

New results on nonconvex optimization

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Three problems

1. The “SUV” problem

- given full-dimensional polyhedra P^1, \dots, P^K in \mathbb{R}^d ,
- find a point closest to the origin *not* contained inside any of the P^h .

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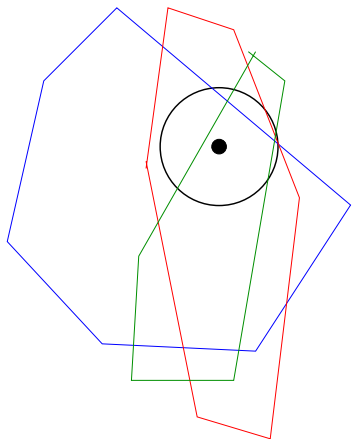
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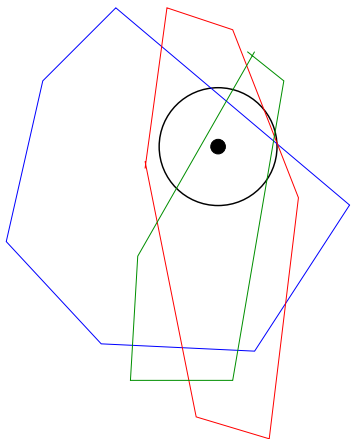
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(application: X-ray lithography)





- Typical values for d (dimension): less than 20; usually even smaller
- Typical values for K (number of polyhedra): possibly hundreds, but often less than 50

2.

Cardinality constrained, convex quadratic programming.

$$\begin{aligned} \min \quad & x^T Q x + c^T x \\ \text{s.t.} \quad & A x \leq b \\ & x \geq 0, \quad \|x\|_0 \leq k \end{aligned}$$

$\|x\|_0$ = number of nonzero entries in x .

- $Q \succeq 0$
- $x \in \mathbb{R}^n$ for n possibly large
- k relatively small, e.g. $k = 100$ for $n = 10000$
- VERY hard problem – just getting good bounds is tough

2b.

Sparse vector in column space (Spielwan, Wang, Wright '12)

Given a vector $y \in \mathbb{R}^n$ (n large)

$$\begin{aligned} \min \quad & \|y - Ax\|_2 \\ \text{s.t.} \quad & A \in \mathbb{R}^{n \times n}, x \in \mathbb{R}^n \\ & \|x\|_0 \leq k \end{aligned}$$

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- Both A and x are variables
- Usual “convexification” approach may not work
- Again, looks VERY hard

3. AC-OPF problem in rectangular coordinates

Given a power grid, determine voltages at every node so as to minimize a convex objective

$$\begin{aligned} \min \quad & v^T A v \\ \text{s.t.} \quad & L_k \leq v^T F_k v \leq U_k, \quad k = 1, \dots, K \\ & v \in \mathbb{R}^{2n}, \quad (n = \text{number of nodes}) \end{aligned}$$

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- voltages are complex numbers; v is the vector of voltages in rectangular coordinates (real and imaginary parts)
- $A \succeq 0$
- n could be in the tens of thousands, or more
- the F_k are very sparse (neighborhood structure for every node)
- Problem HARD when grid under distress and $L_k \approx U_k$.

Why are these problems so hard

Generic problem: $\min Q(x), \quad s.t. \quad x \in F,$

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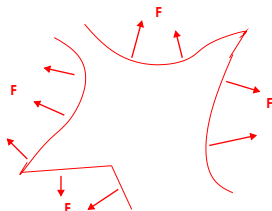
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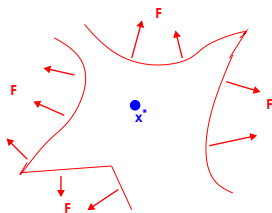
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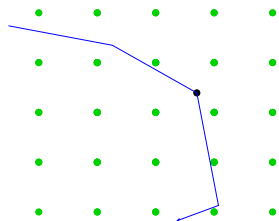
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x^* solves $\min \left\{ Q(x), : x \in \hat{F} \right\}$ where $F \subset \hat{F}$ and \hat{F} convex

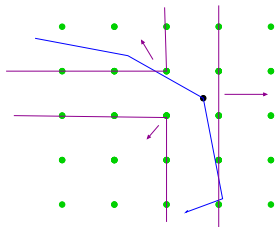
Lattice-free cuts for **linear** integer programming

Generic problem: $\min c^T x, \quad s.t. \quad Ax \leq b, \quad z \in \mathbb{Z}^n$



