

A Simple Method for Estimating Betas When Factors Are Measured with Error[†]

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Abstract

We propose a simple method for estimating betas (factor loadings) when factors are measured with error: Ordinary Least-squares Instrumental Variable Estimator (OLIVE). OLIVE is intuitive and easy to implement. OLIVE performs well when the number of instruments becomes large (can be larger than the sample size), while the performance of conventional instrumental variable methods and two-step GMM becomes poor or even infeasible. OLIVE is especially suitable for estimating asset return betas, since this is often a large N and small T setting. Intuitively, since all asset returns vary together with a common set of factors, one can use information contained in other asset returns to improve the beta estimate for a given asset. We apply the method to reexamine Lettau and Ludvigson's (2001b) test of the (C)CAPM. We find that in regressions where macroeconomic factors are included, using OLIVE instead of OLS beta estimates improves the R-squared significantly (e.g., from 31% to 80%). More importantly, our results based on OLIVE beta estimates help to resolve two puzzling findings by Lettau and Ludvigson (2001b) and Jagannathan and Wang (1996): first, the sign of the average risk premium on the beta for the market return changes from negative to positive, consistent with the theory; second, the estimated value of average zero-beta rate is no longer too high (e.g., from 5.19% to 1.91% per quarter).

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1. Introduction

In financial economics, we often need to estimate asset return betas (factor loadings). OLS is the simplest and most widely used method by both academic researchers and practitioners. However, factors, especially those constructed using macroeconomic data, are known to contain large measurement error. In addition, even when a factor is measured accurately, it may still be different from the true underlying factor. For example, the return on the stock market index is perhaps measured reasonably accurately, but it may still contain large “measurement error” in the sense that it may be an imperfect proxy for the return on the true market portfolio (Roll’s (1977) critique). Under these circumstances, the OLS beta estimator will be inconsistent. Furthermore, in the Fama and MacBeth (1973) two-pass framework, if the first-pass beta estimates are inconsistent due to measurement error in factors, then the second-pass risk premia and zero-beta rate estimates will be inconsistent as well.

Instrumental variable estimation is the usual solution to the measurement error problem. Intuitively, since all asset returns vary together with a common set of factors, one can use information contained in other asset returns to improve the beta estimate for a given asset. This is often a large N and small T setting, because there are typically more assets or stocks than time periods. Ideally, we would want to use all available information, that is, all valid instruments (the other $(N-1)$ asset returns), but conventional instrumental variable estimators such as 2SLS (Two-Stage Least Squares) perform poorly when the number of instruments is large. This is similar to the “weak instruments” problem (Hahn and Hausman (2002)). Further, these methods cannot accommodate more instruments than the sample size.

In this paper, we propose a simple method for estimating betas when factors are measured with error: Ordinary Least-squares Instrumental Variable Estimator (OLIVE). OLIVE easily allows for large numbers of instruments (can be larger than the sample size). It is intuitive,

easy to implement, and achieves better performance in simulations than other instrumental variable estimators such as 2SLS, B2SLS (Bias-corrected Two-Stage Least Squares), LIML (Limited Information Maximum Likelihood), and FULLER (Fuller (1977)), especially when the number of potential instruments ($N-1$) is large and the sample size (T) is small.

We show that OLIVE is a consistent estimator, under the assumption that idiosyncratic errors are cross-sectionally independent (Proposition 1). Consistency is obtained when the number of assets (N) is fixed or goes to infinity. When idiosyncratic errors are cross-sectionally correlated, returns of other assets as instruments are invalid in the conventional sense because they are correlated with the regression errors. We show that even in this case, OLIVE beta estimates remain consistent, provided that N is large (Proposition 2). In a sense, we exploit the large N of panel data to arrive at a consistent estimator. Since conventional GMM breaks down for $N > T$, and consistency in the absence of valid instruments requires large N , OLIVE's ability to handle large N is appealing.

OLIVE can be viewed as a one-step GMM estimator using the identity weighting matrix. When N is larger than T , the optimal weighting matrix in the GMM estimation cannot be consistently estimated in the usual unconstrained way. However, in our particular setting, we are able to derive the two-step equation-by-equation GMM estimator, as well as the joint GMM estimator, based on the restrictions implied by the model. Even though the two-step GMM estimator is asymptotically optimal, it performs worse than OLIVE in simulations. This is because the two-step GMM estimator has poor finite sample properties due to imprecise estimation of the optimal weighting matrix.

Previous studies also have shown that the two-step GMM estimator which is optimal in the asymptotic sense can be severely biased in finite samples of reasonable size (e.g., Ferson and Foerster (1994), Hansen, Heaton, and Yaron (1996), Newey and Smith (2004), and Doran and Schmidt (2006)). One-step GMM estimators use weighting matrices that are independent of estimated parameters, whereas the efficient two-step GMM estimator weighs the moment

conditions by a consistent estimate of their covariance matrix. This weighting matrix is constructed using an initial consistent estimate of the parameters in the model. Wyhowski (1998) performs simulations for the dynamic panel data model that show the GMM estimator performs quite well if the true optimal weighting matrix is used. Methods to correct the bias problem include, for example, using a subset of the moment conditions and normal quasi-MLE. Other solutions to this problem use higher order expansions to construct weighting matrix estimators, or use generalized empirical likelihood (G.E.L.) estimators as in Newey and Smith (2004). In another recent paper, Doran and Schmidt (2006) suggest using principal components of the weighting matrix. Given the difficulty in estimating the optimal weighting matrix, especially when N is large, using identity weighing matrix becomes an intuitive option. OLIVE can be viewed as a GMM estimator using the identity weighting matrix.

Fama and MacBeth's (1973) two-pass method can be modified by using OLIVE instead of OLS to estimate betas in the first-pass. As an empirical application, we reexamine Lettau and Ludvigson's (2001b) test of the (C)CAPM using this modified Fama-MacBeth method. Lettau and Ludvigson's factor *cay* has been found to have strong forecasting power for excess returns on aggregate stock market indices. The factor *cay* is the cointegrating residual between log consumption c , log asset wealth a , and log labor income y . Macroeconomic variables usually contain large measurement error. We find that in regressions where macroeconomic factors are included, using OLIVE instead of OLS improves the R^2 significantly (e.g., from 31% to 80%).

More importantly, our results based on OLIVE beta estimates help to resolve two puzzling findings by Lettau and Ludvigson (2001b). As mentioned earlier, if we use OLS when factors are measured with error, both the first-pass beta estimates and the second-pass risk premia and zero-beta rate estimates will be inconsistent. On the other hand, since OLIVE beta estimates are consistent even when factors contain measurement error, the risk premia and zero-beta rate can be consistently estimated in the second-pass if OLIVE is used in the first-pass to estimate betas.

First, Lettau and Ludvigson (2001b) state that “[a] problem with this model, however, is that there is a negative average risk price on the beta for the value-weighted return.” They also note that “Jagannathan and Wang (1996) report a similar finding for the signs of the risk prices on the market and human capital betas” (page 1259). When we use OLIVE beta estimates, this problem goes away. Using OLIVE instead of OLS estimation in the first-pass changes the sign of the average risk premium on the beta for the value-weighted market index from negative to positive, which is in accordance with the theory.

Second, in Lettau and Ludvigson (2001b), “the estimated value of the average zero-beta rate is large.” As the authors observed, this finding is not uncommon in studies that use macroeconomic factors. They note that Jagannathan and Wang (1996) also find the estimated zero-beta rates to be large. Lettau and Ludvigson (2001b) note that sampling error could be one of the potential explanations for this puzzling finding. However, they conclude that “[p]rocedures for discriminating the sampling error explanation for these large estimates of the zero-beta rate from others are not obvious, and its development is left to future research” (page 1260). We find that, when OLIVE beta estimates from the first-pass are used, the estimated value of the average zero-beta rate in the second-pass is no longer too high (e.g., from 5.19% to 1.91% per quarter). Our results suggest that measurement error in factors is the cause of this problem. Sampling error is a second-order issue; it becomes negligible as the sample size T becomes large. Unlike sampling error, the measurement error problem does not diminish as the sample size T becomes large, because OLS produces inconsistent beta estimates. When macroeconomic factors with measurement error are included in the model, OLIVE can provide more precise beta estimates in the first-pass, which lead to more precise estimates of the zero-beta rate in the second-pass.

In contrast, it makes almost no difference whether we use OLIVE or OLS to estimate betas for the Fama-French three-factor model, where the factors may contain little measurement error as they are constructed from stock returns. Overall, our results from this empirical

application validate the use of OLIVE to help improve beta estimation when factors are measured with error. Our empirical results support and strengthen Lettau and Ludvigson (2001b) and Jagannathan and Wang (1996) by resolving some of their puzzling findings. Our findings are also consistent with the theme in Ferson, Sarkissian, and Simin (2007) that the (C)CAPMs might work better than previously recognized in the literature.

Many existing empirical asset pricing models implicitly assume that macroeconomic variables are measured without error, for example, Chen, Roll, and Ross (1986). Previous studies have noted the measurement error problem in this context (see, e.g., Ferson and Harvey (1999)). Connor and Korajczyk (1991) develop and apply a procedure similar to 2SLS. They first regress macroeconomic variables on statistical factors obtained from Asymptotic Principal Components (APC, developed in Connor and Korajczyk (1986)), and then use fitted values instead of original macroeconomic variables in asset pricing tests. They find that most of the variation in macroeconomic variables is measurement error. Their method can potentially overcome the measurement error problem in macroeconomic variables. However, since the fitted values are linear combinations of statistical factors, they do not contain any more information beyond statistical factors, which lack clear economic interpretations. Wei, Lee, and Chen (1991) also note the presence of errors-in-variables problem in factors. They use the standard econometric treatment: instrumental variables approach (IV or 2SLS). Both their factors and instruments are size-based portfolios. Even if there is measurement error in size-based portfolio returns, the problem would not be solved by using other size-based portfolio returns as instruments. As one would expect, they find extremely high first-stage R^2 's. This means their IV results will be very similar to OLS results, and indeed that is what they find.

The rest of the paper is organized as follows. In Section 2, we describe the model setup and introduce the simple estimator, OLIVE. We also outline other conventional IV estimators. In Section 3, as a theoretical extension, we derive the two-step equation-by-equation GMM estimator and the joint GMM estimator. We conduct a Monte Carlo simulation study to compare

the above estimators in Section 4. In Section 5, we reexamine some results in Lettau and Ludvigson (2001b) as an empirical application of OLIVE. Section 6 concludes.

2. Estimation Framework

2.1. Model Setup

To describe the model, we begin by assuming that asset returns are generated by a linear multi-factor model:

$$y_{it} = x_t^* ' B_i + e_{it}, \quad (1)$$

where $i = 1, \dots, N$, $t = 1, \dots, T$, y_{it} is asset i 's return at time t , x_t^* is an $M \times 1$ vector of true factors at time t , and B_i is an $M \times 1$ vector of factor loadings for asset i . However, the true factors x_t^* are observed with error:

$$x_t = x_t^* + v_t, \quad (2)$$

where v_t is an $M \times 1$ vector of measurement error. This is similar to the setup in Connor and Korajczyk (1991) and Wansbeek and Meijer (2000). Using (2), we can rewrite (1) as:

$$y_{it} = x_t ' B_i + \varepsilon_{it}, \quad (3)$$

where $\varepsilon_{it} = e_{it} - v_t ' B_i$.

