

Rational Inattention Lecture 1

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Behavioral Economics G6943
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- (Hopefully) convinced you that attention costs are important
- Introduced the concept of consideration sets
 - Along with sequential search and satisficing
- Showed that the model did a reasonable job in some circumstances
- But, there is something restrictive about consideration sets
 - Items are either in the consideration set and fully understood
 - Or outside the consideration set, and nothing is learned
- Seems like a good model for choice over a large number of simple alternatives
- Not for a small number of complex alternatives

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Name	Description
Roth Conversion Evaluator	Estimate the potential benefits of converting to a Roth IRA, explore how much to convert and how to pay for it.
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Savings Planner	Take a few minutes to tell us your priorities and we'll help you create a plan to save and pay down debt.
Portfolio Review	Identify a target asset mix that aligns with your goals. Then easily implement an investment strategy that will help you stay on track.
myPlan Snapshot®	Answer five easy questions for a quick estimate of how much you may need to save for retirement compared with your projected savings.
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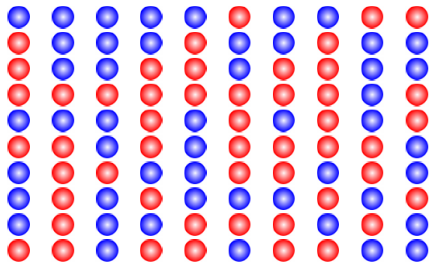
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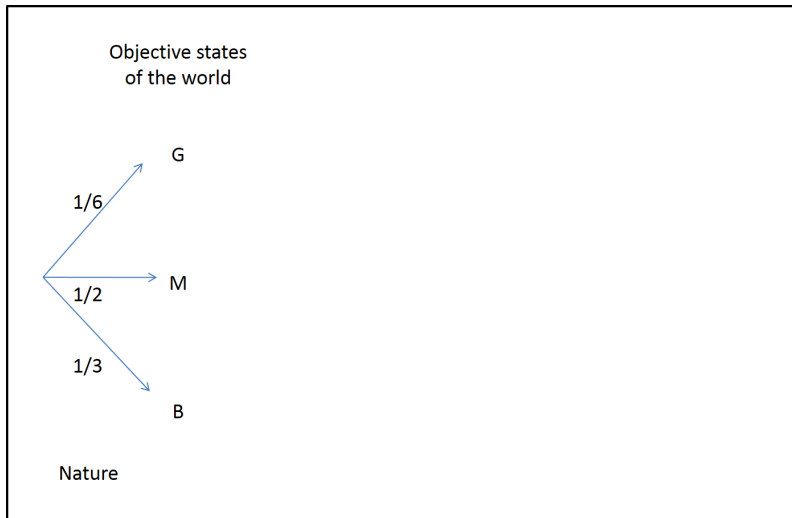


Act	Payoff 47 red dots	Payoff 53 red dots
a	20	0
b	0	10

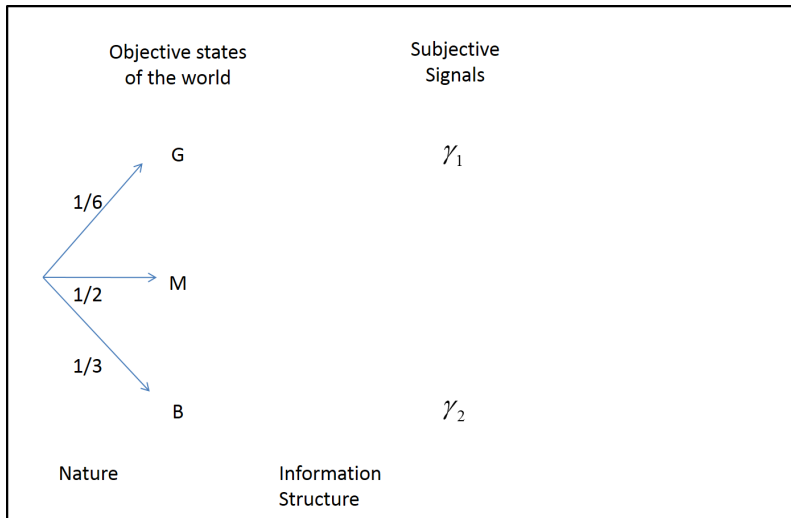
- Objective states of the world
 - e.g. Demand could be 'good', 'medium' or 'bad'
- Decision maker chooses an action
 - e.g. Set price to be high, medium, or low
- Gross payoff depends on action and state
 - e.g. Quantity sold depends on price and demand
- Decision maker get to learn something about the state before choosing action
 - e.g. Could do market research, focus groups, etc.
- Can choose what to learn conditional on the problem

- The specifics of the process of information acquisition may be very complex
- We model the choice of information in an *abstract* way
- The decision maker chooses an *information structure*
 - Set of signals to receive
 - Probability of receiving each signal in each state of the world
- Choose action conditional on signal received
- Value of strategy given by
 - Expected value of actions taken given posterior beliefs
 - Minus cost of information
- Notice that this is an optimizing model with additional constraints
 - Subjects respond to costs and incentives
 - At least an interesting benchmark

