

Search and Satisficing

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- We will begin by studying one of the oldest and most famous models of bounded rationality
 - Satisficing
 - Originally described by Herbert Simon [1955]
- A very simple and intuitive choice procedure

- Say you are trying to buy a car
- Here is what you do
 - ① Decide what features your car needs to have
 - Automatic, 5 star safety rating, go faster stripes, price less than \$10,000
 - ② Go to the car lot and look at the first car
 - ③ Does this car satisfy the needs you identified in (1)?
 - If yes, buy the car
 - If not go on to the next car and repeat (3)
 - ④ If you have looked at all the cars in the lot, and none of them satisfy your needs, go back and buy the best one

- The procedure was called 'satisficing' to differentiate it from 'maximizing'
 - i.e. looking at **all** cars and choosing the one with the highest utility
- You won't necessarily end up with the best option
 - Maybe you bought a car that satisfied your desires, but if you had searched one more you would have got the same model \$1000 cheaper
- But is a much easier procedure than utility maximizing
 - Don't in general have to look at all the cars

- We are going to cover two things with regard to Satisficing

① Satisficing as optimal choice

- Simon introduced Satisficing as a 'psychologically rational' theory of choice
- Turns out it can be optimal under some circumstances

② Testing the Satisficing model

- Turns out that testing the satisficing model using standard choice data is hard
- We will discuss some different data sets that we can use

Satisficing as Optimal Stopping

- Imagine that you are back in the car lot
- You have seen a car which is pretty good
- But there are 1000 other cars in the car lot you could look at
- It takes time and effort to look at the next car to see how good it is
- Should you stop and buy the car you are looking at, or keep searching?
- This is an **optimal stopping problem**

Satisficing as Optimal Stopping

- We want to write down a model that captures the following idea
 - Before looking at a car, you don't know how good it is
 - Once you look at a car, you know exactly how good it is
 - But there is a cost to looking at each car
- Should you keep searching, given the cars that you have already seen?

- A set A containing M items
- A utility function $u: X \rightarrow \mathbb{R}$
 - Value of each option
- A probability distribution f :
 - Beliefs about the value of each option before it is seen
- A cost k :
 - Has to be paid in order to understand the value of the next available alternative.

- At any point, decision maker has to choose either to
- ① Stop searching, and choose the best available alternative that they have looked at
 - We allow recall, so the DM can choose any of the objects that they have already seen
- ② Search another item and pay the cost k
- If they continue searching they will be faced with the same choice after they have looked at the next alternative

- How could we solve this model?
- Backwards induction!
 - Imagine that you had looked at all but one alternative
 - What would you do?
 - Work backwards from there

After Searching all but one Item

- Let's say that the DM has searched $M - 1$ items
- The best thing they have seen so far has utility \bar{u}
- Should they search the M th item?
- How would you decide?
- Compare the value of not searching to the value of searching

The Value of Not Searching

- What happens if the firm doesn't search?
- Get the item with utility \bar{u} and pay costs of all the searching done so far

$$\bar{u} - (1 - M)k$$

- What happens if the firm searches?
- Will have to pay, so search costs now Mk
- What are the benefits?
- Depends on the value of the new alternative you look at u
 - If $u < \bar{u}$ then will choose old item and get \bar{u}
 - If $u > \bar{u}$ then choose new item and get u
 - Integrate up over possible values of u
- Total value of searching is

$$\int_{-\infty}^{\bar{u}} \bar{u}f(u)du + \int_{\bar{u}}^{\infty} uf(u)du - Mk$$

- So continuing to search is better if

$$\begin{aligned} & \int_{-\infty}^{\bar{u}} \bar{u} f(u) du + \int_{\bar{u}}^{\infty} u f(u) du - Mk \\ & \geq \bar{u} - (1 - M)k \end{aligned}$$

- Notice we can write

$$\bar{u} = \int_{-\infty}^{\bar{u}} \bar{u} f(u) du + \int_{\bar{u}}^{\infty} \bar{u} f(u) du$$

- So continuing better if

$$k \leq \int_{\bar{u}}^{\infty} (u - \bar{u}) f(u) du$$

$$k \leq \int_{\bar{u}}^{\infty} (u - \bar{u}) f(u) du$$

- Notice that the left hand side does not change with \bar{u}
- The right hand side **decreases** in \bar{u}
 - Value of continuing to search falls as the value of the best thing you have already seen increases
- Thus we can find a u^* such that

$$k = \int_{u^*}^{\infty} (u - u^*) f(u) du$$

- Optimal strategy
 - Keep searching if the best item you have seen is worse than u^*
 - Stop if it is better than u^*
- This is called a **reservation stopping rule**