We cannot use OLS to estimate B_i equation-by-equation, even though x_t is observable, because the error term ε_{it} is correlated with the observable factors x_t due to the measurement error v_t .

For a fixed asset i , rewrite (3) as

$$Y_i = X B_i + \varepsilon_i, \quad (4)$$

where Y_i is a T vector of asset returns, $X \equiv [1, (x_1, \dots, x_T)']$ is a $T \times (M + 1)$ matrix of observable factors (1 is a T vector of 1's), and B_i is an $(M+1)$ vector of factor loadings. As noted before, OLS produces inconsistent estimates of factor loadings:

$$\widehat{B}_i^{OLS} = (X'X)^{-1}X'Y_i. \quad (5)$$

Let $Y_{-i} \equiv [Y_1, \dots, Y_{i-1}, Y_{i+1}, \dots, Y_N]$ be a $T \times (N-1)$ matrix of all asset returns excluding the i th asset. Then Y_{-i} can serve as instrumental variables. Let $Z_i \equiv [1, Y_{-i}]$, multiply both sides of equation (4) by Z_i to obtain:

$$Z_i'Y_i = Z_i'XB_i + Z_i'\varepsilon_i. \quad (6)$$

It can be shown that the usual IV or 2SLS is equivalent to running Feasible GLS on (6); that is,

$$\widehat{B}_i^{2SLS} = (X'Z_i(Z_i'Z_i)^{-1}Z_i'X)^{-1}X'Z_i(Z_i'Z_i)^{-1}Z_i'Y_i. \quad (7)$$

The idea of 2SLS is first to project the regressors (X) onto the space of instruments (Z_i), and then to regress the dependent variables (Y_i) on fitted values of regressors instead of regressors themselves. It is well known that two-staged least squares (2SLS) estimators may perform poorly when the instruments are weak or when number of instruments is large. In this case 2SLS tends to suffer from substantial small sample biases.

2.2. OLIVE

The motivation behind our approach begins with the fact that 2SLS only works when N (number of instruments) is much smaller than T (sample size), which is not the case for most finance applications. To illustrate the problem, imagine the case where $N = T$. Then the fitted values are the same as original regressors, and 2SLS becomes the same as OLS. This problem of 2SLS is related to the “weak instruments” literature in econometrics, which has grown rapidly in recent years; see for example Hahn and Hausman (2002).

We propose to estimate factor loadings B_i by simply running OLS on equation (6). We call it Ordinary Least-squares Instrumental Variable Estimator (OLIVE):

$$\widehat{B}_i^{OLIVE} = (X'Z_iZ_i'X)^{-1}X'Z_iZ_i'Y_i. \quad (8)$$

Proposition 1. *Under the assumption that idiosyncratic errors e_{it} are cross-sectionally independent, then for either fixed N or N going to infinity, the OLIVE estimator is \sqrt{T} consistent and asymptotically normal.*

See Appendix A for a proof of Proposition 1. Proposition 1 relies on the assumption of valid instruments. That is, e_{jt} is uncorrelated with e_{it} ($j \neq i$). However, if the idiosyncratic errors are also cross-sectionally correlated, none of the instruments will be valid in the conventional sense. For example, if the objective is to estimate B_1 , by equation (3), $\varepsilon_{1t} = e_{1t} - B_1'v_t$. When e_{1t} is correlated with e_{jt} , y_{jt} will be correlated with ε_{1t} . Thus y_{jt} will not be a valid instrument. However, we can still establish the consistency of the OLIVE, provided that the cross-sectional correlation is not too strong and N is large. To this end, let $\gamma_{ij} = E(e_{it}e_{jt})$. We assume

$$\sum_{j=1}^N |\gamma_{ij}| \leq C < \infty \quad (9)$$

for each i . This condition is analogous to the sum of autocovariances being bounded in the time series context, a requirement for a time series being weakly correlated. Bai (2003) shows that the condition implies (3) being an approximate factor model of Chamberlain and Rothschild (1983).

Proposition 2. *Under the assumption of weak cross-sectional correlation for the idiosyncratic errors as stated in (9), if $\sqrt{T}/N \rightarrow 0$, then the OLIVE estimator is \sqrt{T} consistent and asymptotically normal.*

A proof of Proposition 2 is provided in Appendix B. Mere consistency would only require $1/N \rightarrow 0$. It is the \sqrt{T} consistency and asymptotic normality that require $\sqrt{T}/N \rightarrow 0$. Note that under fixed N , all IV estimators discussed in the next section including

OLIVE (using y_{jt} as instruments) will be inconsistent due to the lack of valid instruments. In a sense, we exploit the large N of panel data to arrive at a consistent estimator. Far from being a nuisance, large N is clearly beneficial. In view that conventional GMM breaks down for $N > T$ and consistency in the absence of valid instruments requires large N , OLIVE's ability to handle large N is appealing.

Let $\hat{\varepsilon}_i = Y_i - X\hat{B}_i^{OLIVE}$ and $\hat{\sigma}_i^2 = \frac{1}{T-M-1} \hat{\varepsilon}_i' \hat{\varepsilon}_i$, the variance-covariance matrix of

\hat{B}_i^{OLIVE} is a $(M+1) \times (M+1)$ matrix:

$$\hat{\Omega}_i = \hat{\sigma}_i^2 (X'Z_iZ_i'X)^{-1} (X'Z_iZ_i'Z_iZ_i'X) (X'Z_iZ_i'X)^{-1}. \quad (10)$$

The above estimation is done for each $i = 1, \dots, N$. With the B_i obtained for each i , we can estimate x_t^* using a cross-section regression based on equation (1). This is done for each $t = 1, \dots, T$. Given x_t^* , the estimated risk premia can be recovered as in Black, Jensen, and Scholes (1972) (see also Campbell, Lo, and MacKinlay (1997, Chapter 6)).

The above setup also allows us to test the validity of the multi-factor models. When the instrumental variables are $Z_i \equiv [t, Y_{-i}]$, the constant regressor t itself is an instrumental variable.

The test for the constant coefficient's being zero is $t = \frac{\hat{a}_i}{\sqrt{\hat{\Omega}^{11}}}$, where $\hat{\Omega}^{11}$ is the first diagonal

element of the inverse matrix $\hat{\Omega}_i^{-1}$.

There is an alternative method for estimating the true factors, i.e., the method of Connor and Korajczyk (1991). They first regress the observed factors on APC estimated statistical factors and use the fitted values as estimates of the true factors (rotate observed factors onto statistical factors). They find the R-squared to be quite small, and they interpret this as evidence for much measurement error in the observed factors. APC should have good performance theoretically and empirically. However, the statistical factors using the principle-components

method lack clear economic interpretations. In contrast, note that estimated factors x_t^* using OLIVE has the same interpretations as x_t , the observable factors. Thus the estimated risk premia also have economic interpretations.

2.3. Other IV Estimators

We compare the performance of OLIVE with OLS and several well known IV estimators: 2SLS, LIML, B2SLS, as well as FULLER. OLS is to be considered as a benchmark. 2SLS is the most widely used IV estimator. It has finite sample bias that depends on the number of instruments used (K) and inversely on the R^2 of the first-stage regression (Hahn and Hausman (2002)). The higher-order mean bias of 2SLS is proportional to the number of instruments K . However 2SLS can have smaller higher-order mean squared error (MSE) than LIML using the second-order approximations when the number of instruments is not too large. LIML is known not to have finite sample moments of any order. LIML is also known to be median unbiased to second order and to be admissible for median unbiased estimators (Rothenberg (1983)). The higher-order mean bias for LIML does not depend on K . B2SLS denotes a bias adjusted version of 2SLS.

The formulae for these estimators are as follows:

Let $P = Z(Z'Z)^{-1}Z'$ be the idempotent projection matrix, $M = I - P$,

$W \equiv [Y, X]$, $Z = (y_1, y_2, \dots, y_{i-1}, y_{i+1}, \dots, y_N)$, then:

$$\begin{aligned}
 \hat{\beta}_{OLS} &= (X'X)^{-1}X'Y \\
 \hat{\beta}_{2SLS} &= (X'PX)^{-1}X'PY \\
 \hat{\beta}_{LIML} &= (X'(P - \hat{\lambda}M)X)^{-1}X'(P - \hat{\lambda}M)Y \\
 \hat{\beta}_{B2SLS} &= (X'(P - \bar{\lambda}M)X)^{-1}X'(P - \bar{\lambda}M)Y \\
 \hat{\beta}_{FULLER} &= (X'(P - \tilde{\lambda}M)X)^{-1}X'(P - \tilde{\lambda}M)Y \\
 \hat{\beta}_{OLIVE} &= (X'ZZ'X)^{-1}X'ZZ'Y
 \end{aligned} \tag{11}$$

For the above equations, 2SLS, LIML, B2SLS, and FULLER can all be regarded as κ -class estimators given by $\frac{X'PY - \kappa X'MY}{X'PX - \kappa X'MX}$. For $\kappa = 0$, we get 2SLS. For $\kappa = \hat{\lambda}$, which is the smallest eigenvalue of the matrix $W'PW(W'MW)^{-1}$, we obtain LIML. For $\kappa = \bar{\lambda}$, which equals $\frac{K-2}{T}$, we obtain B2SLS. For $\kappa = \tilde{\lambda}$, which equals $\hat{\lambda} - \frac{\alpha}{T-K}$, we obtain FULLER. Following Hahn, Hausman, and Kuersteiner (2004), we consider the choice of α to be either 1 or 4 in our simulation studies later (Section 4). The choice of $\alpha = 1$ is advocated by Davidson and McKinnon (1993), which has the smallest bias, while $\alpha = 4$ has a nonzero higher mean bias, but a smaller MSE according to calculation based on Rothenberg's (1983) analysis.

3. Efficient Two-Step GMM

What makes OLIVE appealing is its ease of use. Since OLIVE is a GMM estimator when setting the weighting matrix to an identity matrix, it is natural to try to improve the efficiency of the estimator by using the optimal weighting matrix. Traditional unconstrained GMM will break down when $N > T$ (the estimated weighting matrix is not invertible). We will derive the theoretical weighting matrix, which depends on far fewer number of parameters. Replacing the unknown parameters by their estimated counterparts will result in an estimated theoretical weighting matrix, which is invertible even for $N > T$. In Section 3.1., we describe the equation-by-equation GMM estimation, and in Section 3.2., we describe the joint GMM estimation.

3.1. Equation-by-Equation GMM

Consider estimating B_i for equation i . By definition, $\varepsilon_{it} = y_{it} - x_t' B_i = e_{it} - v_t' B_i$. For every j ($j \neq i$), y_{jt} can serve as an instrument. Let $u_{ijt} = y_{jt} \varepsilon_{it} = (x_t^*{}' B_j + e_{jt})(e_{it} - v_t' B_i)$.

Under the assumption that e_{it} , e_{jt} , v_t , and x_t^* are mutually independent, the moment conditions, or orthogonality conditions, will be satisfied at the true value of B_i :

$$E(u_{ijt}) = E\left[y_{jt}(y_{it} - x_t' B_i)\right] = 0. \quad (12)$$

Each of the $(N-1)$ moment equations corresponds to a sample moment, and we write these $(N-1)$ sample moments as:

$$\bar{u}_{ij}(B_i) = \frac{1}{T} \sum_{t=1}^T u_{ijt}(B_i). \quad (13)$$

Let $\bar{u}_i(B_i)$ be defined by stacking $\bar{u}_{ij}(B_i)$ over j . For a given weighting matrix W_i , the equation-by-equation GMM is estimated by minimizing: $\min_{B_i} \bar{u}_i(B_i)' W_i^{-1} \bar{u}_i(B_i)$. For each i, t , let u_{it} be the $(N-1)$ vector by stacking u_{ijt} over j . The optimal weighting matrix is $W_i = E(u_{it} u_{it}')$. Given the above functional form for u_{ijt} , W_i can be parameterized in terms of $\text{var}(e_{it})$ and B_i for each i , $\text{var}(v_t)$, and $\text{var}(x_t^*) = \text{var}(x_t) - \text{var}(v_t)$.