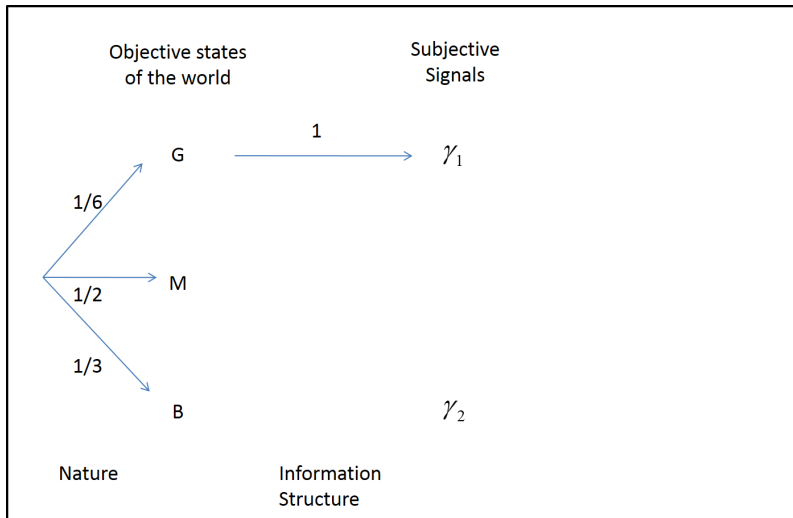
The Choice Problem



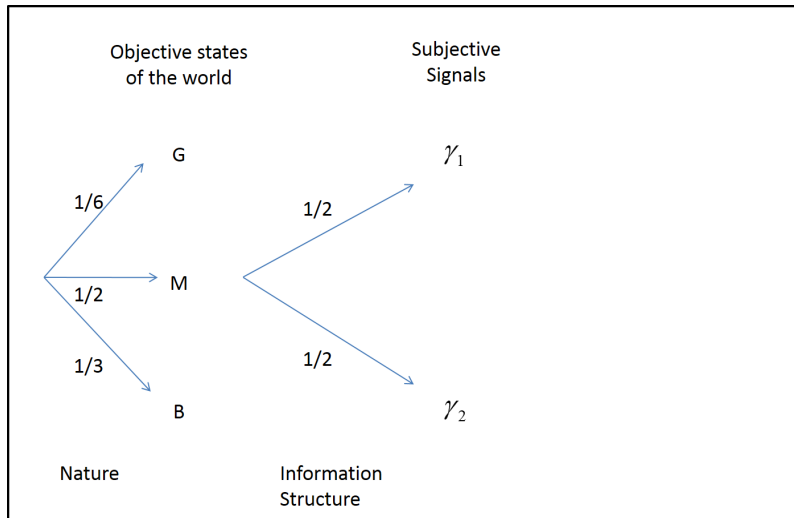
The Choice Problem



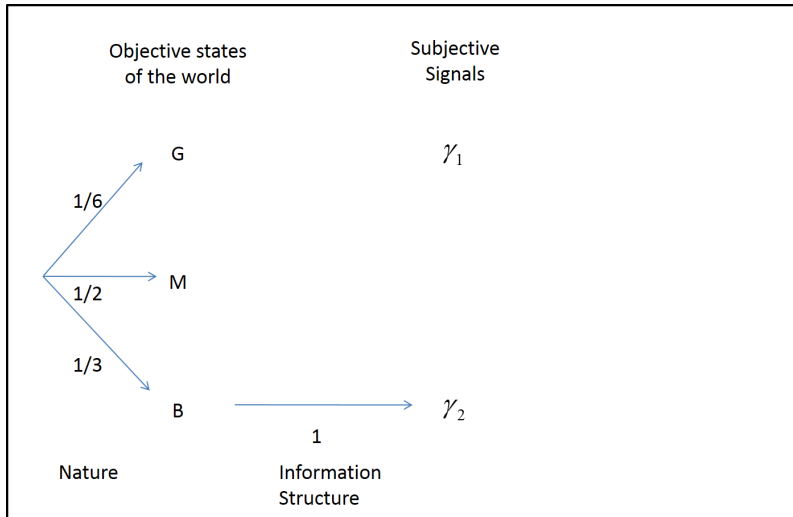
The Choice Problem



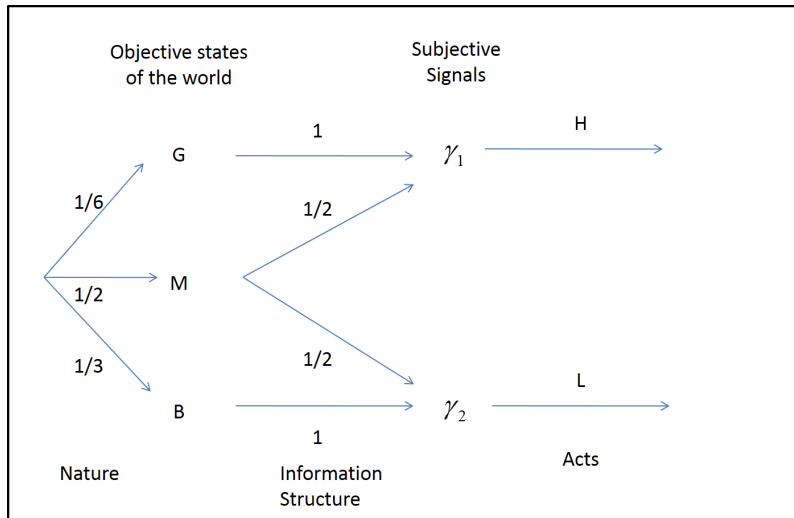
The Choice Problem



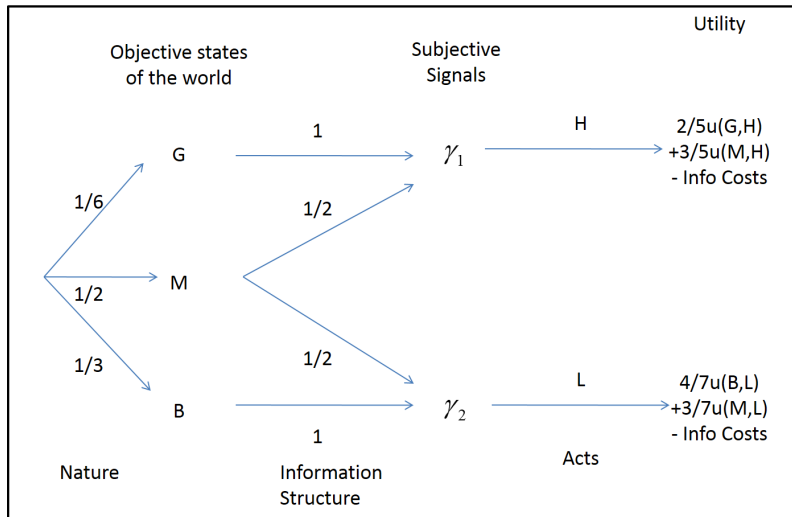
The Choice Problem



The Choice Problem



The Choice Problem



- Note that most 'real world' information gathering activities can be thought of in terms of as generating information structures
- E.g., say that you have developed a new economics class
- There are two possible states of the world
 - Class is good - $\frac{2}{3}$ of people like it on average
 - Class is bad - $\frac{1}{3}$ of people like it on average
- Each is equally likely
- Release a survey in which all 12 members of the class report if they like the class or not
- This generates an information structure
 - 13 signals: 0,1,2..... people say they like the class
 - Probability of each signal given each state of the world can be calculated