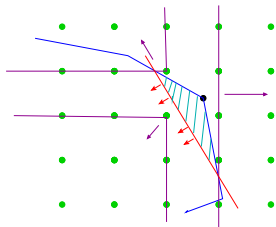
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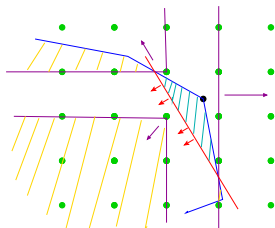
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- Optimal solution at **extreme point** (x^*, z^*) of $\text{conv} \{(x, z) : z \geq Q(x), x \in F\}$
- So $x^* \in F$

Exclude-and-cut

$$\min z, \quad \text{s.t.} \quad z \geq Q(x), \quad x \in F$$

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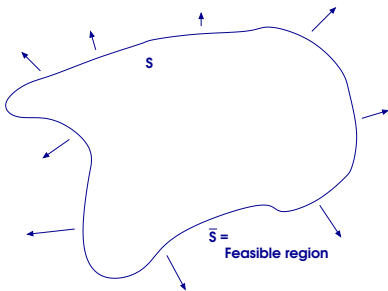
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3. Add to the formulation an inequality $\mathbf{a}z + \boldsymbol{\alpha}^T \mathbf{x} \geq \alpha_0$ valid for

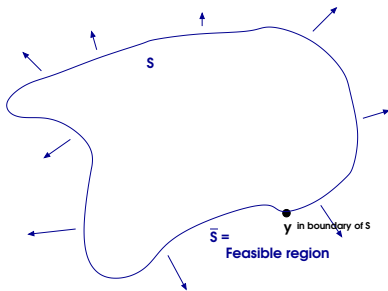
$$\{(x, z) : x \in \bar{S}, z \geq Q(x)\}$$

but violated by (x^*, z^*) .

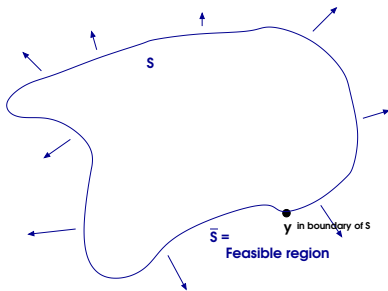
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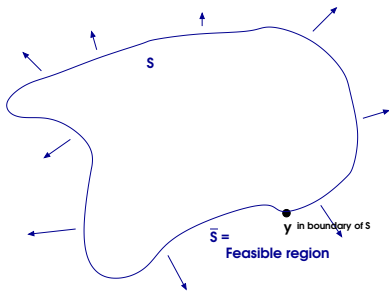


First order inequality:

$$z \geq [\nabla Q(y)]^T (x - y) + Q(y)$$

is valid EVERYWHERE

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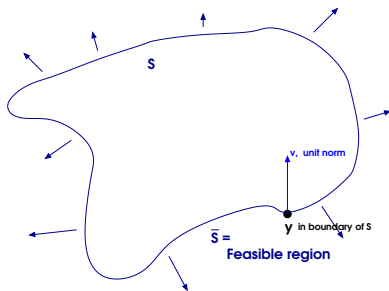


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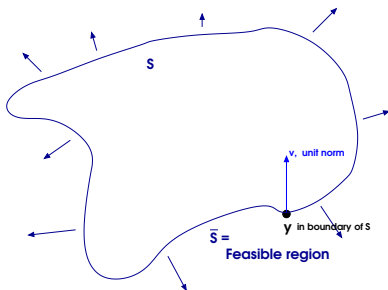
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is valid EVERYWHERE – does not cut-off any points

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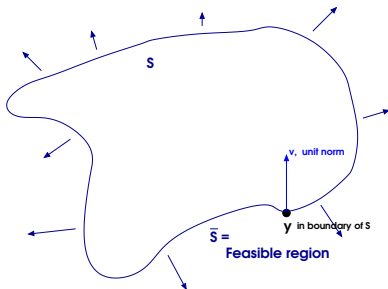
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Lifted first order inequality, for $\alpha \geq 0$:

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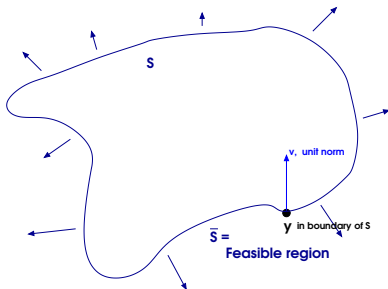