We now derive the expression of W_i . The (j, k) th element of W_i ($j \neq i, k \neq i$) is given by:

$$\begin{aligned} E(u_{ijt} u_{ikt}) &= E\left[y_{jt}(e_{it} - v_t' B_i)(e_{it} - B_i' v_t) y_{kt}\right] \\ &= E\left[y_{jt} (\text{var}(e_{it}) + B_i' \text{var}(v_t) B_i) y_{kt}\right] \\ &= E\left[(B_j' x_t^* + e_{jt})(x_t^* B_k + e_{kt})(\text{var}(e_{it}) + B_i' \text{var}(v_t) B_i)\right], \quad (14) \\ &= E\left[(B_j' \text{var}(x_t^*) B_k + \delta_{jk} \text{var}(e_{jt}))(\text{var}(e_{it}) + B_i' \text{var}(v_t) B_i)\right] \\ &= (B_j' \text{var}(x_t^*) B_k + \delta_{jk} \text{var}(e_{jt}))(\text{var}(e_{it}) + B_i' \text{var}(v_t) B_i) \end{aligned}$$

where $\delta_{jk} = 1$ if $j = k$, and zero otherwise. In the last equality, B_j s are assumed non random coefficients.

For example, suppose $i = 1$, then the above covariance matrix is simply the following.

Let

$$\Lambda_{-1} = \begin{bmatrix} B_2 \\ B_3 \\ \vdots \\ B_N \end{bmatrix}, \quad (15)$$

then the $(N-1)$ by $(N-1)$ covariance matrix W_1 is given by:

$$W_1 = (\text{var}(e_{1t}) + B_1' \text{var}(v_t) B_1) (\Lambda_{-1} \text{var}(x_t^*) \Lambda_{-1}' + \Omega_{-1}), \quad (16)$$

where Ω_{-1} is a diagonal matrix of dimension $(N-1)$, that is

$$\Omega_{-1} = \text{diag}(\text{var}(e_{2t}), \dots, \text{var}(e_{Nt})). \quad (17)$$

Note that $(\text{var}(e_{1t}) + B_1' \text{var}(v_t) B_1)$ is a scalar, which is the variance of the OLS residual

ε_{1t} , thus can be estimated by $\frac{1}{T} \sum_{t=1}^T \hat{\varepsilon}_{1t}^2$.

For a general i , the formula for W_i becomes:

$$W_i = (\text{var}(e_{it}) + B_i' \text{var}(v_t) B_i) (\Lambda_{-i} \text{var}(x_t^*) \Lambda_{-i}' + \Omega_{-i}). \quad (18)$$

The analytical expression for the inverse of W_i is:

$$\begin{aligned} W_i^{-1} &= \frac{(\Lambda_{-i} \text{var}(x_t^*) \Lambda_{-i}' + \Omega_{-i})^{-1}}{\text{var}(e_{it}) + B_i' \text{var}(v_t) B_i} \\ &= \frac{\Omega_{-i}^{-1} - \Omega_{-i}^{-1} \Lambda_{-i} \left((\text{var}(x_t^*)^{-1}) + \Lambda_{-i}' \Omega_{-i}^{-1} \Lambda_{-i} \right)^{-1} \Lambda_{-i}' \Omega_{-i}^{-1}}{\text{var}(\varepsilon_{it})} \end{aligned} \quad (19)$$

The estimation procedure is then as follows.

First we use OLIVE to obtain, for each asset i , \widetilde{B}_i and $\hat{\varepsilon}_{it} = y_{it} - x_{it}' \widetilde{B}_i$, which equals an estimate of $e_{it} - v_t' B_i$. The denominator of W_i^{-1} is computed by the sample variance of $\hat{\varepsilon}_{it}$.

Second, given \widetilde{B}_i , we run cross-sectional regression to obtain x_t^* for each t , and then estimate $\text{var}(x_t^*)$. Also, given x_t^* , we can estimate $\hat{e}_{it} = y_{it} - x_t^* \widetilde{B}_i$, so that $\text{var}(e_{it})$ are computed for each i .

Third, we use the above estimates to construct a consistent estimate of $E(u_t u_t')$, and use that to do two-step GMM. For each asset i , there is an $(N-1) \times (N-1)$ weighing matrix W_i .

The estimate of beta is:

$$\hat{B}_i = (X' Z_i \hat{W}_i^{-1} Z_i' X)^{-1} X' Z_i \hat{W}_i^{-1} Z_i' Y_i. \quad (20)$$

The choice of W_i is optimal in the sense that it leads to the smallest asymptotic variance matrix for the GMM estimate. However, a number of papers have found that GMM estimators using all of the available moment conditions may have poor finite sample properties in highly identified models. With many moment conditions, the optimal weighting matrix is poorly estimated. The problem becomes more severe when many of the moment conditions (implicit instruments) are “weak.” The poor finite sample performance of the estimates has two aspects, as noted by Doran and Schmidt (2006). First, the estimates may be seriously biased. This is generally believed to be a result of correlation between the estimated weighting matrix \hat{W}_i and the sample moment conditions in equation (13). Second, the asymptotic variance expression may seriously understate the finite sample variance of the estimates, so that the estimates are spuriously precise.

3.2. Joint GMM

In this subsection, we discuss joint GMM estimation of $B = (B_1', B_2', \dots, B_N)'$. Let u_t be the vector with elements u_{ijt} for all i, j pairs ($j \neq i$). The optimal GMM weighting matrix, $E(u_t u_t')$, is difficult to estimate in the usual unconstrained way because the number of moment conditions, $N(N-1)$, can be much larger than T . Under our model specification, however, $E(u_t u_t')$ can also be parameterized in terms of $\text{var}(e_{it})$, B_i , $\text{var}(v_t)$, and $\text{var}(x_t^*)$.

The $N(N-1)$ by $N(N-1)$ weighting matrix W can be partitioned into N^2 block matrices, each being $(N-1)$ by $(N-1)$. We denote these block matrices $W_{ih} = E(u_{it}u_{ht}')$, for all $i, h = 1, \dots, N$. The block diagonal matrix W_{ii} corresponds to the equation-by-equation weighting matrix W_i , as derived in equation (14) in the previous subsection. In short, the (j, k) th element of the block diagonal matrix W_{ii} (denoted as w_{jk}^{ii}) is:

$$\begin{aligned} w_{jk}^{ii} &= E(u_{ijt}u_{ikt}) = E\left[y_{jt}(e_{it} - v_t' B_i)(e_{it} - B_i' v_t)y_{kt}\right] \\ &= (B_j' \text{var}(x_t^*) B_k + \delta_{jk} \text{var}(e_{jt})) (\text{var}(e_{it}) + B_i' \text{var}(v_t) B_i) \end{aligned}$$

The block off-diagonal matrix W_{ih} ($i \neq h$) represents the variance-covariance matrix between the orthogonality conditions for assets i and h . This matrix is nonzero because an instrument used for asset i may also be used for asset h . In addition, asset i is also an instrument for asset h and vice versa. Thus the orthogonality conditions associated with different equations are correlated. The (j, k) th element of this matrix, w_{jk}^{ih} , equals $E(u_{ijt}u_{hkt}) = E\left[y_{jt}(e_{it} - v_t' B_i)(e_{ht} - B_h' v_t)y_{kt}\right]$, where $j \neq i$ and $k \neq h$ by definition of IV. We derive the formulae for w_{jk}^{ih} , the (j, k) th element of the block off-diagonal matrix W_{ih} , in each of the four possible cases in Appendix C.

We now have the whole weighting matrix W . GMM is estimated by minimizing $\min_B \bar{u}(B)' W^{-1} \bar{u}(B)$. The estimate of beta is:

$$\hat{B} = ((I \otimes X)' Z \hat{W}^{-1} Z' (I \otimes X))^{-1} (I \otimes X)' Z \hat{W}^{-1} Z' Y, \quad (21)$$

where $Y = (Y_1', \dots, Y_N)'$. Z is a block diagonal matrix, with $Z = \text{diag}(Z_1, Z_2, \dots, Z_N)$, where $Z_i \equiv [I, Y_{-i}]$.

Joint GMM will not be used in this paper because the number of moment conditions, $N(N-1)$, is too large. But if N is small, joint GMM will be useful. In the next simulation section,

when comparing OLIVE with other estimators, we only consider the two-step equation-by-equation GMM estimator (2GMM), in addition to the IV estimators discussed in Section 2.3.

4. Simulation Study

4.1. Monte Carlo Design

We conduct a Monte Carlo simulation study to compare the performance of our simple OLIVE estimator with other estimators. The data generating process (DGP) for our simulation study is as follows. We assume no intercept, i.e., arbitrage pricing theory (APT) or capital asset pricing model (CAPM) holds, as in Connor and Korajczyk (1993) and Jones (2001). Although the estimation framework is general for any factor model, we implement our simulation with a stock market application in mind. The DGP below is very similar to the one in Connor and Korajczyk (1993).

We first generate a security with a true beta of one, which is to be estimated. Then we generate $K = N-1$ instruments using the following:

$$\begin{aligned}
 x_t &= x_t^* + v_t, t = 1, \dots, T \\
 y_{it} &= \beta_i' x_t^* + e_{it} = \beta_i' x_t + (-\beta_i' v_t + e_{it}) = \beta_i' x_t + \varepsilon_{it}, i = 1, \dots, N \\
 x_t^* &\sim MVN(\pi, \sigma_x^2 I^J) \\
 v_t &\sim MVN(0^J, \sigma_v^2 I^J) \\
 \beta_i &\sim MVN(\mu^J, \sigma_\beta^2 I^J) \\
 e_t &\sim MVN(0^N, \sigma_e^2 I^N) \\
 y_{-i,t} &= (y_{1t}, y_{2t}, \dots, y_{i-1,t}, y_{i+1,t}, \dots, y_{Nt})
 \end{aligned}$$

We use $K = (1, 2, 3, 5, 10, 30, 45, 55, 90, 150, 300, 600)$, $T = 60$, $\pi = 0.1$, $\sigma_x = 0.1$, $\sigma_\beta = 1$ and 1000 replications. Without loss of generality, we assume J , the number of explanatory variables to be 1, which makes the model specification equivalent to the CAPM for the excess return. We allow x and β to be normally generated. One advantage of OLIVE is that when K is larger than T , it still works while most other IV estimators do not.