- Ω : Objective states of the world (finite)
 - with prior probabilities μ
- a : An action - utility depends on the state
 - $U(a, \omega)$ utility of action a in state ω
 - \mathcal{A} : Set of actions:
- $A \subset \mathcal{A}$: Decision problem (finite)

- For each decision problem
 - 1 Choose information structure (π)
 - Defined by:
 - Set of signals: $\Gamma(\pi)$
 - Probability of receiving each signal γ from each state ω : $\pi(\gamma|\omega)$
 - 2 Choose action conditional on signal received (C)
 - $C(\gamma)$ probability distribution over actions given signal γ
- In order to maximize
 - Expected value of actions taken given posterior beliefs
 - Minus cost of information K

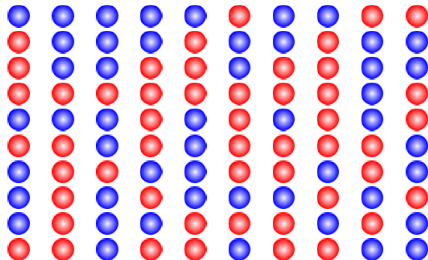
- Easy to calculate the *value* of an information structure

$$G(A, \pi) = \max_{C: \Gamma(\pi) \rightarrow \Delta(A)} \sum_{\Omega} \mu(\omega) \sum_{\gamma \in \Gamma(\pi)} \pi(\gamma | \omega) \left(\sum_{a \in A} C(a | \gamma) U(a(\omega)) \right)$$

- But what is the correct information processing technology?
 - Choose variance of normal signal (e.g. Verrecchia 1982)?
 - Shannon mutual information costs (e.g. Sims 1998)?
 - Choose from set of available partitions (e.g. Ellis 2012)?
 - Sequential search (e.g. McCall 1970)?
- As usual, have two possible approaches
 - ① Make further assumptions
 - ② Ask if there is *any* cost function that can explain the data
- Today we take approach 2
- Next week we will follow approach 1

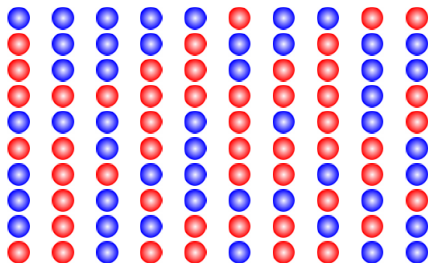
- Let D be a collection of decision problems
- What could we observe?
- Standard choice data
 - $C(A)$: what is chosen from A
- Stochastic choice data
 - $P_A(a)$: probability of choosing alternative a
- **State dependent stochastic choice data** P_A
 - $P_A(a|\omega)$ probability of choosing action a conditional on state ω
- Also assume we observe:
 - Prior probabilities μ
 - Utilities U
- Do **not** observe
 - Information structures π_A
 - Subjective signals γ
 - Information costs K

An Experimental Example



- Subjects presented with 100 balls
- State is determined by the number of red balls
- Prior distribution of red balls known to subject

An Experimental Example



Action	Payoff 49 red balls	Payoff 51 red balls
a	10	0
b	0	10

- No time limit: trade off between effort and financial rewards

An Experimental Example

- Data: State dependant stochastic choice
 - Probability of choosing each action in each objective state of the world

Action	State = 49 red balls	State = 51 red balls
Prob choose a	$P(a 49)$	$P(a 51)$
Prob choose b	$P(b 49)$	$P(b 51)$

- Observe subject making same choice 50 times
- Can use this to estimate P_A
 - But we will not be able to observe P_A perfectly
 - Will only be able to make probabilistic statements

- What type of stochastic choice data $\{D, P\}$ is consistent with optimal information acquisition?
- i.e. there exists a cost function K
- For each decision problem $A \in D$ an information structure π_A and choice function C_A s.t.
 - C_A is optimal for each γ
 - π_A is optimal given K
 - C_A and π_A are consistent with P_A

$$P_A(a|\omega) = \sum_{\gamma \in \Gamma(\pi_A)} \pi_A(\gamma|\omega) C_A(a|\gamma).$$

- What ‘mistakes’ are consistent with optimal behavior in the face of information costs?

- This approach is very flexible
 - No in principle restriction on information structures
 - No restrictions on costs
- Nests other models of information acquisition
 - e.g. Shannon Mutual Information set costs to

$$K(\pi) = \lambda E \left(\log \frac{\mu(\omega)\pi(\gamma|\omega)}{\mu(\omega)\pi(\gamma)} \right)$$

- Can mimic a hard constraints
 - e.g. a model in which subjects choose the variance of a normal signal, set the cost of all other information structures to ∞

