

$$\frac{d}{dt} \cos \omega t = -\omega \sin \omega t \quad \frac{d}{dt} \sin \omega t = \omega \cos \omega t$$

Thus $x(t) = A \cos(\omega t + \phi)$

where $\omega^2 = \frac{k}{m}$ and A & ϕ

are determined by the particle's initial position and velocity

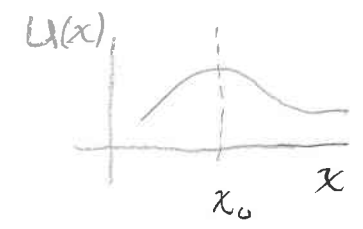
$$x(0) = A \cos \phi$$

$$\dot{x}(0) = -A \omega \sin \phi$$

$$A = \sqrt{x(0)^2 + \frac{1}{\omega^2} \dot{x}(0)^2} \quad \tan \phi = \frac{-\dot{x}(0)}{\omega x(0)}$$

- $|x(t)| \leq |A|$ so if A is small the particle will stay within the region where anharmonic terms in $U(x)$ can be neglected

- Not true for related motion about a maximum of $U(x)$:



$$U(x) = U(x_0) + \frac{dU}{dx}(x-x_0) + \frac{1}{2} \frac{d^2U}{dx^2}(x-x_0)^2 + \dots$$

$\nwarrow < 0$

Now we can choose

$$x_0 = 0, \quad U(x_0) = 0, \quad \kappa = -\frac{d^2U}{dx^2}(x_0) > 0$$

$$U(x) = -\frac{1}{2} \kappa x^2 + m \frac{d^2x}{dt^2} = +\kappa x$$

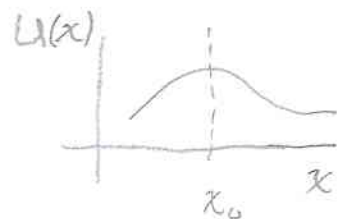
The opposite of a restoring force!

$$x(t) = a e^{+\sqrt{\kappa/m} t} + b e^{-\sqrt{\kappa/m} t}$$

or $= A \cosh(\sqrt{\kappa/m} t + \phi)$

Unless we can miraculously choose $a = 0$ exactly the particle will quickly leave the "harmonic" region

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2. Consider pendulum motion



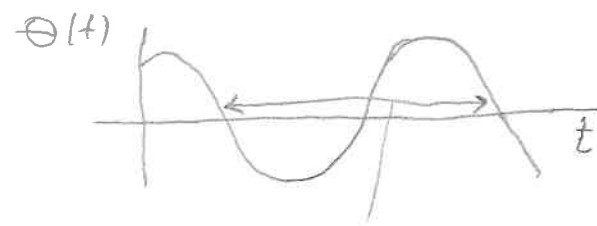
$$m l \ddot{\theta} = -mg \sin \theta$$

$$\theta - \frac{1}{3!} \theta^3 + \dots$$

$$\text{or } \ddot{\theta} \approx -\frac{g}{l} \theta$$

again oscillating about the minimum of the energy at $\theta=0$

$$\theta(t) = A \cos(\omega t + \phi) \quad \omega = \sqrt{\frac{g}{l}}$$

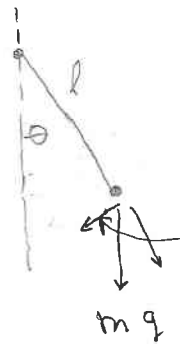


$$\text{period } T, \quad T\omega = 2\pi, \quad T = \frac{2\pi}{\omega}$$

Frequency ν is the number of cycles per unit time so

$$\nu T = 1 \quad \text{or } \nu = \frac{1}{T} = \frac{\omega}{2\pi}$$

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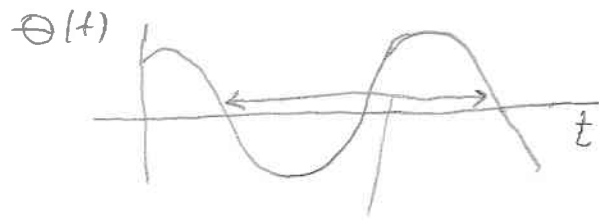
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3. Simple harmonic motion with complex numbers.

Our equation $m \frac{d^2 x}{dt^2} + kx = 0$

is an example of a linear ordinary differential equation with constant coefficients which should be easy to solve with a simple exponential:

$$x(t) = A e^{\lambda t}$$

$$m \lambda^2 A e^{\lambda t} + k A e^{\lambda t} = 0$$

Requires λ to be a root of the polynomial

$$m \lambda^2 + k = 0$$

an equation that can be solved only if we introduce complex numbers

$$\lambda = \pm \sqrt{-\frac{k}{m}} = \pm i \sqrt{\frac{k}{m}}$$

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numbers $\lambda = \pm \sqrt{-\frac{k}{m}} = \pm i \sqrt{\frac{k}{m}}$

where $i^2 = -1$

Expand the real numbers by including an extra element $i = \sqrt{-1}$.