Two important parameters for the performance of the estimators are the standard deviation of the error in returns, σ_e , and the standard deviation of the measurement error, σ_v . We allow these two parameters to change from low (0.01), medium (0.1), to high (1), i.e., $\sigma_e \in (0.01, 0.1, 1)$ and $\sigma_v \in (0.01, 0.1, 1)$. When σ_e increases from 0.01 to 1, the instruments becomes weaker. When σ_v increases, the magnitude of measurement error increases. Table 1 presents simulation results when both σ_v and σ_e are set equal to 0.1, which is the medium measurement error and medium instruments case.¹

4.2. Monte Carlo Results

In Tables 1, a variety of summary statistics is computed for each estimator. When K is set from 1 to 55 ($K < T$), all estimators are computed. When $K > T$, only OLS, OLIVE, and the two-step equation-by-equation GMM estimator (2GMM) are computed because other IV estimators become infeasible. Following Donald and Newey (2001), we compute the median and mean bias and the median and mean absolute deviation (AD), for each estimator from the true value of β generated. We examine dispersion of each estimator using both the inter-quartile range (IQR) and the difference between the 0.1 and 0.9 deciles (Dec. Rge) in the distribution of each estimator. Throughout, OLS offers the smallest dispersion in terms of both IQR and Dec. Rge. This finding is consistent with Hahn, Hausman, and Kuersteiner (2004). We also report the coverage rate of a nominal 95% confidence interval (Cov. Rate).

When there is only one instrument, 2SLS, LIML, OLIVE, and 2GMM are all equivalent. Throughout, both OLS and 2GMM seem to be biased downwards. As Newey and Smith (2004) point out, the asymptotic bias of GMM often grows with the number of moment restrictions. Our simulation results show that the performance of the two-step GMM estimator becomes worse as

¹ Simulation results under other parameter values are generally similar to those in Table 1. These supplemental tables are not included to save space and are readily available upon request.

the number of instruments grows. As the number of instruments becomes very large (e.g., when $K = 150, 300,$ and 600), 2GMM has even worse performance than OLS.

As expected, LIML performs well in terms of median Bias when it is feasible (when $K = 3, 10, 30,$ and 55). In terms of mean Bias, FULLER1 usually performs well (when $K = 2, 5, 10,$ and 30). In general, OLIVE does quite well in terms of bias. It is comparable to these “unbiased” estimators and sometimes the bias of OLIVE is even smaller (for example, when $K = 2, 5, 45,$ and 55 for median bias, and when $K = 3, 45,$ and 55 for mean bias).

As the number of instruments increase, the advantage of OLIVE in terms of absolute deviation becomes more significant. When K equals 10 and larger, OLIVE has the smallest median and mean absolute deviations. Moreover, when K is larger than 10, OLIVE also has the smallest mean squared error.

When the number of instruments is larger than the number of time periods ($K > T$), instrumental variable estimators such as 2SLS, LIML, B2SLS, and FULLER all become infeasible. Among the three estimators that are still feasible, OLIVE performs significantly better than both OLS and 2GMM in terms of median and mean bias, median and mean absolute deviation, and mean squared error.

Overall, when the number of instruments increases, the advantage of OLIVE becomes more and more significant (this is also true in the supplemental tables). The performance of OLIVE improves almost monotonically as the number of instruments increases (levels off when K becomes very large). On the other hand, other IV estimators usually peak at a certain number of instruments then deteriorate as the number of instruments further increase. This demonstrates another advantage of OLIVE: one can simply use all valid instruments at hand without having to select instruments or determine the optimal number of instruments.

5. Empirical Application: Lettau and Ludvigson (2001b)

5.1. Background

One of the most successful multifactor models for explaining the cross-section of stock returns is the Fama-French three-factor model. Fama and French (1993) argue that the new factors they identify, “small-minus-big” (SMB) and “high-minus-low” (HML), proxy for unobserved common risk factors. However, both SMB and HML are based on returns on stock portfolios sorted by firm characteristics, and it is not clear what underlying economic risk factors they proxy for. On the other hand, even though macroeconomic factors are theoretically easy to motivate and intuitively appealing, they have had little success in explaining the cross-section of stock returns.²

Lettau and Ludvigson (2001b) specify a macroeconomic model that does almost as well as the Fama-French three-factor model in explaining the 25 Fama-French portfolio returns. They explore the ability of *conditional* versions of the CAPM and the Consumption CAPM (CCAPM) to explain the cross-section of average stock returns. They express a conditional linear factor model as an unconditional multifactor model in which additional factors are constructed by scaling the original factors. This methodology builds on the work in Cochrane (1996), Campbell and Cochrane (1999), and Ferson and Harvey (1999). The choice of the conditioning (scaling) variable in Lettau and Ludvigson (2001b) is unique: cay - a cointegrating residual between log consumption c , log asset wealth a , and log labor income y . Lettau and Ludvigson (2001a) finds that cay has strong forecasting power for excess returns on aggregate stock market indices. Lettau and Ludvigson (2001b) argue that cay may have important advantages as a scaling variable in cross-sectional asset pricing tests because it summarizes investor expectations about the entire market portfolio.

We conjecture that, as with most factors constructed using macroeconomic data, cay may contain measurement error. If so, our OLIVE method should improve the findings in Lettau and

² See Ludvigson and Ng (2007) for a discussion of current empirical literature on the risk-return relation.

Ludvigson (2001b). Indeed, our empirical results suggest the presence of large measurement error in *cay* and other macroeconomic factors, but not in return-based factors, such as the Fama-French factors.

5.2. Data and Methodology

Our sample is formed using data from the third quarter of 1963 to the third quarter of 1998. We choose the same time period as Lettau and Ludvigson (2001b), so that our results are directly comparable. As in Lettau and Ludvigson (2001b), the returns data are for the 25 Fama-French (1992, 1993) portfolios. These data are value-weighted returns for the intersections of five size portfolios and five book-to-market equity (BE/ME) portfolios on NYSE, AMEX and NASDAQ stocks in CRSP and COMPUSTAT. We convert the monthly portfolio returns to quarterly data. The Fama-French factors, SMB and HML, are constructed the same way as in Fama and French (1993). R_{vw} is the value-weighted CRSP index return. The conditioning variable, *cay*, is constructed as in Lettau and Ludvigson (2001a,b). We use the measure of labor income growth, Δy , advocated by Jagannathan and Wang (1996). Labor income growth is measured as the growth in total personal, per capita income less dividend payments from the National Income and Product Accounts published by the Bureau of Economic Analysis. Labor income is lagged one month to capture lags in the official reports of aggregate income.

Our methodology can be viewed as a modified version of Fama and MacBeth's (1973) two-pass method. Lettau and Ludvigson (2001b) discuss different methods available, and argue that the Fama-MacBeth procedure has important advantages for their application. In the first-pass, the time-series betas are computed in one multiple regression of the portfolio returns on the factors. In addition to estimating betas by running time-series OLS regressions like in Lettau and Ludvigson (2001b), we also use OLIVE to estimate betas. For a given portfolio (R_i), returns on the other portfolios serve as "instruments" (R_{-i}). As shown by our simulation results, if factors

contain measurement error, betas estimated using OLIVE are much more precise than betas estimated using OLS (and more precise than other IV methods).

In the second-pass, cross-sectional OLS regressions using 25 Fama-French portfolio returns are run on betas estimated using either OLS or OLIVE in the first-pass to draw comparisons:

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_i' \lambda. \quad (22)$$

5.3. Empirical Results

Tables 2 and 3 report the Fama-MacBeth cross-sectional regression (second-pass) coefficients, λ , with two t -statistics in parentheses for each coefficient estimate. The top t -statistic uses uncorrected Fama-MacBeth standard errors, and the bottom t -statistic uses the Shanken (1992) correction. The cross-sectional R^2 is also reported. Table 2 (Table 3) corresponds to Table 1 (Table 3) in Lettau and Ludvigson (2001b), with the same row numbers representing the same models. For each row, the OLS results are replications of Lettau and Ludvigson (2001b). After numerous correspondences with the authors (we are grateful for their timely responses), we are able to obtain very similar results, though not completely identical. The OLIVE results are based on our OLIVE beta estimates in the first-pass. Sections 5.3.1 and 5.3.2 discuss results in Table 2, while section 5.3.3 discusses results in Table 3.

5.3.1. Unconditional Models

Following Lettau and Ludvigson (2001b), we begin by presenting results from three unconditional models.

Row 1 of Table 2 presents results from the static CAPM, with the CRSP value-weighted return, R_{vw} , used as a proxy for the unobservable market return. This model implies the following cross-sectional specification:

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_{vwi} \lambda_{vw} . \quad (23)$$

The OLS results in Row 1 highlight the failure of the static CAPM, as documented by previous studies (see, e.g., Fama and French (1992)). Only 1% of the cross-sectional variation in average returns can be explained by the beta for the market return. The estimated value of λ_{vw} is statistically insignificant and has the wrong sign (negative instead of positive) according the CAPM theory. The constant term, which is an estimate of the zero-beta rate, is too high (4.18% per quarter). Estimating betas using OLIVE instead of OLS provides little improvement in terms of cross-sectional explanatory power: the R^2 is still 1%. However, the sign of the estimated value of λ_{vw} changes from negative to positive, though still statistically insignificant, and the estimated zero-beta rate decreases from 4.18% to 3.48% per quarter. We expect the advantage of OLIVE estimation to be small here, since R_{vw} is a return-based factor likely with little measurement error.

Row 2 of Table 2 presents results for the human capital CAPM, which adds the beta for labor income growth, Δy , into the static CAPM (Jagannathan and Wang (1996)):

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_{vwi} \lambda_{vw} + \beta_{\Delta yi} \lambda_{\Delta y} . \quad (24)$$

The human capital CAPM performs much better than the static CAPM, explaining 58% of the cross-sectional variation in returns. Labor income growth is a macroeconomic factor, which probably contains measurement error. When OLIVE is used to estimate betas, the R^2 jumps from 58% to 78%. However, for both OLS and OLIVE results, the estimated value of λ_{vw} has the wrong sign and the estimated zero-beta rate is too high.

Row 3 of Table 2 presents results for the Fama-French three-factor model:

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_{vwi} \lambda_{vw} + \beta_{SMBi} \lambda_{SMB} + \beta_{HMLi} \lambda_{HML} . \quad (25)$$

This specification performs extremely well with OLS estimated betas: the R^2 becomes 81%; the estimated value of λ_{vw} has the correct positive sign; and the estimated zero-beta rate is reasonable (1.76% per quarter). The Fama-French factors should contain little measurement error, since they

are constructed from stock returns. As one would expect, using OLIVE estimated betas yields almost identical coefficient estimates. The R^2 only marginally improves to 83%.

5.3.2. Conditional/Scaled Factor Models

Row 4 of Table 2 reports results from the scaled, conditional CAPM with one fundamental factor, the market return, and a single scaling variable, \widehat{cay} :

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_{cayi} \lambda_{cay} + \beta_{vwi} \lambda_{vw} + \beta_{vwcayi} \lambda_{vwcay}. \quad (26)$$

Under this specification, using OLIVE instead of OLS to estimate betas dramatically improves the cross-sectional explanatory power from 31% to 80%, which is similar to the performance of the Fama-French three-factor model. This is consistent with our conjecture that since \widehat{cay} is constructed using macroeconomic data, it contains large measurement error. Using OLIVE also changes the sign of the estimated value of λ_{vw} from negative to positive, though the estimated coefficients are close to zero for both OLS and OLIVE. Using OLIVE also reduces the estimated zero-beta rate from 3.69% to 3.09% per quarter, though they are still too high.

Rows 5 and 5' are variations of Row 4. Given the finding that the estimated value of λ_{cay} is not statistically different from zero in Row 4, Row 5 omits β_{cayi} as an explanatory variable in the second-pass cross-sectional regressions, but still includes \widehat{cay} in the first-pass time-series regressions. Row 5' further excludes \widehat{cay} in the first-pass time-series regressions (results from this specification are not reported in Lettau and Ludvigson (2001b)). Results in Rows 5 and 5' are very similar to those in Row 4, suggesting that the time-varying component of the intercept is not an important determinant of cross-sectional returns. The impact of using OLIVE to estimate betas is also very similar: the cross-sectional R^2 jumps from about 30% to about 80%.