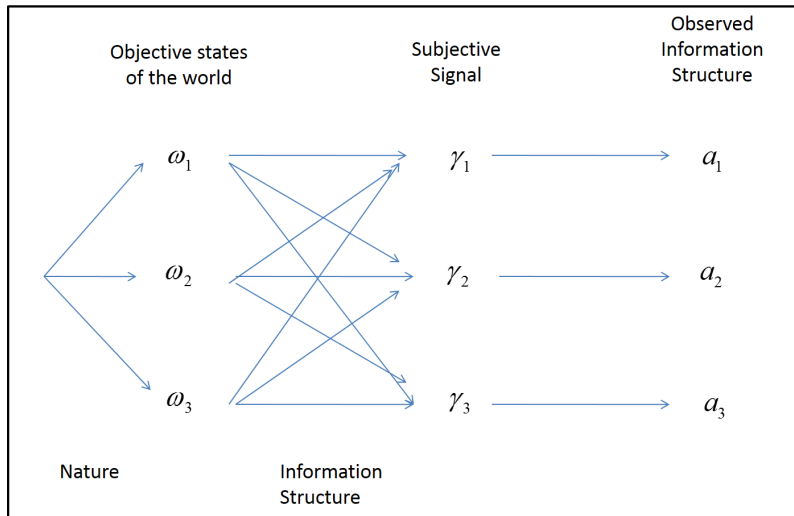
Observing Information Structures

- Key observation: State dependent stochastic choice data tells us a lot about the information structure a decision maker has used
- Assume that decision maker is 'well behaved'
 - Chooses each action in response to at most one signal
 - No mixed strategies - one action per signal
- Information structure can be observed directly from state dependent stochastic choice
 - For each chosen action a there is an associated signal $\bar{\gamma}^a$
 - Probability of signal $\bar{\gamma}^a$ in state ω is the same as the probability of choosing a in ω

$$\bar{\pi}(\bar{\gamma}^a|\omega) = P(a|\omega)$$

- Call $\bar{\pi}$ the 'revealed information structure'

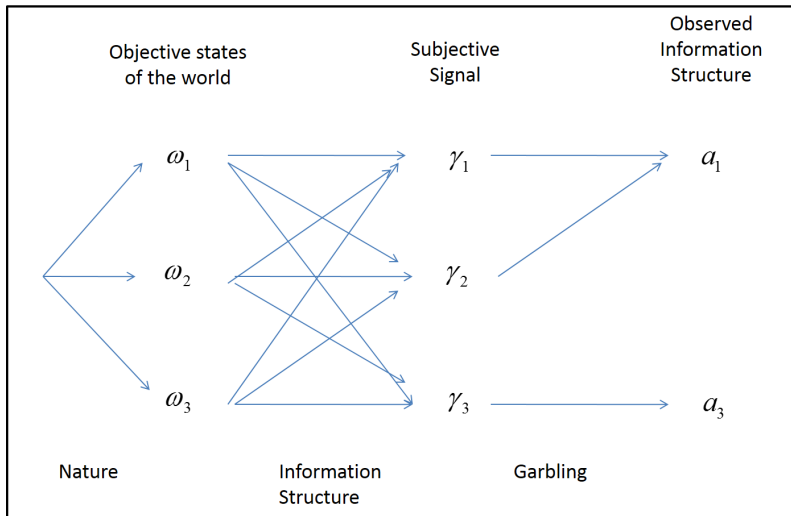
Recovering Attention Strategy

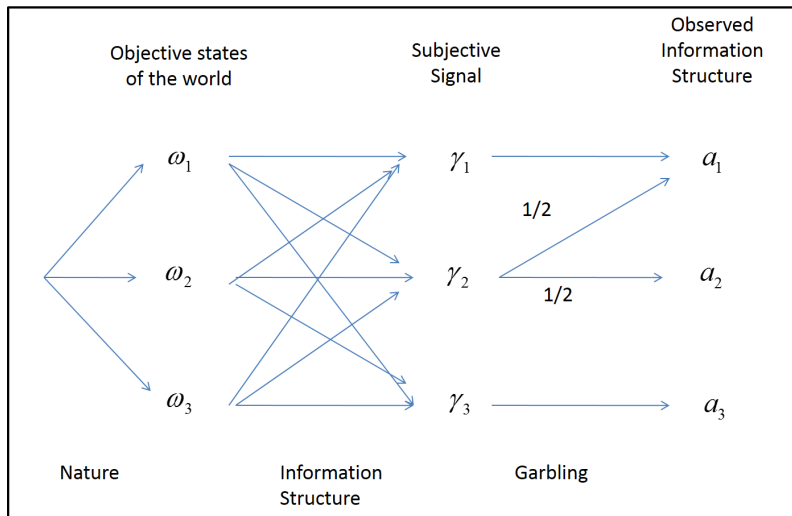


Observing Attentional Strategies

- What if decision maker is not well behaved?
 - Chooses some act in more than one **subjective** state
 - Mixed strategies - more than one act in an **subjective** state

Same Act in Different States





Observing Information Structures

- Can still recover revealed information structure $\bar{\pi}$
- Not necessarily the same as true information structure π
- But will be a **garbling** of the true information structure
 - i.e. π is statistically sufficient for $\bar{\pi}$
- There exists a stochastic $|\Gamma(\pi)| \times |\Gamma(\bar{\pi})|$ matrix B such that if we
 - Apply π
 - For each state γ^i move to state $\bar{\gamma}^j$ with probability B^{ij}
 - We obtain $\bar{\pi}$
- i.e.

$$\sum_j B^{ij} = 1 \quad \forall j$$
$$\bar{\pi}(\bar{\gamma}^j | \omega) = \sum_i B^{ij} \pi(\gamma^i | \omega) \quad \forall j$$

- Intuition: SDSC data cannot be more informative than the signal that created it

An Aside: Blackwell's Theorem

- Let $G(A, \pi)$ be the *gross value* of using information structure π in decision problem A

$$\begin{aligned} & G(A, \pi) \\ = & \max_{C: \Gamma(\pi) \rightarrow \Delta(A)} \sum_{\Omega} \mu(\omega) \sum_{\gamma \in \Gamma(\pi)} \pi(\gamma|\omega) \left(\sum_{a \in A} C(a|\gamma) U(a(\omega)) \right) \end{aligned}$$

- An information structure π is sufficient for information structure π' if and only if

$$G(A, \pi) \geq G(A, \pi') \quad \forall A$$

- $\bar{\pi}$ may not be the agent's true information structure
 - But the true information structure π must be sufficient for $\bar{\pi}$
 - π will be at least as valuable as $\bar{\pi}$ in any decision problem
- Turns out that this is all we need

Characterizing Rational Inattention

- Choice of act optimal given attentional strategy
- Choice of attention strategy optimal