- This tells us what to do when we have searched $M - 1$ items
- What about when we have searched $M - 2$ items?
- First, let's think about what you should do if the value of the best item you have seen \bar{u} is less than u^*
 - The reservation level from last period
- Should definitely keep searching
 - We know from before that if $\bar{u} < u^*$ it is worth searching at least one more period
 - If there are 2 items left to search, can always just search one of them and stop

- What if $\bar{u} > u^*$
- Should definitely stop searching!
 - Will definitely stop searching after looking at the next alternative
 - We know that from the optimal strategy in $M - 1$
 - But that also told us that if $\bar{u} > u^*$ it is not worth searching one more item
- Can repeat for $M - 3, M - 4$ etc

- The optimal strategy is the same in each period!
 - Stop searching if you uncover an object with value greater than u^*
 - Carry on searching otherwise
- If you get to the end, just choose the best option
- But this sounds exactly like satisficing!
 - Keep searching until you find something that is 'good enough'
 - Good enough means better than u^*
- Caveat: We have made some rather specific assumptions to make sure optimal strategy is satisficing
 - e.g. no learning about f

- What is the advantage of deriving this as an optimal strategy?
- Allows us to make predictions about how behavior changes with the environment

$$k = \int_{u^*}^{\infty} (u - u^*) f(u) du$$

- The satisficing level is
 - **Falling** with the cost of looking
 - **Rising** in the variance of f (for a fixed mean)
 - **Rises** one for one with the mean of f (for a fixed variance)
 - **Does not change** with the size of the choice set

Testing the Satisficing Model

- Let's say I have persuaded you that the satisficing model sounds more persuasive than utility maximization
- What should you do next?
- Figure out how to test this hypothesis!
 - We are, after all, scientists
 - Even if we are only social scientists
- How can we do this?

- Approach 1: using standard choice data
- Unfortunately this isn't going to work
- Why?
 - ① Assumption 1: always search through choice sets in the same order
 - Same prediction as utility maximization
 - See homework
 - ② Assumption 2: Change search order in each choice
 - Can rationalize any data set
 - Just assume everything is above the satisficing level
 - Whatever is chosen is the thing that was

- We need a richer data set
- Will consider two
 - ① Choice process data
 - Records how people's choices change the longer they think
 - ② Search data
 - Records what it is that people have looked at before making a choice

- Imagine we were interested in the behavior of someone buying a stereo
- We could follow them around the shop
- At any given time, we could ask
 - "If you had to choose now, which stereo would you pick?"
- This would be pretty annoying, but would give us very rich data
 - Standard choice data: $C(A)$ choice from set A
 - Choice process data: $C(A, t)$ choice from A **having thought about the problem for time t**
 - Also observe the time at which they make their 'final' choice

- We can use choice process data to test the satisficing model
 - People search through alternatives one at a time
 - At any given time, $C(A, t)$ is the best of the things that they have seen
 - When they find something that is better than the satisficing level they stop searching and make a final choice
- What type of choice process data is consistent with this behavior?
 - To make our lives easier, we will assume we know the utility of each alternative

- Which of the following are consistent with Satisficing?

Observation	Available options	Sequence of Choices	Final Choice
1	{1, 2, 3, 4}	{3, 1, 4}	4
2	{2, 4, 6, 10}	{2, 4, 6}	6
3	{2, 4, 6, 8, 10}	{2, 4, 8}	8
4	{2, 4, 6, 8, 10}	{2, 6, 8, 10}	10

- We require two conditions to ensure that data is consistent with satisficing
 - ① Subjects must always switch to higher value alternatives
 - ② There must be some u^* such that search stops if and only if the utility of the chosen value is above u^*

- We will now talk through an experiment that will allow us to test whether the satisficing model explains choice mistakes
- We need three things in our design
 - ① Ranking of alternatives is clear to us as experimenters
 - ② But subjects still make mistakes
 - ③ Need to be able to collect choice process data

- Subjects choose between 'sums'

four plus eight minus four

- Value of option is the value of the sum
- 'Full information' ranking obvious, but uncovering value takes effort
- 6 treatments
 - 2 x complexity (3 and 7 operations)
 - 3 x choice set size (10, 20 and 40 options)
- No time limit

Round
2 of 30

Current selection:

four plus eight minus four

Choose one:

- zero
- three plus five minus seven
- four plus two plus zero
- four plus three minus six
- four plus eight minus four
- three minus three plus one
- five plus one minus one
- eight plus two minus five
- three plus six minus five
- four minus two minus one
- five plus five minus one