Row 6 of Table 2 reports results from the scaled, conditional version of the human capital CAPM:

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_{cayt} \lambda_{cay} + \beta_{vwt} \lambda_{vw} + \beta_{\Delta yt} \lambda_{\Delta y} + \beta_{vw c ay t} \lambda_{vw c ay} + \beta_{\Delta y c ay t} \lambda_{\Delta y c ay}. \quad (27)$$

We focus our discussions on this “complete” specification. Using OLIVE instead of OLS in the first-pass to estimate betas improves the second-pass cross-sectional R^2 from 77% to 83% (similar to the performance of the Fama-French three-factor model).

More importantly, our results here help to resolve two puzzling findings by Lettau and Ludvigson (2001b) and Jagannathan and Wang (1996). The second-pass risk premia and zero-beta rate estimates will be inconsistent if factors are measured with error and OLS is used to estimate betas in the first-pass. On the other hand, the risk premia and zero-beta rate can be consistently estimated in the second-pass if OLIVE is used in the first-pass to estimate betas, because OLIVE beta estimates are consistent even when factors contain measurement error.

Lettau and Ludvigson (2001b) use OLS to estimate betas and find that two features of their cross-sectional results in their Table 1 bear noting.³ First, they state that “[a] problem with this model, however, is that there is a negative average risk price on the beta for the value-weighted return.” They also note that “Jagannathan and Wang (1996) report a similar finding for the signs of the risk prices on the market and human capital betas.” Indeed, in our OLS results in Row 6 of Table 2, the estimated value of λ_{vw} (coefficient on the market return beta) is -2.00, and the estimated value of $\lambda_{\Delta y c ay}$ (coefficient on the scaled human capital beta) is -0.17, both negative which is inconsistent with the theory. However, when we use OLIVE to estimate betas in the first-pass, the estimated value of λ_{vw} becomes positive (1.33), and the estimated value of $\lambda_{\Delta y c ay}$ becomes close to zero (-0.0005), more consistent with the theory.

Second, Lettau and Ludvigson (2001b) state that “the estimated value of the average zero-beta rate is large.” “The average zero-beta rate should be between the average ‘riskless’ borrowing and lending rates, and the estimated value is implausibly high for the average investor. Although the (C)CAPM can explain a substantial fraction of the cross-sectional variation in these

³ See pages 1259-1260 of Lettau and Ludvigson (2001b).

25 portfolio returns, this result suggests that the scaled models do a poor job of simultaneously pricing the hypothetical zero-beta portfolio. This finding is not uncommon in studies that use macro variables as factors. For example, the estimated values for the zero-beta rate we find here have the same order of magnitude as that found in Jagannathan and Wang (1996).” The authors note that “[i]t is possible that the greater sampling error we find in the estimated betas of the scaled models with macro factors is contributing to an upward bias in the zero-beta estimates of those models relative to the estimates for models with only financial factors.” They also note that “[s]uch arguments for large zero-beta estimates have a long tradition in the cross-sectional asset pricing literature (e.g., Black et al. 1972; Miller and Scholes 1972).” However, the authors conclude that “[p]rocedures for discriminating the sampling error explanation for these large estimates of the zero-beta rate from others are not obvious, and its development is left to future research.” Our results suggest that measurement error in factors is the cause of this problem. Sampling error is a second-order issue; it becomes negligible as the sample size T becomes large. Unlike sampling error, the measurement error problem does not diminish as the sample size T becomes large. When macroeconomic factors with measurement error are included in the model, OLIVE can provide more precise beta estimates in the first-pass, which lead to more precise estimates of the zero-beta rate in the second-pass. In Row 6 of Table 2, the estimated zero-beta rate based on OLS estimated betas is too high at 5.19% per quarter. However, when we use OLIVE to estimate betas, the estimated zero-beta rate drops dramatically to a reasonable 1.91% per quarter.

Rows 7 and 7' are variations of Row 6. Row 7 omits β_{cayt} as an explanatory variable in the second-pass cross-sectional regressions, but still includes \widehat{cay} in the first-pass time-series regressions. Row 7' further excludes \widehat{cay} in the first-pass time-series regressions (results from this specification are not reported in Lettau and Ludvigson (2001b)). Results in Rows 7 and 7' are very similar to those in Row 6. The impact of using OLIVE instead of OLS to estimate betas

is also very similar: the cross-sectional R^2 increases; the sign of the estimated value of λ_{vw} changes from negative to positive; and the estimated zero-beta rate drops significantly to a reasonable magnitude.

To summarize, our results in Table 2 confirm the existence of large measurement error in macroeconomic factors, such as \widehat{cay} and labor income growth, and validate the use of OLIVE to help improve beta estimation under these circumstances. In addition, to the extent that our empirical results help resolve some puzzling findings in Lettau and Ludvigson (2001b) and Jagannathan and Wang (1996), we also strengthen their results.

5.3.3. Consumption CAPM

Table 3 presents, for the consumption CAPM, the same results presented in Table 2 for the static CAPM and the human capital CAPM. The scaled multifactor consumption CAPM, with \widehat{cay} as the single conditioning variable takes the form:

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_{cayi} \lambda_{cay} + \beta_{\Delta ci} \lambda_{\Delta c} + \beta_{\Delta ccayi} \lambda_{\Delta ccay}, \quad (28)$$

where Δc denotes consumption growth (log difference in consumption), as measured in Lettau and Ludvigson (2001a).

As a comparison, Row 1 of Table 3 reports results of the unconditional consumption CAPM. The performance of this specification is poor, explaining only 16% of the cross-sectional variation in portfolio returns. Using OLIVE beta estimates seems to have made the performance even worse.

Row 2 of Table 3 presents the results of estimating the scaled specification in equation (28). The R^2 jumps to 70%, in sharp contrast to the unconditional results in Row 1. When OLIVE is used to estimate betas, the R^2 further increases to 82%. For both OLS and OLIVE results, the estimated value of $\lambda_{\Delta ccay}$ (scaled consumption growth) is positive and statistically significant.

Row 3 excludes β_{cay_i} as an explanatory variable in the second-pass cross-sectional regressions, but still includes \widehat{cay} in the first-pass time-series regressions. This seems to have made very little difference, as the results in Row 3 are very similar to those in Row 2. Again, when OLIVE estimated betas are used, the R^2 increases from 69% to 81%.

Row 3' further excludes \widehat{cay} in the first-pass time-series regressions. As noted by Lettau and Ludvigson (2001b), the results here are somewhat sensitive to this exclusion.⁴ The R^2 drops to 27% for OLS results and 34% for OLIVE results. These results suggest that including the scaling variable \widehat{cay} as a factor in the pricing kernel can be important even when the beta for this factor is not priced in the cross-section.

Our results in Table 3 suggest that using OLIVE instead of OLS to estimate betas in the conditional consumption CAPM generally increases the cross-sectional variation of portfolio returns explained by the model, as measured by the R^2 . However, unlike in Table 2, the estimated zero-beta rates remain high.

6. Conclusion

In this paper, we put forth a simple method for estimating betas (factor loadings) when factors are measured with error, which we call OLIVE. OLIVE uses all available instruments at hand, and is intuitive and easy to implement. OLIVE achieves better performance in simulations than OLS and other instrumental variable estimators such as 2SLS, B2SLS, LIML, and FULLER, when the number of instruments is large. OLIVE can be interpreted as a GMM estimator when setting the weighting matrix equal to the identity matrix and it has better finite sample properties than the efficient two-step GMM estimator. OLIVE also has an important advantage over the Asymptotic Principle Components (APC) because the statistical factors of the principle

⁴ Results from this specification are not reported in Lettau and Ludvigson (2001b). See footnote 25 on page 1261 of their paper.

components method lack clear economic interpretations, while OLIVE directly makes use of the observed economic factors.

OLIVE has many potential applications. For example, it can be used in cross-country studies, where data from other countries can be used as instruments for the country in question. OLIVE is especially suitable for estimating asset return betas when factors are measured with error, since this is often a large N and small T setting. Intuitively, since all asset returns vary together with a common set of factors, one can use information contained in other asset returns to improve the beta estimate for a given asset.

As an empirical application, we reexamine Lettau and Ludvigson's (2001b) test of the (C)CAPM using OLIVE in addition to OLS to estimate betas. Lettau and Ludvigson's factor *cay* has been found to have strong forecasting power for excess returns on aggregate stock market indices, but may contain measurement error. We find that in regressions where macroeconomic factors are included, using OLIVE instead of OLS improves the R^2 significantly. Perhaps more importantly, our results from OLIVE estimation help to resolve two puzzling findings by Lettau and Ludvigson (2001b) and Jagannathan and Wang (1996): first, the sign of the average risk premium on the beta for the market return changes from negative to positive, which is in accordance with the theory; second, the estimated value of average zero-beta rate is no longer too high. These results suggest that when macroeconomic factors with measurement error are included in the model, OLIVE can provide more precise beta estimates in the first-pass, which lead to more precise estimates of the risk premia and zero-beta rate in the second-pass.

Overall, our results from this empirical application validate the use of OLIVE to help improve beta estimation when factors are measured with error. Our empirical results support and strengthen Lettau and Ludvigson (2001b) and Jagannathan and Wang (1996) by resolving some of their puzzling findings. Our findings are also consistent with the theme in Ferson, Sarkissian, and Simin (2007) that the (C)CAPMs might work better than previously recognized in the literature.

Appendices

Appendix A. Proof of Proposition 1 (see Section 2.2).

To simplify notation, we consider a more abstract setting. Let

$$y_t = \beta' x_t + \varepsilon_t = x_t' \beta + \varepsilon_t, \quad (\text{A1})$$

where x_t and β are $M \times 1$ vectors, $E(x_t \varepsilon_t) \neq 0$, and $x_t = x_t^* + v_t$. Let $z_{it} = \beta_i' x_t^* + e_{it}$ be instruments ($i = 1, \dots, N; t = 1, \dots, T$). Here we assume there are N instruments (i.e., $N+1$ assets).