Characterizing Rational Inattention

- Choice of act optimal given attentional strategy
- Choice of attention strategy optimal

Optimal Choice of Action

Action	Payoff 49 red balls	Payoff 51 red balls
a^1	20	0
b^1	0	10

Prior: $\{0.5, 0.5\}$

Action	State = 49 red balls	State = 51 red balls
Prob choose a	$\frac{1}{2}$	$\frac{1}{3}$
Prob choose b	$\frac{1}{2}$	$\frac{2}{3}$

- Posterior probability of 49 red balls when action b was chosen

$$\begin{aligned}\Pr(\omega = 49 | b \text{ chosen}) &= \frac{\Pr(\omega = 49, b \text{ chosen})}{\Pr(b \text{ chosen})} \\ &= \frac{\frac{1}{4}}{\frac{1}{4} + \frac{2}{6}} = \frac{3}{7}\end{aligned}$$

- But for this posterior

$$\begin{aligned}\frac{3}{7}U(a(49)) + \frac{4}{7}U(a(51)) &= \frac{3}{7}20 + \frac{4}{7}0 = 8.6 \\ \frac{3}{7}U(b(49)) + \frac{4}{7}U(b(51)) &= \frac{3}{7}0 + \frac{4}{7}10 = 5.7\end{aligned}$$

- To avoid such cases requires

$$a \in \arg \max_{a \in A} \sum_{\omega} \Pr(\omega|a) U(a(\omega))$$

- Which implies

Condition 1 (No Improving Action Switches) For every chosen action a

$$\sum \mu(\omega) P_A(a|\omega) [u(a(\omega)) - u(b(\omega))] \geq 0.$$

for all $b \in A$

- If $\bar{\pi}$ not true information structure, condition still holds
 - a optimal at all posteriors in which it is chosen
 - Must also be optimal at convex combination of these posteriors

Characterizing Rational Inattention

- Choice of act optimal given attentional strategy
- Choice of attention strategy optimal

Optimal Choice of Attention Strategy

Decision Problem 1

Action	Payoff 49 red balls	Payoff 51 red balls
a^1	10	0
b^1	0	10

Prior: $\{0.5, 0.5\}$

Action	State = 49 red balls	State = 51 red balls
Prob choose a	$\frac{3}{4}$	$\frac{1}{4}$
Prob choose b	$\frac{1}{4}$	$\frac{3}{4}$

Optimal Choice of Attention Strategy

Decision Problem 2

Action	Payoff 49 red balls	Payoff 51 red balls
a^2	20	0
b^2	0	20

Prior: $\{0.5, 0.5\}$

Action	State = 49 red balls	State = 51 red balls
Prob choose a	$\frac{2}{3}$	$\frac{1}{3}$
Prob choose b	$\frac{1}{3}$	$\frac{2}{3}$

Optimal Choice of Attention Strategy

- $G(A, \pi)$ is the gross value of using information structure π in decision problem A

G	$\bar{\pi}^1$	$\bar{\pi}^2$
$\{a^1, b^1\}$	$7\frac{1}{2}$	$6\frac{2}{3}$
$\{a^2, b^2\}$	15	$13\frac{1}{3}$

- Cost function must satisfy

$$G(\{a^1, b^1\}, \pi^1) - K(\pi^1) \geq G(\{a^1, b^1\}, \pi^2) - K(\pi^2)$$

$$G(\{a^2, b^2\}, \pi^2) - K(\pi^2) \geq G(\{a^2, b^2\}, \pi^1) - K(\pi^1)$$

- Which implies

$$\frac{5}{6} = G(\{a^1, b^1\}, \pi^1) - G(\{a^1, b^1\}, \pi^2) \geq$$

$$K(\pi^1) - K(\pi^2) \geq$$

$$G(\{a^2, b^2\}, \pi^1) - G(\{a^2, b^2\}, \pi^2) = 1\frac{2}{3}$$

Optimal Choice of Attention Strategy

- Surplus must be maximized by correct assignments

$$\begin{aligned} G(\{a^1, b^1\}, \pi^1) + G(\{a^2, b^2\}, \pi^2) \\ \geq G(\{a^1, b^1\}, \pi^2) + G(\{a^2, b^2\}, \pi^1) \end{aligned}$$

- What if $\bar{\pi} \neq \pi$?
- We know that revealed and true information structure must give same value in DP it was observed

$$G(A^i, \bar{\pi}^i) = G(A^i, \pi^i)$$

- Also, as π weakly Blackwell dominates $\bar{\pi}$

$$G(A^i, \bar{\pi}^j) \leq G(A^i, \pi^j)$$

Optimal Choice of Attention Strategy

- Surplus must be maximized by correct assignments

$$\begin{aligned} & G(\{a^1, b^1\}, \bar{\pi}^1) + G(\{a^2, b^2\}, \bar{\pi}^2) \\ & \geq G(\{a^1, b^1\}, \pi^2) + G(\{a^2, b^2\}, \pi^1) \end{aligned}$$

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Optimal Choice of Attention Strategy

- Surplus must be maximized by correct assignments

$$\begin{aligned} G(\{a^1, b^1\}, \bar{\pi}^1) + G(\{a^2, b^2\}, \bar{\pi}^2) \\ \geq G(\{a^1, b^1\}, \bar{\pi}^2) + G(\{a^2, b^2\}, \bar{\pi}^1) \end{aligned}$$

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- Also, as π weakly Blackwell dominates $\bar{\pi}$

$$G(A^i, \bar{\pi}^j) \leq G(A^i, \pi^j)$$

- To guarantee the existence of a cost function requires a stronger condition

Condition 2 (No Improving Attention Cycles) For an observed sequence of decision problems $A^1 \dots A^K$ and associated revealed information structures $\bar{\pi}^1 \dots \bar{\pi}^K$

$$\begin{aligned} & G(A^1, \bar{\pi}^1) - G(A^1, \bar{\pi}^2) \\ & + G(A^2, \bar{\pi}^2) - G(A^2, \bar{\pi}^3) \\ & + \dots \\ & + G(A^K, \bar{\pi}^K) - G(A^K, \bar{\pi}^1) \\ \geq & 0 \end{aligned}$$

- Note that this condition relies only on observable objects

Theorem

For any data set $\{D, P\}$ the following two statements are equivalent

- ① $\{D, P\}$ satisfy NIAS and NIAC
- ② *There exists a $K : \Pi \rightarrow \mathbb{R}$, $\{\pi^A\}_{A \in D}$ and $\{C^A\}_{A \in D}$ such that π^A and $C^A : \Gamma(\pi^A) \rightarrow A$ are optimal and generate P^A for every $A \in D$*

Proof.

