Robust Markov Decision Process

Beyond (and back to) Rectangularity

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What is this talk about?

Uncertainty in transition kernels of Markov Chains.

Geometry of the uncertainty set and tractability.

Markov Decision Process (MDP)



MDP: states S, actions A, reward (r_{sa}), transition probabilities ($P_{sas'}$). **Decision Maker:**

Policy π : Being in state s, what action(s) should I choose?

Goal: Given transition probabilities $P = (P_{sas'})$,

solve
$$\max_{\pi \in \Pi} R(\pi, \mathbf{P})$$
, where $R(\pi, \mathbf{P}) = E^{\pi, \mathbf{P}} \left[\sum_{t=0}^{\infty} \lambda^t r_{\mathbf{s}_t a_t} \mid \mathbf{s}_0 = \mathbf{p}_0 \right]$.

Bellman (1957), Howard (1960); Puterman (1994).

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 \rightarrow Iterate:

$$V_{s}^{k+1} = F_{s}(V^{k}, P), \forall s; V^{0} \in \mathbb{R}^{S}_{+}.$$

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Our goal

Solve $\max_{\pi \in \Pi} \min_{P \in \mathbb{P}} R(\pi, P)$.

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• **Tractable** for some special cases. Iyengar (2005), El Ghaoui, Nilim (2005):

(s,a)-rectangularity:
$$\mathbb{P} = \underset{s,a}{\times} \mathbb{P}_{sa}, \ (P_{sas'})_{s'} \in \mathbb{R}^{S}_{+}.$$

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• Cartesian product X × Y: no constraints across components.

What does Rectangularity mean?

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different health states, same treatment \rightarrow related effect, ie, $\textit{P}_{s_1a} \text{ and }\textit{P}_{s_2a} \text{ might be related}.$

Idea: Transitions depend of common underlying vectors.

$$P_{sa} = \sum_{i=1}^{r} u_{sa}^{i} \mathbf{w}^{i},$$
$$\sum_{i=1}^{r} u_{sa}^{i} = 1, \forall (s, a),$$
$$(\mathbf{w}_{1}, ..., \mathbf{w}_{r}) = \mathbf{W} \in \mathbb{W}$$

Factor matrix (FM) uncertainty set

Generality of FM uncertainty set

For $r = S \times A$, this captures **any** uncertainty set \mathbb{P} .

"min_{$P \in \mathbb{P}$} $R(\pi, P) \ge \gamma$?" is strongly NP-Hard (Wiesemann et al. (2012)).

We assume r-rectangularity:

$$\mathbb{W} = \underset{i=1,\ldots,r}{\times} \mathbb{W}^{i}.$$

Idea: Coupled \mathbb{P} = simple transformation of uncoupled \mathbb{W} .

Think about SVD / Nonnegative Matrix Factorization.

Sum-up so far

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- We solve $\max_{\pi \in \Pi} \min_{W \in \mathbb{W}} R(\pi, W)$.
- We prove a structural result:

 $\max_{\pi \in \Pi} \min_{W \in \mathbb{W}} R(\pi, W) = \min_{W \in \mathbb{W}} \max_{\pi \in \Pi} R(\pi, W).$

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• We extend classical properties of MDPs (Maximum principle, Blackwell optimality).
Theorem 1: Policy Evaluation for rectangular \mathbb{W} Consider a fixed policy π and \mathbb{W} r-rectangular. $\min_{W \in \mathbb{W}} R(\pi, W)$ can be casted as an MDP over $\{1, ..., r\}$.



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• Also LP formulation, Policy Iteration.

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$$\max_{\pi\in\Pi}\min_{W\in\mathbb{W}} R(\pi, W) = \min_{W\in\mathbb{W}}\max_{\pi\in\Pi} R(\pi, W).$$

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Lemma

There exists a deterministic robust optimal policy π^* .

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Key Lemma

$$W^* \in \arg\min_{W \in W} R(\pi^*, W),$$

$$\pi^* \in \arg\max_{\pi \in \Pi} R(\pi, W^*).$$

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Theorem 2: Robust value iteration Robust Value Iteration obtains (π^*, W^*) in polynomial time with $W^* \in \arg\min_{W \in W} R(\pi^*, W),$ $\pi^* \in \arg\max_{\pi \in \Pi} R(\pi, W^*).$



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- Their fixed points are the solutions to our max-min problem.