For example, to estimate B_1 in the notation of Section 2, we let $\beta = B_1$, and $y_t = y_{1t}$, $\varepsilon_t = e_{1t}$,

and $z_{it} = y_{i+1,t}$ for $i \geq 1$. Then

$$\frac{1}{T} \sum_{t=1}^T z_{it} y_t = \frac{1}{T} \sum_{t=1}^T z_{it} x_t' \beta + \frac{1}{T} \sum_{t=1}^T z_{it} \varepsilon_t, \quad (\text{A2})$$

or it can be simplified as

$$\bar{y}_i = \bar{x}_i' \beta + \bar{\varepsilon}_i, \quad (\text{A3})$$

where $\bar{x}_i = \frac{1}{T} \sum_{t=1}^T x_t z_{it}'$, $\bar{\varepsilon}_i = \frac{1}{T} \sum_{t=1}^T z_{it} \varepsilon_t$, and $\bar{y}_i = \frac{1}{T} \sum_{t=1}^T z_{it} y_t$. The estimator OLIVE is

$$\hat{\beta}^{OLIVE} = (\bar{x}' \bar{x})^{-1} \bar{x}' \bar{y}. \text{ Now}$$

$$\begin{aligned} E(\bar{x}_i \bar{\varepsilon}_i) &= E\left(\frac{1}{T^2} \sum_{t=1}^T z_{it} x_t' \sum_{s=1}^T z_{is} \varepsilon_s\right) \\ &= \frac{1}{T} E\left(\frac{1}{T} \sum_{t=1}^T z_{it} x_t' z_{it} \varepsilon_t\right) + \frac{1}{T} \left[\frac{1}{T}\right] \sum_{t=1}^T \sum_{s=1, s \neq t}^T E(z_{it} x_t' z_{is} \varepsilon_s). \end{aligned} \quad (\text{A4})$$

$$= O\left(\frac{1}{T}\right) \rightarrow 0 \quad \text{as } t \rightarrow \infty$$

Therefore,

$$\begin{aligned} \hat{\beta}^{OLIVE} - \beta &= \left(\sum_{i=1}^N \bar{x}_i \bar{x}_i'\right)^{-1} \sum_{i=1}^N \bar{x}_i \bar{\varepsilon}_i \\ &= \left(\frac{1}{N} \sum_{i=1}^N \bar{x}_i \bar{x}_i'\right)^{-1} \left(\frac{1}{N} \sum_{i=1}^N \bar{x}_i \bar{\varepsilon}_i\right) \end{aligned} \quad (\text{A5})$$

$$\begin{aligned}
\sqrt{T}(\widehat{\beta}^{OLIVE} - \beta) &= \left(\frac{1}{N} \sum_{i=1}^N \overline{\overline{x_i x_i'}} \right)^{-1} \left(\frac{1}{N} \sum_{i=1}^N \sqrt{T} \overline{\overline{x_i \varepsilon_i}} \right) \\
&= \left(\frac{1}{N} \sum_{i=1}^N \overline{\overline{x_i x_i'}} \right)^{-1} \frac{1}{N} \sum_{i=1}^N \left[\left(\frac{1}{T} \sum_{t=1}^T x_t z_{it}' \right) \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T z_{it} \varepsilon_t \right) \right], \\
&= A_N^{-1} \frac{1}{N} \sum_{i=1}^N D_{iT} \xi_{iT}
\end{aligned} \tag{A6}$$

where $A_N = \frac{1}{N} \sum_{i=1}^N \overline{\overline{x_i x_i'}}$, $D_{iT} = \frac{1}{T} \sum_{t=1}^T x_t z_{it}'$, and $\xi_{iT} = \frac{1}{\sqrt{T}} \sum_{t=1}^T z_{it} \varepsilon_t$. Note that ξ_{iT} and ξ_{jT} are

dependent through the common term $\sum_{t=1}^T x_t^* \varepsilon_t$, see (A8) below. The instruments z_{it} are

determined by true factor x_t^* :

$$z_{it} = \beta_i' x_t^* + e_{it}, \tag{A7}$$

therefore,

$$\xi_{iT} = \frac{1}{\sqrt{T}} \sum_{t=1}^T \beta_i' x_t^* \varepsilon_t + \frac{1}{\sqrt{T}} \sum_{t=1}^T e_{it} \varepsilon_t, \tag{A8}$$

and

$$D_{iT} \xi_{iT} = D_{iT} \beta_i' \frac{1}{\sqrt{T}} \sum_{t=1}^T x_t^* \varepsilon_t + D_{iT} \frac{1}{\sqrt{T}} \sum_{t=1}^T e_{it} \varepsilon_t. \tag{A9}$$

$$\frac{1}{N} \sum_{i=1}^N D_{iT} \xi_{iT} = \left[\frac{1}{N} \sum_{i=1}^N D_{iT} \beta_i' \right] \left[\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t^* \varepsilon_t \right] + \frac{1}{N} \sum_{i=1}^N \left[D_{iT} \frac{1}{\sqrt{T}} \sum_{t=1}^T e_{it} \varepsilon_t \right]. \tag{A10}$$

We have

$$\left[\frac{1}{N} \sum_{i=1}^N D_{iT} \beta_i' \right] \left[\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t^* \varepsilon_t \right] \rightarrow \Gamma N(0, \Omega), \tag{A11}$$

where $\left[\frac{1}{N} \sum_{i=1}^N D_{iT} \beta_i' \right] \rightarrow \Gamma$, and $\left[\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t^* \varepsilon_t \right] \rightarrow N(0, \Omega)$. We also have

$$\frac{1}{N} \sum_{i=1}^N \left[D_{iT} \frac{1}{\sqrt{T}} \sum_{t=1}^T e_{it} \varepsilon_t \right] = O_p(N^{-1/2}) \rightarrow 0. \tag{A12}$$

To see (A12) is $O_p(N^{-1/2})$, we write

$$D_{iT} = \frac{1}{T} \sum_{t=1}^T x_t z_{it}' = \frac{1}{T} \sum_{t=1}^T (x_t^* + v_t)(x_t^* \beta_i + e_{it}) = \frac{1}{T} \sum_{t=1}^T x_t^* x_t^* \beta_i + O_p(T^{-1/2}),$$

and $E(D_{it}) = G\beta_i$, where $G = E\left(\frac{1}{T} \sum_{t=1}^T x_t^* x_t^*\right)$. Adding and subtracting $E(D_{iT})$, then

equation (A12) can be rewritten as

$$\frac{1}{N} \sum_{i=1}^N [D_{iT} - E(D_{iT})] \frac{1}{\sqrt{T}} \sum_{t=1}^T e_{it} \varepsilon_t + GN^{-1/2} \frac{1}{\sqrt{NT}} \sum_{i=1}^N \sum_{t=1}^T \beta_i e_{it} \varepsilon_t = I + II. \quad (\text{A13})$$

Since $D_{iT} - E(D_{iT}) = O_p(T^{-1/2})$, term I is dominated by II . From

$$\frac{1}{\sqrt{NT}} \sum_{i=1}^N \sum_{t=1}^T \beta_i e_{it} \varepsilon_t = O_p(1), \quad (\text{A14})$$

we have $II = O_p(N^{-1/2})$.

If N is fixed, (A12) is $O_p(1)$ and is not negligible. This term will contribute to the limiting distribution; but the \sqrt{T} consistency and the asymptotic normality still hold.

Appendix B. Proof of Proposition 2 (see Section 2.2).

The proof of Proposition 1 remains valid up to (A11). We show (A12) is still asymptotically negligible if $\sqrt{T}/N \rightarrow 0$. It is sufficient to consider II in (A13). Let $\gamma_i = E(e_{it} \varepsilon_t)$, with $\gamma_i \neq 0$, equation (A14) will no longer hold. But it can be rewritten as

$$\frac{1}{\sqrt{NT}} \sum_{i=1}^N \sum_{t=1}^T \beta_i e_{it} \varepsilon_t = \frac{1}{\sqrt{NT}} \sum_{i=1}^N \sum_{t=1}^T \beta_i [e_{it} \varepsilon_t - E(e_{it} \varepsilon_t)] + \frac{1}{\sqrt{NT}} \sum_{i=1}^N \sum_{t=1}^T \beta_i \gamma_i. \quad (\text{A15})$$

The first term on the right hand side is $O_p(1)$. Assuming $\|\beta_i\| \leq M$ for all i , the second term is bounded by $M(\sqrt{T/N}) \sum_{i=1}^N |\gamma_i| = O(\sqrt{T/N})$ because $\sum_{i=1}^N |\gamma_i| = O(1)$ by assumption (9). Thus (A15) is $O_p(1) + O_p(\sqrt{T/N})$. This implies that, noting the extra term $N^{-1/2}$, II in (A13) is equal to $O_p(N^{-1/2}) + O_p(\sqrt{T}/N)$, which converges to zero if $\sqrt{T}/N \rightarrow 0$.

Appendix C. Derivations for Joint GMM (see Section 3.2).

We derive the formulae for w_{jk}^{ih} , the (j, k) th element of the block off-diagonal matrix

W_{ih} , in each of the following four possible cases.

Case 1: $j \neq h$ and $k \neq i$.

$$\begin{aligned}
w_{jk}^{ih} &= E(u_{ijt}u_{hkt}) = E\left[y_{jt}(e_{it} - v_t' B_i)(e_{ht} - B_h' v_t)y_{kt}\right] \\
&= E\left[y_{jt}(B_i' \text{var}(v_t) B_h) y_{kt}\right] \\
&= E\left[(B_j' x_t^* + e_{jt})(x_t^* B_k + e_{kt})(B_i' \text{var}(v_t) B_h)\right] \\
&= E\left[(B_j' \text{var}(x_t^*) B_k + \delta_{jk} \text{var}(e_{jt}))(B_i' \text{var}(v_t) B_h)\right] \\
&= (B_j' \text{var}(x_t^*) B_k + \delta_{jk} \text{var}(e_{jt}))(B_i' \text{var}(v_t) B_h)
\end{aligned} \tag{A16}$$

where $\delta_{jk} = 1$ if $j = k$, and zero otherwise.

Case 2: $j = h$ and $k \neq i$.

$$\begin{aligned}
w_{jk}^{ih} &= E(u_{ijt}u_{hkt}) = E\left[y_{ht}(e_{it} - v_t' B_i)(e_{ht} - B_h' v_t)y_{kt}\right] \\
&= E\left[(B_h' x_t^* + e_{ht})(e_{ht} - B_h' v_t)(e_{it} - v_t' B_i)(x_t^* B_k + e_{kt})\right] \\
&= E\left[(B_h' x_t^* e_{ht} - B_h' x_t^* v_t' B_h + e_{ht}^2 - B_h' v_t e_{ht})(B_k' x_t^* e_{it} - B_k' x_t^* v_t' B_i + e_{it} e_{kt} - B_i' v_t e_{kt})\right] \\
&= E\left[\begin{aligned}
&B_h' x_t^* x_t^* B_k \bullet e_{ht} e_{it} - B_h' x_t^* x_t^* B_k \bullet B_i' v_t \bullet e_{ht} + B_h' x_t^* e_{ht} e_{it} e_{kt} - B_h' x_t^* v_t' B_i e_{ht} e_{kt} \\
&- B_h' x_t^* x_t^* B_k \bullet B_h' v_t e_{it} + B_h' x_t^* x_t^* B_k \bullet B_h' v_t v_t' B_i - B_h' x_t^* v_t' B_h \bullet e_{it} e_{kt} + B_h' v_t v_t' B_i \bullet B_h' x_t^* e_{kt} \\
&+ B_k' x_t^* \bullet e_{it} e_{ht}^2 - B_k' x_t^* v_t' B_i \bullet e_{ht}^2 + e_{it} e_{kt} e_{ht}^2 - B_i' v_t e_{kt} e_{ht}^2 \\
&- B_k' x_t^* v_t' B_h \bullet e_{ht} e_{it} + B_h' v_t v_t' B_i \bullet B_k' x_t^* \bullet e_{ht} - B_h' v_t e_{ht} e_{it} e_{kt} + B_h' v_t v_t' B_i \bullet e_{ht} e_{kt}
\end{aligned}\right] \\
&= E\left[B_h' x_t^* x_t^* B_k \bullet B_h' v_t v_t' B_i\right] \\
&= B_h' \text{var}(x_t^*) B_k \bullet B_h' \text{var}(v_t) B_i
\end{aligned} \tag{A17}$$