$2 \rightarrow 1$ Trivial

$1 \rightarrow 2$ Rochet [1987] (literature on implementation)



- This problem is familiar from the implementation literature
- Say there were a set of environments $X_1 \dots X_N$ and actions $B_1 \dots B_M$ such that the utility of each environment and each state is given by

$$u(X_i, B_j)$$

- Say we want to implement a mechanism such that action $Y(X_i)$ is taken at in each environment.
- We need to find a taxation scheme $\tau : B_1 \dots B_M \rightarrow \mathbb{R}$ such that

$$u(X_i, Y(X_i)) - \tau(Y(X_i)) \geq u(X_i, B) - \tau(B) \\ \forall B_1 \dots B_M$$

- This is the same as our problem.

- Our problem is equivalent to finding $\theta : D \rightarrow \mathbb{R}$, such that, for all $A_i, A_j \in D$

$$G(A_i, \pi^i) - \theta(A_i) \geq G(A_i, \pi^j) - \theta(A_j)$$

- Just define $K(\pi) = \theta(A_i)$ if $\pi = \pi^i$ for some i , or $= \infty$ otherwise
- We can apply a proof from Rockerfellar [1970] to show that NIAC gives us this condition

- Pick some arbitrary A_0 and define

$$T(A) = \sup_{\text{all chains } A_0 \text{ to } A=A_M} \sum_{n=0}^{M-1} G(A_{i+1}, \pi^i) - G(A_i, \pi^i)$$

- NIAC implies that $T(A_0) = 0$
- Also note that

$$T(A_0) \geq T(A_i) + G(A_0, \pi^i) - G(A_i, \pi^i)$$

- So $T(A_i)$ is bounded

- Furthermore, for any A_i, A_j we have

$$T(A_i) \geq T(A_j) + G(A_i, \pi^j) - G(A_j, \pi^j)$$

- So, setting $\theta(A_j) = G(A_j, \pi^j) - T(A_j)$, we get

$$G(A_i, \pi^j) - \theta(A_i) \geq G(A_i, \pi^j) - \theta(A_j)$$

Costs and Blackwell Ordering

- So far we have been completely agnostic about the cost function
- Perhaps we want to impose some more structure
 - e.g. information structure that are more (Blackwell) Informative are (weakly) more expensive
- Turns out we get this 'for free'
- Say we observe π^A in A and π^B in B such that π^A is sufficient for π^B
- It must be the case that

$$\begin{aligned} G(B, \pi^B) - K(\pi^B) &\geq G(B, \pi^A) - K(\pi^A) \Rightarrow \\ K(\pi^A) - K(\pi^B) &\geq G(B, \pi^A) - G(B, \pi^B) \end{aligned}$$

- But by Blackwell's theorem

$$G(B, \pi^A) \geq G(B, \pi^B)$$

Restrictions on the Cost Function

- Any behavior that can be rationalized can be rationalized with a cost function that
 - Is weakly monotonic with respect to Blackwell?
 - Allows mixing
 - Positive with free inattention
- Reminiscent of Afriat's theorem
- Can also extend to 'sequential rational inattention'

- Say $\bar{\pi}^A$ is the revealed attn. strategy in decision problem A .
- Assuming weak monotonicity, it must be that

$$K(\bar{\pi}^A) - K(\pi) \leq G(A, \bar{\pi}^A) - G(A, \pi)$$

- If $\bar{\pi}^B$ is used in decision problem B then we can bound relative costs

$$G(B, \bar{\pi}^A) - G(B, \bar{\pi}^B) \leq K(\bar{\pi}^A) - K(\bar{\pi}^B) \leq G(A, \bar{\pi}^A) - G(A, \bar{\pi}^B)$$

- Tighter bounds can be obtained using chains of observations

$$\begin{aligned} & \max_{\{A^1 \dots A^n \in D \mid A^1 = B, A^n = A\}} \sum \left[G(A^i, \bar{\pi}^{A^i}) - G(A^i, \bar{\pi}^{A^{i+1}}) \right] \\ & \leq K(\bar{\pi}^A) - K(\bar{\pi}^B) \\ & \leq \min_{\{A^1 \dots A^n \in D \mid A^1 = A, A^n = B\}} \sum \left[G(A^i, \bar{\pi}^{A^i}) - G(A^i, \bar{\pi}^{A^{i+1}}) \right] \end{aligned}$$

What If Utility and Priors Are Unobservable?

- Can add 'there exists' to the statement of the NIAS and NIAC conditions
- Data has an optimal costly attention representation if **there exists** $\mu \in \Delta(\Omega)$ and $U : X \rightarrow \mathbb{R}$ such that
 - NIAS is satisfied
 - NIAC is satisfied
- If μ is known but U is unknown, conditions are linear and (relatively) easy to check
- If μ and U are unknown, conditions are harder to check
 - Still not vacuous
- Alternatively, can enrich data so that these objects can be recovered

Rational Inattention vs Random Utility

- Alternative model of random choice: Random Utility
 - ① Agent receives some information about the state of the world
 - ② Draws a utility function from some set
 - ③ Chooses in order to maximize utility given information
- Key differences between Random Utility and Rational Inattention
 - ① Random Utility allows for multiple utility functions
 - ② Rational Inattention allows attention to vary with choice problem
- How can we differentiate between the two?