Decision Maker:

$$\pi^* \in \arg \max_{\pi \in \Pi} R(\pi, W^*).$$

Adversary:

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$$\beta_i^* = H_i(\boldsymbol{\beta}^*, \pi^*), \; \forall \; i.$$



Using $W^{*T}V^* = \beta^*$, $V_s^* = f_s(V^*), \forall s,$ $\beta_i^* = h_i(\beta^*), \forall i,$ and $f : \mathbb{R}^S \to \mathbb{R}^S, h : \mathbb{R}^r \to \mathbb{R}^r$ are contractions.

Some useful properties

Maximum principle: in classical MDP, $V^{\pi^*} \ge V^{\pi}$, for all policy π .

Robust Maximum principle

 $V^{\pi^*,W^*} \ge V^{\pi,W}$, for all policy π , for all $W \in \arg\min_{W \in \mathbb{W}} R(\pi, W)$.

Blackwell optimality: the optimal nominal policy remains optimal when $\lambda \rightarrow$ 1.

Robust Blackwell optimality There exists (π^*, W^*) and $\lambda_0 \in (0, 1)$, such that for all λ in $(\lambda_0, 1)$, $(\pi^*, W^*) \in \arg \max_{\pi \in \Pi} \min_{W \in W} R(\pi, W, \lambda).$ Application: how to use FM uncertainty set?

- use of Non Negative Matrix Factorization (NMF).
- use of Robust maximum principle.

Use of Non Negative Matrix Factorization (NMF)

NMF \iff non-negative SVD:

given $A \ge 0$, minimize ||A - BC|| with $B \ge 0, C \ge 0$.

Suppose we have estimated $\hat{P} = (\hat{P}_{sas'})$ with confidence $\tau > 0$.

we want
$$\hat{\boldsymbol{P}}_{sa} = \sum_{i=1}^{r} u_{sa}^{i} \boldsymbol{w}_{i}.$$

Therefore, for $\hat{P} = (\hat{P}_{s_1a_1}, ..., \hat{P}_{SA})$, we solve the NMF program $\min_{W \in H_1, u \in H_2} \|\hat{P} - Wu\|.$

r-rectangularity: obtaining (\hat{W}, \hat{u}) , budget of uncertainty sets:

$$\mathbb{W}^{i} = \{ \mathbf{w}_{i} = \hat{\mathbf{w}}_{i} + \boldsymbol{\delta} | \boldsymbol{\delta} \in \mathbb{R}^{S}, \| \boldsymbol{\delta} \|_{1} \leq \sqrt{S} \cdot \tau, \| \boldsymbol{\delta} \|_{\infty} \leq \tau, \mathbf{e}_{S}^{\top} \mathbf{w}_{i} = 1, \mathbf{w}_{i} \geq \mathbf{0} \}, \forall i.$$

300,000 'patients histories' at Kaiser Permanente hospitals:

Patients arrive in hospital ward with risk score $s \in \{1, ..., n\}$. Risk score updated every six hours: $s \rightarrow s'$, Markov chain T.

Question: proactive transfer of patients to the emergency room?

Pros: better outcome when treated in emergency room.

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Proposition: structure of optimal policies.
The optimal nominal policy \pi^{\text{nom}} is threshold.
The optimal robust policy \pi^{\text{rob}} is threshold, and thr(\pi^{\text{rob}}) \leq thr(\pi^{\text{nom}}).
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Example: π^{nom} admits top 8% patients, π^{rob} admits top 27.1%.

Our contributions:

Assuming \mathbb{W} is rectangular:

- Efficient algorithm for $\min_{W \in \mathbb{W}} R(\pi, W)$.
- Robust Value Iteration for $\max_{\pi \in \Pi} \min_{W \in \mathbb{W}} R(\pi, W)$.
- Equilibrium result:

$$\exists (\pi^*, W^*), W^* \in \min_{W \in \mathbb{W}} R(\pi^*, W), \pi^* \in \max_{\pi \in \Pi} R(\pi, W^*).$$

 \Rightarrow strong duality + deterministic optimal robust policy.

• Robust maximum principle, robust Blackwell optimality.

Future work:

• Robust MDP with long-run average reward.
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- Fixed parameter r + non-rectangular \mathbb{W} .

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Thank you! Any questions?

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