Case 3, $j \neq h$ and $k = i$. This is the mirror case of Case 2. In short, the formula is:

$$\begin{aligned}
w_{jk}^{ih} &= E(u_{ijt}u_{hkt}) = E\left[y_{jt}(e_{it} - v_t' B_i)(e_{ht} - B_h' v_t)y_{it}\right] \\
&= B_i' \text{var}(x_t^*) B_j \bullet B_h' \text{var}(v_t) B_i
\end{aligned} \tag{A18}$$

Case 4: $j = h$ and $k = i$.

$$\begin{aligned}
w_{jk}^{jh} &= E(u_{ijt}u_{hkt}) = E[y_{ht}(e_{it} - v_t' B_i)(e_{ht} - B_h' v_t)y_{it}] \\
&= E\left[(B_h' x_t^* + e_{ht})(e_{it} - v_t' B_i)(e_{ht} - B_h' v_t)(x_t^* B_i + e_{it})\right] \\
&= E\left[(B_h' x_t^* e_{it} - B_h' x_t^* v_t' B_i + e_{ht} e_{it} - B_i' v_t e_{ht})(B_i' x_t^* e_{ht} + e_{ht} e_{it} - B_h' v_t x_t^* B_i - B_h' v_t e_{it})\right] \\
&= E\left[\begin{aligned} &B_h' x_t^* x_t^* B_i \bullet e_{ht} e_{it} + B_h' x_t^* \bullet e_{ht} e_{it}^2 - B_h' x_t^* x_t^* B_i \bullet B_h' v_t \bullet e_{it} - B_h' x_t^* v_t' B_h \bullet e_{it}^2 \\ &- B_h' x_t^* x_t^* B_i \bullet B_i' v_t \bullet e_{ht} - B_h' x_t^* v_t' B_i \bullet e_{ht} e_{it} + B_h' x_t^* x_t^* B_i \bullet B_h' v_t v_t' B_i + B_h' v_t v_t' B_i \bullet B_h' x_t^* \bullet e_{it} \\ &+ B_i x_t^* \bullet e_{ht}^2 e_{it} + e_{ht}^2 e_{it}^2 - B_h' v_t x_t^* B_i \bullet e_{ht} e_{it} - B_h' v_t \bullet e_{ht} e_{it}^2 \\ &- B_i' v_t x_t^* B_i \bullet e_{ht}^2 - B_i' v_t \bullet e_{ht}^2 e_{it} + B_h' v_t v_t' B_i \bullet B_i' x_t^* \bullet e_{ht} + B_h' v_t v_t' B_i \bullet e_{ht} e_{it} \end{aligned} \right] \\
&= E\left[B_h' x_t^* x_t^* B_i \bullet B_h' v_t v_t' B_i + e_{ht}^2 e_{it}^2\right] \\
&= B_h' \text{var}(x_t^*) B_i \bullet B_h' \text{var}(v_t) B_i + \text{var}(e_{it})^2
\end{aligned} \tag{A19}$$

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Table 1. Simulation Results

This table presents the simulation results. We compare OLIVE with other IV estimators including 2SLS, LIML, B2SLS, FULLER1 and FULLER4 (the choice of the α parameter is either 1 or 4), as well as the two-step equation-by-equation GMM estimator (2GMM). The formulae of the above estimators are as follows:

$$\begin{aligned}\widehat{\beta}_{OLS} &= (X'X)^{-1}X'Y \\ \widehat{\beta}_{2SLS} &= (X'PX)^{-1}X'PY \\ \widehat{\beta}_{LIML} &= (X'(P-\widehat{\lambda}M)X)^{-1}X'(P-\widehat{\lambda}M)Y \\ \widehat{\beta}_{B2SLS} &= (X'(P-\bar{\lambda}M)X)^{-1}X'(P-\bar{\lambda}M)Y \\ \widehat{\beta}_{FULLER} &= (X'(P-\tilde{\lambda}M)X)^{-1}X'(P-\tilde{\lambda}M)Y \\ \widehat{\beta}_{OLIVE} &= (X'ZZ'X)^{-1}X'ZZ'Y \\ \widehat{\beta}_{2GMM} &= (X'Z\widehat{W}^{-1}Z'X)^{-1}X'Z\widehat{W}^{-1}Z'Y\end{aligned}$$

We first generate a security with a true beta of one, which is to be estimated using the above estimators. Then we generate $K = N-1$ other securities which serve as instruments using the following data generating process (DGP):

$$\begin{aligned}x_t &= x_t^* + v_t, t = 1, \dots, T \\ y_{it} &= \beta_i' x_t^* + e_{it} = \beta_i' x_t + (-\beta_i' v_t + e_{it}) = \beta_i' x_t + \varepsilon_{it}, i = 1, \dots, N \\ x_t^* &\sim MVN(\pi, \sigma_x^2 I^J) \\ v_t &\sim MVN(0^J, \sigma_v^2 I^J) \\ \beta_i &\sim MVN(\mu_i, \sigma_\beta^2 I^J) \\ e_t &\sim MVN(0^N, \sigma_e^2 I^N) \\ y_{-i,t} &= (y_{1t}, y_{2t}, \dots, y_{i-1,t}, y_{i+1,t}, \dots, y_{Nt})\end{aligned}$$

We use $K = (1, 2, 3, 5, 10, 30, 45, 55, 90, 150, 300, 600)$, $T = 60$, $\pi = 0.1$, $\sigma_x = 0.1$, $\sigma_\beta = 1$, and 1,000 replications. Without loss of generality, we set J , the number of explanatory variables to be 1, which makes the model specification equivalent to the CAPM for the excess return. We allow x and β to be normally generated. One advantage of OLIVE is that when K is larger than T , it still works while most other IV estimators no longer do. This is why we can only compare the performance of OLS, OLIVE, and 2GMM for $K = (90, 150, 300, 600)$. We set $\sigma_v = 0.1$ and $\sigma_e = 0.1$ (medium measurement error and medium instruments). The statistics reported include median bias (Med. Bias), mean bias (Mean Bias), median absolute deviation (Med. AD), mean absolute deviation (Mean AD), squared-root of mean squared error (SQRT. MSE), inter-quartile range (IQR), the difference between the 0.1 and 0.9 deciles (Dec. Rge), and the coverage rate of a nominal 95% confidence interval (Cov. Rate).

Table 1 Continued

K	Estimator	Med. Bias	Mean Bias	Med. AD	Mean AD	SQRT. MSE	IQR	Dec. Rge	Cov. Rate
1	OLS	-0.3306	-0.3328	0.3306	0.3328	0.3458	0.1207	0.2445	1.0000
	2SLS	0.0011	-0.1366	0.1259	0.3926	3.6599	0.2542	0.5502	0.9860
	LIML	0.0011	-0.1366	0.1259	0.3926	3.6599	0.2542	0.5502	0.9860
	B2SLS	-0.0207	-0.0208	0.1209	0.1583	0.2179	0.2349	0.4850	1.0000
	FULLER1	-0.0226	-0.0216	0.1202	0.1578	0.2168	0.2356	0.4847	1.0000
	FULLER4	-0.0725	-0.0729	0.1178	0.1437	0.1852	0.2085	0.4178	1.0000
	OLIVE	0.0011	-0.1366	0.1259	0.3926	3.6599	0.2542	0.5502	0.9860
	2GMM	0.0011	-0.1366	0.1259	0.3926	3.6599	0.2542	0.5502	0.9860
2	OLS	-0.3313	-0.3300	0.3313	0.3300	0.3440	0.1251	0.2499	1.0000
	2SLS	-0.0068	0.0028	0.1007	0.1236	0.1625	0.1999	0.3831	1.0000
	LIML	0.0052	0.0104	0.1016	0.1378	0.2607	0.1997	0.3865	0.9980
	B2SLS	-0.0068	0.0028	0.1007	0.1236	0.1625	0.1999	0.3831	1.0000
	FULLER1	-0.0078	0.0009	0.0979	0.1227	0.1620	0.1962	0.3769	1.0000
	FULLER4	-0.0398	-0.0336	0.0969	0.1159	0.1473	0.1823	0.3444	1.0000
	OLIVE	0.0010	0.0111	0.1019	0.1249	0.1641	0.2024	0.3854	1.0000
	2GMM	-0.0033	0.0025	0.1036	0.1239	0.1615	0.2038	0.3780	1.0000
3	OLS	-0.3324	-0.3362	0.3324	0.3362	0.3492	0.1298	0.2468	1.0000
	2SLS	-0.0275	-0.0191	0.0979	0.1141	0.1431	0.1874	0.3467	1.0000
	LIML	-0.0065	0.0041	0.0965	0.1179	0.1520	0.1925	0.3624	1.0000
	B2SLS	-0.0174	-0.0090	0.0982	0.1159	0.1461	0.1898	0.3508	1.0000
	FULLER1	-0.0185	-0.0070	0.0967	0.1152	0.1469	0.1892	0.3551	1.0000
	FULLER4	-0.0429	-0.0376	0.0958	0.1120	0.1397	0.1771	0.3348	1.0000
	OLIVE	-0.0131	-0.0012	0.0947	0.1155	0.1467	0.1850	0.3598	1.0000
	2GMM	-0.0290	-0.0207	0.1008	0.1206	0.1599	0.1868	0.3661	1.0000
5	OLS	-0.3351	-0.3342	0.3351	0.3342	0.3490	0.1380	0.2620	1.0000
	2SLS	-0.0380	-0.0308	0.0982	0.1117	0.1377	0.1812	0.3549	1.0000
	LIML	0.0014	0.0070	0.0949	0.1146	0.1434	0.1900	0.3725	1.0000
	B2SLS	-0.0132	-0.0040	0.0957	0.1151	0.1428	0.1887	0.3714	1.0000
	FULLER1	-0.0068	-0.0027	0.0961	0.1123	0.1400	0.1875	0.3687	1.0000
	FULLER4	-0.0326	-0.0304	0.0977	0.1089	0.1352	0.1785	0.3439	1.0000
	OLIVE	0.0001	0.0041	0.0949	0.1123	0.1403	0.1882	0.3657	1.0000
	2GMM	-0.0280	0.0513	0.1016	0.2474	2.9960	0.1932	0.3790	0.9930
10	OLS	-0.3315	-0.3305	0.3315	0.3305	0.3444	0.1306	0.2416	1.0000
	2SLS	-0.0734	-0.0657	0.1060	0.1161	0.1425	0.1641	0.3097	1.0000
	LIML	-0.0059	0.0092	0.0914	0.1117	0.1442	0.1820	0.3503	1.0000
	B2SLS	-0.0134	-0.0008	0.0931	0.1137	0.1466	0.1836	0.3550	1.0000
	FULLER1	-0.0137	0.0000	0.0922	0.1100	0.1408	0.1773	0.3427	1.0000
	FULLER4	-0.0371	-0.0265	0.0938	0.1076	0.1354	0.1693	0.3175	1.0000
	OLIVE	-0.0070	0.0055	0.0908	0.1073	0.1385	0.1818	0.3369	1.0000
	2GMM	-0.0510	-0.0050	0.1081	0.2826	2.1224	0.1822	0.3814	0.9900