- Random Utility implies monotonicity
 - In fact, fully characterized by Block Marschak monotonicity
- For any two decision problems $\{A, A \cup b\}$, $a \in A$ and $b \notin A$

$$P_A(a|\omega) \geq P_{A \cup b}(a|\omega)$$

- Rational Inattention can lead to violations of monotonicity (Ergin, Matejka and McKay)

Act	Payoff 49 red dots	Payoff 51 red dots
a	23	23
b	20	25
c	40	0

- Adding act c to $\{a, b\}$ can increase the probability of choosing b in state 51

- Introduce an experimental interface that can be used to collect state dependent stochastic choice data
- Use it to perform some basic tests
 - Whether subjects actively adjust their attention
 - Whether they do so optimally
 - Measure attention costs
- Rule out alternative models with fixed attention
 - Signal Detection Theory
 - Random Utility Models

An Aside: Testing Axioms with Stochastic Data

- Much of the following is going to come down to testing axioms of the following form

$$P(a|1) \geq P(a|2)$$

- These are conditions on the **population** probabilities
- We don't observe these, instead we observe **sample** estimates $\bar{P}(a|1)$ and $\bar{P}(a|2)$
- What to do?

An Aside: Testing Axioms with Stochastic Data

- We can make **statistical statements** about the validity of the axioms
- But there are two ways to do this
 - ① Can we reject a **violation** of the axiom
 - i.e., is it the case that $\bar{P}(a|1) > \bar{P}(a|2)$ and we can reject the hypothesis that $P(a|1) = P(a|2)$ at (say) the 5% level
 - ② Can we find a **significant** violation of the axiom
 - i.e. is it the case that $\bar{P}(a|1) < \bar{P}(a|2)$ and we can reject the hypothesis that $P(a|1) = P(a|2)$ at (say) the 5% level
- (1) Is clearly a much tougher test than (2)
- If we have low power we will never be able to do (1)

- Experiment 1: Extensive Margin
- Experiment 2: Spillovers
- Experiment 3: Intensive Margin

Experiment 1: Extensive Margin

Table 1: Experiment 1				
Decision Problem	Payoffs			
	$U(a(1))$	$U(a(2))$	$U(b(1))$	$U(b(2))$
1	2	0	0	2
2	10	0	0	10
3	20	0	0	20
4	30	0	0	30

- Two equally likely states
- Two acts (a and b)
- Symmetric change in the value of making correct choice
- 46 subjects

- In the symmetric 2x2 case, NIAC and NIAS have specific forms
- NIAS:

$$P_A(a|\omega_1) \geq \max \{ \alpha P_A(a|\omega_2), \alpha P_A(a|\omega_2) + \beta \}, \quad (1)$$

where

$$\alpha = \frac{u(b(\omega_2)) - u(a(\omega_2))}{u(a(\omega_1)) - u(b(\omega_1))}$$
$$\beta = \frac{u(a(\omega_1)) + u(a(\omega_2)) - u(b(\omega_1)) - u(b(\omega_2))}{(u(a(\omega_1)) - u(b(\omega_1)))}$$

- In this case boils down to

$$P(a|\omega_1) \geq P(a|\omega_2)$$

- NIAC:

$$\Delta P(a|\omega_1) (\Delta (u(a(\omega_1)) - u(b(\omega_1)))) + \quad (2)$$

$$\Delta P(b|\omega_2) (\Delta (u(b(\omega_2)) - u(a(\omega_2)))) \quad (3)$$

$$\geq 0 \quad (4)$$

- In this case boils down to

$$\begin{aligned} & P_1(a|\omega_1) + P_1(b|\omega_2) \\ \leq & P_2(a|\omega_1) + P_2(b|\omega_2) \\ \leq & P_3(a|\omega_1) + P_3(b|\omega_2) \\ \leq & P_4(a|\omega_1) + P_4(b|\omega_2) \end{aligned}$$

Do People Optimally Adjust Attention?

- Alternative model: Choose optimally conditional on fixed signal
 - e.g. Signal detection theory [Green and Swets 1966]
- In general, choices can vary with incentives
 - Changes optimal choice in posterior state
- But not in this case
 - Optimal to choose a if $\gamma_1 > 0.5$, regardless of prize
- Change in choice between decision problems rules out Signal Detection Theory
 - Also rational inattention with fixed entropy

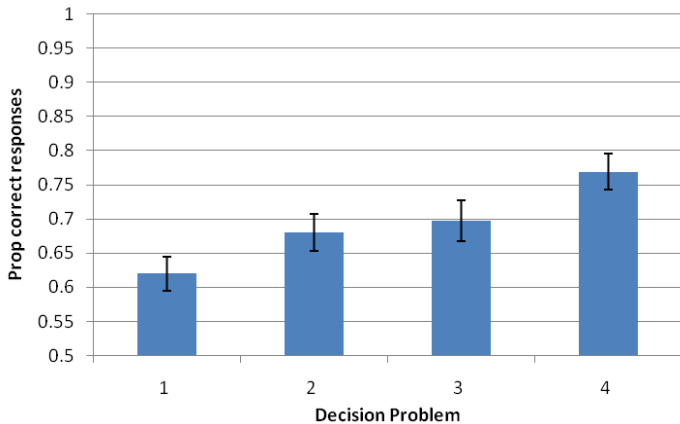
- NIAS test: For each decision problem

$$P(a|1) \geq P(a|2)$$

- From the aggregate data

Table 2: NIAS Test			
DP	$P_j(a 1)$	$P_j(a 2)$	Prob
1	0.71	0.48	0.000
2	0.75	0.39	0.000
3	0.76	0.37	0.000
4	0.80	0.29	0.000

