} \\ \mathbf{7} & \text{return } \mathcal{C} \end{array}
```

Claim: If the optimal set cover has k elements, then C has at most  $k \log n$  elements.

### Proof

Claim: If the optimal set cover has k sets, then C has at most  $k \log n$  sets.

#### **Proof:**

- Optimal set cover has k sets.
- One of the sets must therefore cover at least n/k of the elements.
- First greedy step must therefore choose a set that covers at least n/k of the elements.
- After first greedy step, the number of uncovered elements is at most n n/k = n(1 1/k) .

### **Proof continued**

Iterate argument

- On remaining uncovered elements, one set in optimal must cover at least a 1/k fraction of the remaining elements.
- So after two steps, the number of uncovered elements is at most

$$n\left(1-\frac{1}{k}\right)^2$$

So after j iterations, the number of uncovered elements is at most

$$n\left(1-\frac{1}{k}\right)^j \le n e^{-j/k}$$

When  $j = k \ln n$ , the numer of uncovered elements is at most

$$ne^{-j/k} = ne^{-k\ln n/k} = ne^{-\ln n} = n/n = 1$$

Therefore, the algorithm stops after choosing at most  $k \ln n$  sets (without knowing k.