Table 1 Continued

K	Estimator	Med. Bias	Mean Bias	Med. AD	Mean AD	SQRT. MSE	IQR	Dec. Rge	Cov. Rate
30	OLS	-0.3321	-0.3309	0.3321	0.3310	0.3454	0.1300	0.2421	1.0000
	2SLS	-0.1950	-0.1938	0.1950	0.1981	0.2227	0.1465	0.2782	1.0000
	LIML	0.0011	0.0119	0.1024	0.1228	0.1579	0.2037	0.3858	1.0000
	B2SLS	-0.0247	-0.0056	0.1187	0.1383	0.1806	0.2231	0.4379	1.0000
	FULLER1	-0.0085	0.0026	0.0989	0.1204	0.1533	0.1988	0.3740	1.0000
	FULLER4	-0.0330	-0.0242	0.0974	0.1161	0.1448	0.1884	0.3587	1.0000
	OLIVE	-0.0032	0.0063	0.0878	0.1053	0.1352	0.1753	0.3311	1.0000
	2GMM	-0.1264	-0.1534	0.1511	0.2372	0.6191	0.2030	0.4255	0.9930
45	OLS	-0.3304	-0.3300	0.3304	0.3300	0.3432	0.1271	0.2384	1.0000
	2SLS	-0.2670	-0.2672	0.2670	0.2676	0.2851	0.1318	0.2497	1.0000
	LIML	0.0085	0.0297	0.1154	0.1530	0.2170	0.2414	0.4661	0.9990
	B2SLS	-0.0562	-0.0114	0.1541	0.1829	0.2529	0.2657	0.5385	0.9990
	FULLER1	-0.0015	0.0186	0.1150	0.1479	0.2044	0.2337	0.4514	1.0000
	FULLER4	-0.0251	-0.0121	0.1095	0.1372	0.1804	0.2132	0.4182	1.0000
	OLIVE	0.0000	0.0061	0.0881	0.1036	0.1325	0.1760	0.3320	1.0000
	2GMM	-0.1875	-0.4270	0.2044	0.5082	3.9644	0.2098	0.4392	0.9880
55	OLS	-0.3284	-0.3293	0.3284	0.3293	0.3436	0.1306	0.2485	1.0000
	2SLS	-0.3086	-0.3090	0.3086	0.3090	0.3245	0.1303	0.2477	1.0000
	LIML	-0.0125	0.0966	0.1861	0.3765	1.9318	0.3709	0.7357	0.9840
	B2SLS	-0.1312	-0.0579	0.2045	0.2451	0.3755	0.3168	0.6430	0.9970
	FULLER1	-0.0219	0.0191	0.1762	0.2757	0.4718	0.3566	0.7090	0.9910
	FULLER4	-0.0487	-0.0234	0.1666	0.2378	0.3628	0.3286	0.6486	0.9970
	OLIVE	-0.0018	0.0093	0.0936	0.1077	0.1369	0.1903	0.3313	1.0000
	2GMM	-0.1972	-0.2130	0.2131	0.3508	1.0007	0.2210	0.4763	0.9800
90	OLS	-0.3358	-0.3323	0.3358	0.3325	0.3469	0.1341	0.2517	1.0000
	OLIVE	0.0042	0.0080	0.0878	0.1071	0.1359	0.1782	0.3358	1.0000
	2GMM	-0.2839	-0.2151	0.3095	0.5725	2.6967	0.2594	0.6174	0.9710
150	OLS	-0.3341	-0.3317	0.3341	0.3317	0.3453	0.1330	0.2443	1.0000
	OLIVE	-0.0075	0.0040	0.0888	0.1032	0.1315	0.1773	0.3239	1.0000
	2GMM	-0.3895	-0.3492	0.4080	0.5876	1.3594	0.2679	0.6326	0.9760
300	OLS	-0.3342	-0.3364	0.3342	0.3364	0.3486	0.1213	0.2345	1.0000
	OLIVE	0.0021	0.0091	0.0937	0.1099	0.1374	0.1884	0.3475	1.0000
	2GMM	-0.5885	-0.5772	0.5995	0.7787	1.7457	0.2931	0.7556	0.9590
600	OLS	-0.3344	-0.3336	0.3344	0.3336	0.3469	0.1268	0.2483	1.0000
	OLIVE	0.0013	0.0099	0.0888	0.1055	0.1318	0.1806	0.3353	1.0000
	2GMM	-0.7352	-0.9429	0.7509	1.1228	5.4738	0.3163	0.8479	0.9570

**Table 2. Fama-MacBeth Regressions Using 25 Fama-French Portfolios:
 λ_j Coefficient Estimates on Betas in Cross-Sectional Regression**

This table corresponds to Table 1 in Lettau and Ludvigson (2001b). The table presents λ estimates from cross-sectional Fama-MacBeth regressions using returns of 25 Fama-French portfolios:

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_i' \lambda.$$

The individual λ_j estimates (from the second-pass cross-sectional regression) for the beta of the factor listed in the column heading are reported. In the first-pass, the time-series betas β_i are computed in one multiple regression of the portfolio returns on the factors, using either OLS or OLIVE as noted in each row. R_{vw} is the CRSP value-weighted index return, Δy is labor income growth, and SMB and HML are the Fama-French mimicking portfolios related to size and book-to-market equity ratios. The scaling variable is \widehat{cay}_t . The table reports the Fama-MacBeth cross-sectional regression coefficients, with two t -statistics in parentheses for each coefficient estimate. The top t -statistic uses uncorrected Fama-MacBeth standard errors, and the bottom t -statistic uses the Shanken (1992) correction. The cross-sectional R^2 is reported. The model is estimated using data from 1963:Q3 to 1998:Q3. The coefficient estimates of the factors are multiplied by 100, and the estimates of the scaled terms are multiplied by 1,000.

Row	Constant	\widehat{cay}_t	Factors _{$t+1$}				$\widehat{cay}_t \cdot$ Factors _{$t+1$}		R^2
			R_{vw}	Δy	SMB	HML	R_{vw}	Δy	
1-OLS	4.18		-0.32						0.01
	(4.47)		(-0.27)						
1-OLIVE	3.48		0.25						0.01
	(4.71)		(0.30)						
2-OLS	4.47		-1.10	1.26					0.58
	(4.78)		(-0.95)	(3.40)					
2-OLIVE	4.42		-1.22	0.06					0.78
	(5.76)		(-1.32)	(3.55)					
3-OLS	1.76		1.44		0.49	1.49			0.81
	(1.22)		(0.89)		(0.97)	(3.31)			
3-OLIVE	1.79		1.41		0.48	1.53			0.83
	(1.63)		(1.11)		(0.96)	(3.39)			
	(1.49)		(1.01)		(0.88)	(3.10)			

Table 2 to be continued ...

Table 2 Continued

Row	Constant	\widehat{cay}_t	Factors _{t+1}				$\widehat{cay}_t \cdot$ Factors _{t+1}		R^2
			R_{vw}	Δy	SMB	HML	R_{vw}	Δy	
4-OLS	3.69 (3.90) (2.62)	-0.04 (-0.19) (-0.13)	-0.07 (-0.06) (-0.04)				1.14 (3.60) (2.41)		0.31
4-OLIVE	3.09 (4.20) (4.18)	-0.02 (-0.60) (-0.58)	0.13 (0.15) (0.15)				0.10 (3.54) (3.51)		0.80
5-OLS	3.70 (3.86) (2.61)		-0.09 (-0.07) (-0.05)				1.17 (3.59) (2.41)		0.31
5-OLIVE	3.54 (2.84) (2.82)		-0.43 (-0.26) (-0.25)				0.11 (2.93) (2.90)		0.78
5'-OLS	3.83 (4.06) (2.62)		-0.23 (-0.19) (-0.12)				1.27 (3.60) (2.31)		0.30
5'-OLIVE	3.15 (4.20) (4.18)		0.06 (0.07) (0.07)				0.10 (3.65) (3.62)		0.80
6-OLS	5.19 (5.60) (3.33)	-0.44 (-1.59) (-0.94)	-2.00 (-1.74) (-1.03)	0.56 (2.11) (1.25)			0.35 (1.69) (1.00)	-0.17 (-2.39) (-1.42)	0.77
6-OLIVE	1.91 (1.80) (1.76)	0.01 (0.16) (0.15)	1.33 (1.07) (1.04)	0.02 (0.67) (0.66)			0.10 (2.00) (1.95)	-0.0005 (-0.05) (-0.05)	0.83
7-OLS	5.14 (5.59) (3.85)		-1.98 (-1.73) (-1.19)	0.59 (2.20) (1.51)			0.60 (2.71) (1.86)	-0.08 (-2.52) (-1.73)	0.75
7-OLIVE	2.00 (2.30) (2.26)		1.26 (1.25) (1.22)	0.02 (0.66) (0.64)			0.10 (1.89) (1.85)	-0.002 (-1.00) (-0.98)	0.83
7'-OLS	4.26 (4.58) (3.40)		-0.97 (-0.84) (-0.51)	0.91 (2.96) (1.80)			0.43 (2.10) (1.28)	-0.10 (-1.65) (-1.00)	0.71
7'-OLIVE	2.14 (2.17) (2.13)		1.06 (0.91) (0.89)	0.01 (0.24) (0.23)			0.15 (2.60) (2.54)	0.002 (0.20) (0.20)	0.83

Table 3. Consumption CAPM
Fama-MacBeth Regressions Using 25 Fama-French Portfolios:
 λ_j Coefficient Estimates on Betas in Cross-Sectional Regression

This table corresponds to Table 3 in Lettau and Ludvigson (2001b). The table presents λ estimates from cross-sectional Fama-MacBeth regressions using returns of 25 Fama-French portfolios:

$$E(R_{i,t+1}) = E(R_{0,t}) + \beta_i' \lambda.$$

The individual λ_j estimates (from the second-pass cross-sectional regression) for the beta of the factor listed in the column heading are reported. In the first-pass, the time-series betas β_i are computed in one multiple regression of the portfolio returns on the factors, using either OLS or OLIVE as noted in each row. Δc denotes consumption growth (log difference in consumption). The scaling variable is \widehat{cay} . The table reports the Fama-MacBeth cross-sectional regression coefficients, with two t -statistics in parentheses for each coefficient estimate. The top t -statistic uses uncorrected Fama-MacBeth standard errors, and the bottom t -statistic uses the Shanken (1992) correction. The cross-sectional R^2 is reported. The model is estimated using data from 1963:Q3 to 1998:Q3. The coefficient estimates of the factors are multiplied by 100, and the estimates of the scaled terms are multiplied by 1,000.

Row	Constant	\widehat{cay}_t	Δc_{t+1}	$\widehat{cay}_t \cdot \Delta c_{t+1}$	R^2
1-OLS	3.25		0.22		0.16
	(4.94)		(1.26)		
1-OLIVE	(4.50)		(1.14)		
	3.34		0.003		0.03
(4.74)		(0.46)			
2-OLS	(0.88)		(0.45)		
	4.27	-0.12	0.03	0.06	0.70
(6.10)	(-0.42)	(0.22)	(3.14)		
2-OLIVE	(4.24)	(-0.29)	(0.15)	(2.18)	
	4.72	0.04	-0.004	0.009	0.82
(3.70)	(0.90)	(-0.27)	(3.44)		
3-OLS	(3.67)	(0.88)	(-0.27)	(3.40)	
	4.09		-0.02	0.07	0.69
(6.81)		(-0.12)	(3.22)		
3-OLIVE	(5.13)		(-0.09)	(2.41)	
	3.49		0.006	0.007	0.81
(5.85)		(0.42)	(3.36)		
3 ² -OLS	(5.83)		(0.41)	(3.34)	
	2.77		0.01	0.04	0.27
(4.37)		(0.09)	(2.36)		
3 ² -OLIVE	(3.77)		(0.07)	(2.03)	
	5.40		0.04	-0.005	0.34
(6.07)		(2.95)	(-2.29)		
	(6.05)		(2.92)	(-2.27)	