Finished

Size 20, Complexity 7

- zero
- seven minus four minus two minus four minus two plus eleven minus four
- six plus five minus eight plus two minus nine plus one plus four
- seven minus two minus four plus three plus four minus three minus three
- seven plus five minus two minus two minus three plus zero minus two
- six plus seven plus six minus two minus six minus eight plus four
- six plus two plus five minus four minus two minus seven plus three
- six minus four minus one minus one plus five plus three minus six
- two plus six plus seven minus two minus four minus two plus zero
- two minus three minus five plus nine minus one plus five minus three
- three plus zero plus two plus zero plus one minus three minus one
- four plus three plus zero minus two plus three plus four minus ten
- seven plus two plus seven minus seven plus three minus two minus two
- three plus three minus two plus zero plus zero minus four plus five
- two minus two plus zero plus nine minus two minus one minus one
- three plus four minus three plus three minus four plus three minus four
- three plus five plus seven plus five minus two minus seven minus ten
- three plus six minus eight plus one plus two minus two plus zero
- three plus five plus zero plus four plus three minus four minus two
- eight minus one plus one minus four minus four minus five plus six
- four minus five plus four minus one minus four plus zero plus four

Finished

Results

Failure rates (%) (22 subjects, 657 choices)

Failure rate		
Set size	Complexity	
	3	7
10	7%	24%
20	22%	56%
40	29%	65%

Results

Average Loss (\$)

Average Loss (\$)		
Set size	Complexity	
	3	7
10	0.41	1.69
20	1.10	4.00
40	2.30	7.12

- In this environment, people do not choose the best option
- Choice does not imply revealed preference
- Can behavior be explained by search and satisficing model?
- Do these models resurrect the concept of revealed preference?

- ① Allow subjects to **select** any alternative at any time
 - Can change selection as often as they like
- ② **Choice** will be recorded at a random time between 0 and 120 seconds unknown to subject
 - Incentivizes subjects to always keep selected current best alternative
 - Treat the sequence of selections as choice process data
- ③ Round can end in two ways
 - After 120 seconds has elapsed
 - When subject presses the 'finish' button
 - We discard any rounds in which subjects do not press 'finish'

Round
2 of 30

Current selection:

four plus eight minus four

Choose one:

- zero
- three plus five minus seven
- four plus two plus zero
- four plus three minus six
- four plus eight minus four
- three minus three plus one
- five plus one minus one
- eight plus two minus five
- three plus six minus five
- four minus two minus one
- five plus five minus one

Finished

Stage 2: Choice Recorded



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Choice Recorded

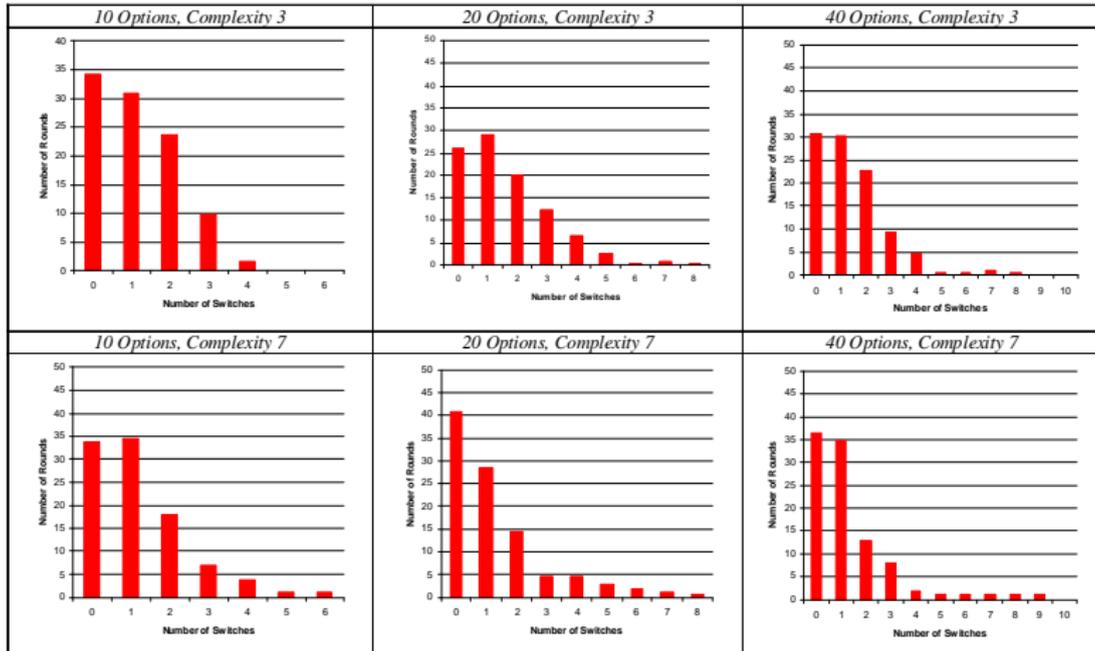
In this round, your choice was recorded after **9** seconds. At that time, you had selected:

four plus four minus six

Next

Do We Get Richer Data from Choice Process Methodology?