Testing NIAC: Experiment 1



NIAC And NIAS: Individual Level

Violate	%
NIAS Only	0
NIAC Only	18
Both	2
Neither	80

- Counting only statistically significant violations

- From Theorem 1

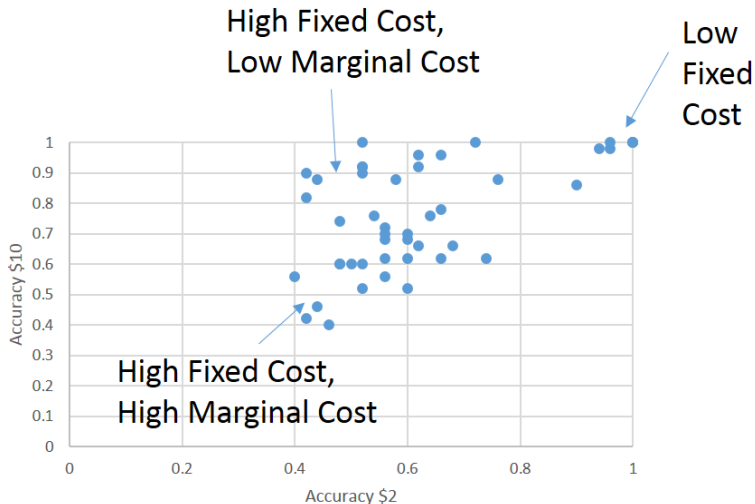
$$\begin{aligned} & G(A_i, \bar{\pi}^{A_j}) - G(A_j, \bar{\pi}^{A_j}) \\ \leq & K(\bar{\pi}^{A_i}) - K(\bar{\pi}^{A_j}) \leq \\ & G(A_j, \bar{\pi}^{A_j}) - G(A_i, \bar{\pi}^{A_j}) \end{aligned}$$

- Plugging in numbers from DP1 (\$2) and DP4 (\$30)

$$0.0014c \leq K(\bar{\pi}^{A_4}) - K(\bar{\pi}^{A_1}) \leq 0.0210c$$

- $K(\bar{\pi}^{A_4})$: 77% accuracy
- $K(\bar{\pi}^{A_1})$: 63% accuracy

Recovering Costs - Individual Level



Experiment 2: Spillovers

Table 2: Experiment 2

DP	Payoffs					
	U(a(1))	U(a(2))	U(b(1))	U(b(2))	U(c(1))	U(c(2))
5	23	23	20	25	n/a	n/a
6	23	23	20	25	30	10
7	23	23	20	25	35	5
8	23	23	20	25	40	0

Table 3			
DP	$P(b 1)$	$P(b 2)$	$P(c 1) - P(c 2)$
5	17%	23%	n/a
6	15%	31%	18%
7	12%	33%	18%
8	13%	39%	29%

- Random utility implies

$$P_5(b|2) \geq P_j(b|2) \text{ for } j \in \{6, 7, 8\}$$

- NIAC implies

$$P_8(c|1) - P_8(c|2) \geq P_7(c|1) - P_7(c|2) \geq P_6(c|1) - P_6(c|2).$$

Experiment 3: Intensive Margin

Experiment 3								
Decision Problem	Payoffs							
	U_1^a	U_2^a	U_3^a	U_4^a	U_1^b	U_2^b	U_3^b	U_4^b
9	1	0	10	0	0	1	0	10
10	10	0	1	0	0	10	0	1
11	1	0	1	0	0	1	0	1
12	10	0	10	0	0	10	0	10

- 4 states of the world: 29, 31, 69, 71 red balls
- Change which states it is important to differentiate between

Testing NIAC: Experiment 3

Experiment 3								
Decision Problem	Payoffs							
	U_1^a	U_2^a	U_3^a	U_4^a	U_1^b	U_2^b	U_3^b	U_4^b
9	1	0	10	0	0	1	0	10
10	10	0	1	0	0	10	0	1

- Comparing DP 9 and 10
 - DP9: important to differentiate between states 3 and 4
 - DP10: important to differentiate between states 1 and 2

$$\begin{aligned}
 & P_{10}(a|\omega_1) + P_{10}(b|\omega_2) + P_9(a|\omega_3) + P_9(b|\omega_4) \\
 \geq & P_9(a|\omega_1) + P_9(b|\omega_2) + P_{10}(a|\omega_3) + P_{10}(b|\omega_4)
 \end{aligned}$$

- Average LHS: 73%, Average RHS: 65% (24 subjects)
- Overall 79% of subjects in line of NIAC

- These are clearly extremely simple experimental tests
- A lot more work to be done
 - identifying where people are optimal and where they are not
 - identifying types of mistakes that they are making
 - measuring costs.

- There are lots of other papers testing the rational inattention hypothesis for specific cost functions:
 - Shannon mutual information (e.g. Sims 2003)
 - Shannon capacity (e.g. Woodford 2012)
 - Choice of optimal partitions (Ellis 2012)
 - All or nothing (Reis 2006)
- We will talk (in particular) about mutual information next week.

- One other paper considers optimal information acquisition without making any assumption about the cost functions
- Rather than state dependant stochastic choice data, uses preferences over menus
 - i.e would you prefer to make a choice for menu A or menu B
- Timeline is as follows
 - Choose between menu
 - State resolves itself
 - Choose what information processing to do
 - Choose an alternative based on signal

- Two key conditions for rational inattention

① Preference for Flexibility

- $A \cup \{a\} \succeq A$
- Always prefer to have more options
- Note relation to 'too much choice'

② Preference for Early Resolution of Uncertainty

- Define $\frac{1}{2}$ mixture of A and B as

$$\left\{ c = \frac{1}{2}a + \frac{1}{2}b \mid a \in A, b \in B \right\}$$

- Choosing from $\frac{1}{2}A + \frac{1}{2}B$ is like choosing from A , choosing from B then flipping a coin to see which choice you get
- This is costly from an informational standpoint

$$\begin{aligned} A &\sim B \Rightarrow \\ A &\succeq \frac{1}{2}A + \frac{1}{2}B \end{aligned}$$

- Introduced 'Rational Inattention'
 - A class of models in which it is costly to learn about the state of the world
- Introduced 'State Dependent Stochastic Choice data'
 - A handy data set for testing models of rational inattention
- Introduced an experimental method for collecting SDSC
- Very early stage in the research program, lots of open questions
 - Many other experiments to be run
 - SDSC data in the wild
 - Link between menu choice and stochastic choice