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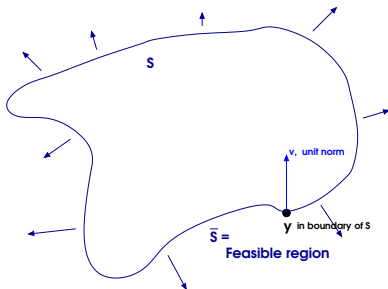
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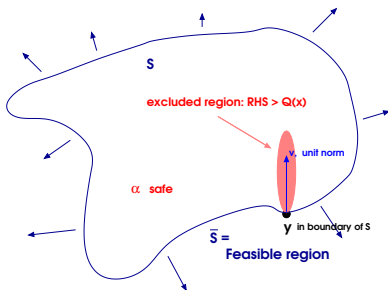
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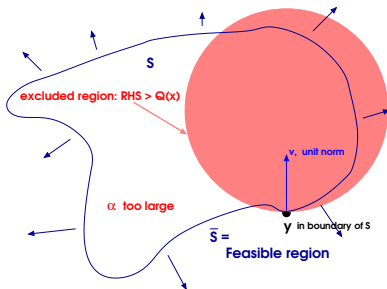
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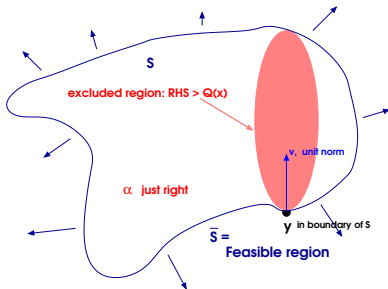
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Given $y \in \partial S$, let

$$\alpha^* \doteq \mathbf{sup} \{ \alpha \geq \mathbf{0} : Q(x) \geq [\nabla Q(y)]^T(x-y) + Q(y) + \alpha v^T(x-y) \}$$

valid for \mathcal{F} .

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Theorem. If Q is convex and differentiable, then $\text{conv}(\mathcal{F})$ is given by

$$\begin{aligned} Q(x) &\geq [\nabla Q(y)]^T(x-y) + Q(y) && \forall y \\ Q(x) &\geq [\nabla Q(y)]^T(x-y) + Q(y) + \alpha^* v^T(x-y) \\ &&& \forall v \text{ and } y \in \partial S. \end{aligned}$$

(abridged)

Separation

Valid **linear** inequalities for $\mathcal{F} \doteq \{ (x, z) \in \mathbb{R}^n \times \mathbb{R} : x \in \overline{S}, z \geq Q(x) \}$.

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Given $(x^*, z^*) \in \mathbb{R}^n \times \mathbb{R}$, how do we separate it from $\text{conv}(\mathcal{F})$?

- Convexity \Rightarrow strongest first-order inequality at x^* is

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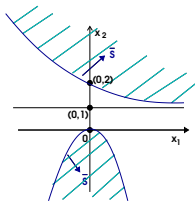
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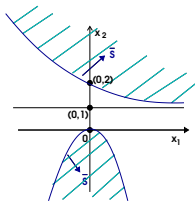
- As a result, poly time separation from $\text{conv}(\mathcal{F})$ is equivalent to poly time separation of lifted first-order inequalities.

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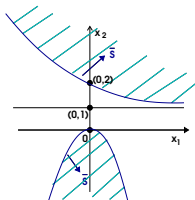
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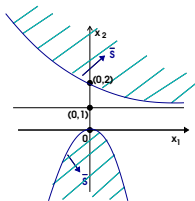
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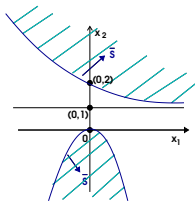
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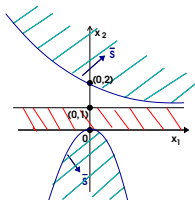
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With $v = (0, 1)^T$, the lifted first-order inequality at $(0, 0)$ is $z \geq \alpha^* x_2 \Rightarrow \alpha^* = e^{-1}$. **Why?**

Because when $x_2 = 1$, $x_2 + e^{-x_2} - 1 = e^{-1} = e^{-1}x_2$, but any larger value for α^* will result with $x_2 + e^{-x_2} - 1 < \alpha^* x_2$ for **some** $x_2 > 1$

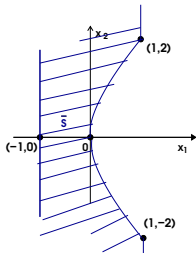
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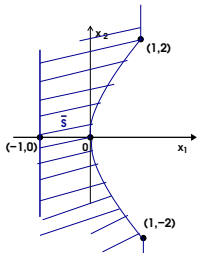
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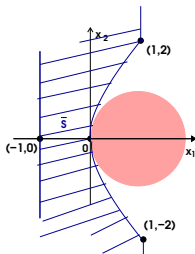
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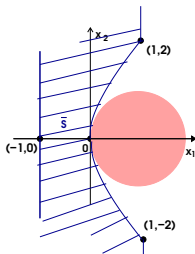
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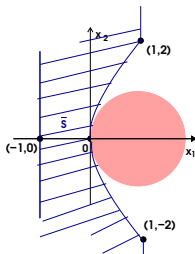
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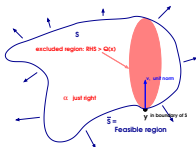


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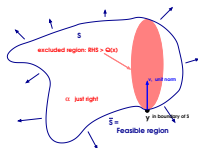
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But **fails to hold** for $R > 1$ and $x_1 \approx 0$!