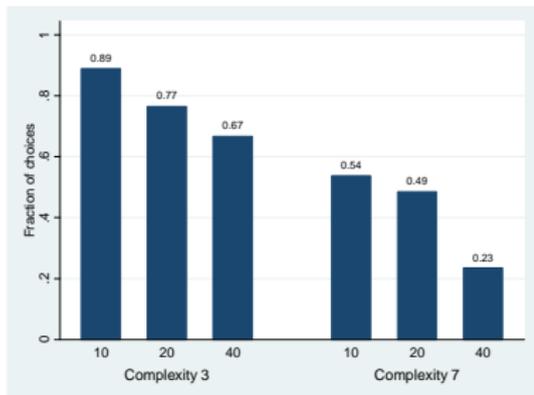
978 Rounds, 76 Subjects



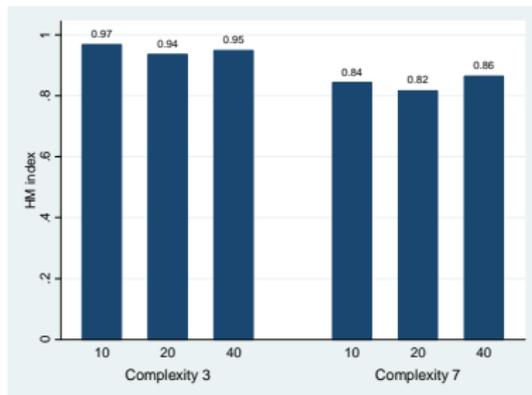
- Subjects must always switch to higher-valued objects
(Condition 1)
- Graph the fraction of switches that satisfy condition 1
- Compare to the fraction of choices that satisfy 'standard' revealed preference

Traditional vs ABS Revealed Preference

Traditional



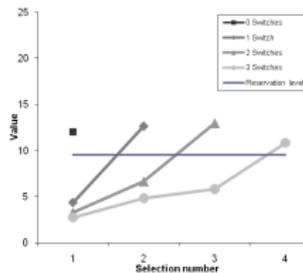
ABS



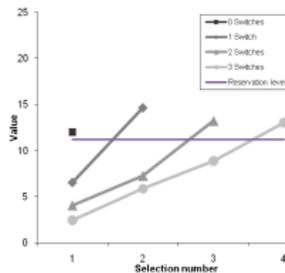
- Broadly speaking, subjects are searching sequentially
- Are they Satisficers?
- Can we find a utility level u^* such that they stop search if and only if they encounter a utility above u^* ?

Satisficing Behavior a la Simon [1955]

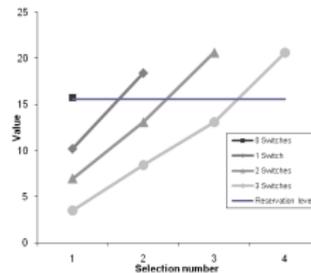
10



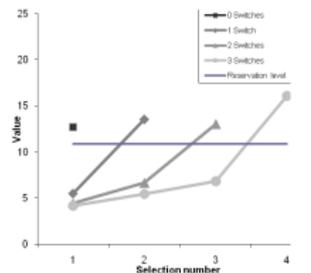
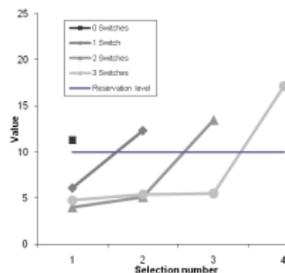
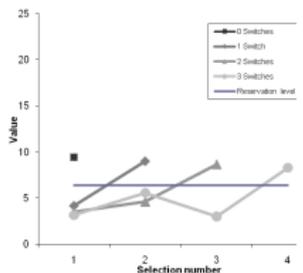
20



40



3



7

Estimating Reservation Levels

- Choice process data allows observation of subjects
 - Stopping search
 - Continuing to search
- Allows us to estimate reservation levels
- Assume that reservation level is calculated with some noise at each switch
- Can estimate reservation levels for each treatment using maximum likelihood

Estimated Reservation Levels

Set size	Complexity			
	3		7	
10	9.54	(0.20)	6.36	(0.13)
20	11.18	(0.12)	9.95	(0.10)
40	15.54	(0.11)	10.84	(0.10)

- Reservation levels decrease with complexity
 - As predicted by theory
- Increase with choice set size
 - Not predicted by theory