Lifted first-order inequality at $y \in \partial S$, in the direction of v : $Q(x) \geq [\nabla Q(y)]^T(x - y) + Q(y) + \alpha^* v^T(x - y)$



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Theorem. If

- $Q(x)$ grows faster than linearly in every direction, and
- There is a ball with interior in the infeasible region, but containing y at its boundary

then the quantity α^* is a “max” and not just a “sup”, i.e. the lifted inequality is tight at some point other than y

Quadratics

Valid **linear** inequalities for $\mathcal{F} = \{ (x, z) : x \in \overline{S}, z \geq Q(x) \}$.

Special case $Q(x)$ a **positive definite** quadratic.

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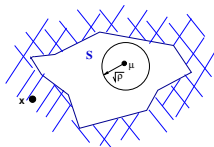
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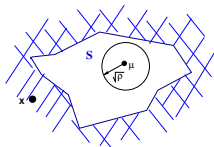
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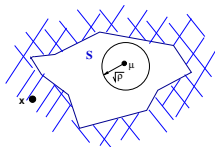
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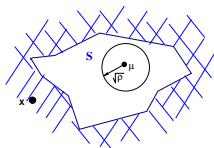
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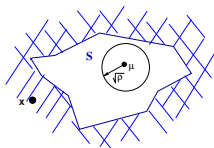
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Theorem: the undominated ball inequalities, and the lifted first-order inequalities, are the same.

Quadratics in action

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Corollary: $\text{conv}(\mathcal{F}) = \{(x, z) : z \geq x(I - \lambda^{-1}A)x + 2\lambda^{-1}b^T x - \lambda^{-1}c, z \geq \|x\|^2\}$.

Also obtained by J.P. Vielma (2013)

But ... Exclude-and-cut, again

$$\min z, \quad \text{s.t.} \quad z \geq Q(x), \quad x \in F$$

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3. Add to the formulation an inequality $\mathbf{a}z + \boldsymbol{\alpha}^T \mathbf{x} \geq \alpha_0$ valid for

$$\{(x, z) : x \in \bar{S}, z \geq Q(x)\}$$

but violated by (x^*, z^*) .

A classical problem: the trust-region subproblem

$$\begin{aligned} \min \quad & x^T A x + b^T x + c \\ \text{s.t.} \quad & \|x\|^2 \leq 1 \\ & x \in \mathbb{R}^n \end{aligned}$$

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Sturm and Zhang (2000): two extensions are polynomially solvable:

$$\begin{aligned} \min \quad & x^T A x + b^T x + c \\ \text{s.t.} \quad & \|x\|^2 \leq 1 \\ & \|x - x^0\|^2 \leq r \end{aligned}$$

(one additional ball inequality), and

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Note: Results leave open the general case with $m = 2$

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$$\begin{aligned} \text{(TLIN):} \quad & \min \quad x^T A x + b^T x + c \\ & \text{s.t.} \quad \|x\|^2 \leq 1 \\ & \quad \quad a_i^T x \leq b_i \quad i = 1, \dots, m \\ & \quad \quad x \in \mathbb{R}^n. \end{aligned}$$

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Theorem: Problem **TLIN** can be solved in time polynomial in the problem size and F^* .

A stronger generalization

$$\begin{aligned} \text{(TGEN):} \quad & \min \quad x^T A x + b^T x + c \\ & \text{s.t.} \quad \|x - x^k\|^2 \leq f_k \quad k = 1, \dots, L_k \\ & \quad \quad \|x - y^k\|^2 \geq g_k \quad k = 1, \dots, M_k \\ & \quad \quad \|x - z^k\|^2 = h_k \quad k = 1, \dots, E_k \\ & \quad \quad a_i^T x \leq b_i \quad i = 1, \dots, m \\ & \quad \quad x \in \mathbb{R}^n. \end{aligned}$$

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- $F^* =$ the number of faces of P that intersect $\bigcap_k \{x : \|x - x^k\| \leq f_k\}$.

Theorem: For every fixed $L_k \geq 1, M_k \geq 0, E_k \geq 0$, problem **TGEN** can be solved in time polynomial in the problem size and F^* .

(SODA 2014)