A general complex number z

has the form $z = a + ib$

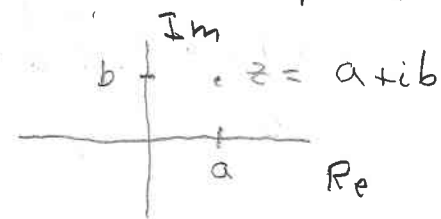
where for $z_1 = a_1 + ib_1$, $z_2 = a_2 + ib_2$

$$z_1 + z_2 = (a_1 + a_2) + i(b_1 + b_2)$$

and for real r , $r \cdot z = (ra) + i(rb)$

Thus, the complex numbers form a real, two-dimensional vector space

$$z = a + ib \equiv (a, b)$$



However, we can also multiply z_1, z_2

$$z_1 \cdot z_2 = (a_1 + ib_1)(a_2 + ib_2)$$

$$= a_1 a_2 - b_1 b_2 + i(b_1 a_2 + a_1 b_2)$$

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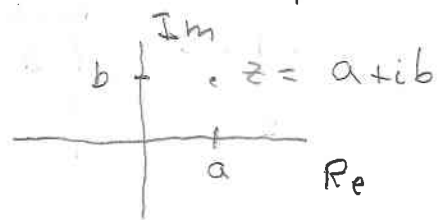
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With this multiplication law, the complex numbers form a field

$0 + i \cdot 0$ is the zero element

$1 + i \cdot 0$ is the unit element

$$0 + z = z, \quad 1 \cdot z = z, \quad 0 \cdot z = 0$$

and if $z \neq 0$, we can find $\frac{1}{z}$

obeying $z \cdot \frac{1}{z} = 1$ as follows:

if $z = a + ib$, define $z^* = a - ib$,

the "complex conjugate of z "

$$\text{Then } z z^* = (a + ib)(a - ib) = a^2 + b^2$$

$$\text{Use } \frac{1}{z} = \frac{z^*}{z z^*}$$

Other requirements of a field

$$z_1 \cdot z_2 = z_2 \cdot z_1, \quad z_1 \cdot (z_2 \cdot z_3) = (z_1 \cdot z_2) \cdot z_3$$

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If $z = a + ib$

$$\text{define } \operatorname{re}(z) \equiv a = \frac{z + z^*}{2}$$

$$\operatorname{im}(z) \equiv b = \frac{z - z^*}{2i}$$

Return to $m \frac{d^2 x}{dt^2} = -kx$ and $x(t) = A$

$$\text{and } x(t) = A e^{\pm i \sqrt{\frac{k}{m}} t}$$

?

$$\text{Define } e^z = 1 + z + \frac{1}{2} z^2 + \frac{1}{3!} z^3 + \dots$$

$$= \sum_{n=0}^{\infty} \frac{1}{n!} z^n$$

This must obey all of the properties of exponents of real numbers since both real and complex numbers add and multiply following the same rules

$$e^{z_1} e^{z_2} = e^{z_1 + z_2}, \quad \frac{1}{e^z} = e^{-z}$$

Note $e^z = e^{a+ib} = e^a e^{ib}$ (89)

so we need to figure out how to determine e^{ib} :

$$e^{ib} = \sum_{n=0}^{\infty} \frac{1}{n!} (ib)^n \quad \text{separate into even and odd powers}$$

$$= \underbrace{\sum_{n=0}^{\infty} \frac{1}{(2n)!} (-1)^n b^{2n}}_{\text{even powers} = \cos b} + i \underbrace{\sum_{n=0}^{\infty} \frac{1}{(2n+1)!} (-1)^n b^{2n+1}}_{\text{odd powers} = \sin b}$$

or $e^{ib} = \cos b + i \sin b$

$$|z|^2 = e^{ib} e^{-ib} = \cos^2 b + \sin^2 b = 1$$

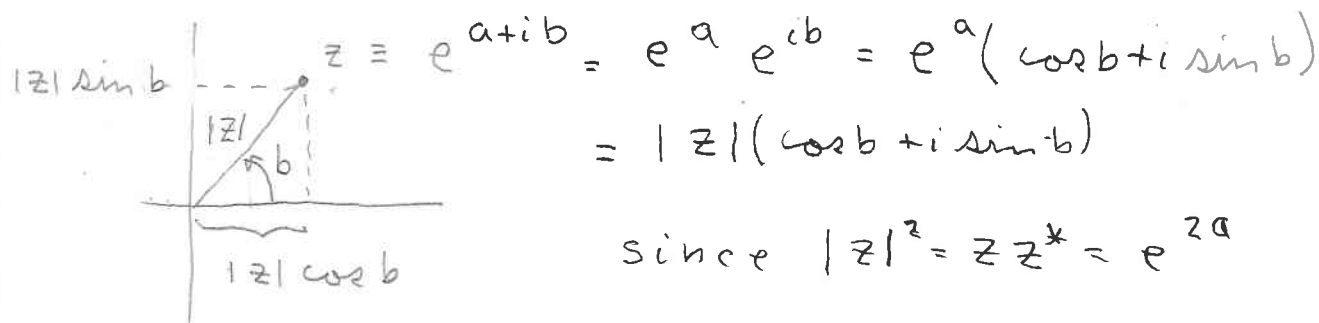
$$e^{i(\theta+\phi)} = e^{i\theta} e^{i\phi}$$

$$\cos(\theta+\phi) + i \sin(\theta+\phi) = (\cos\theta + i \sin\theta)(\cos\phi + i \sin\phi)$$

$$= \cos\theta \cos\phi - \sin\theta \sin\phi$$

$$\cos(\theta+\phi) \quad \checkmark \quad + i (\underbrace{\sin\theta \cos\phi + \cos\theta \sin\phi}_{\sin(\theta+\phi)} \quad \checkmark$$

Viewed in 2-dim plot



$$= |z| (\cos b + i \sin b)$$

$$\text{since } |z|^2 = z z^* = e^{2a}$$

$$z_1 z_2 = |z_1| e^{i\theta_1} |z_2| e^{i\theta_2} = |z_1| |z_2| e^{i\theta_1 + \theta_2}$$

"multiply the magnitudes and add the angles"

4. Apply to damped simple harmonic motion.

Introduce a viscous or damping force proportion to the velocity

$$F_{\text{fric}} = -\sigma \frac{dx}{dt}$$

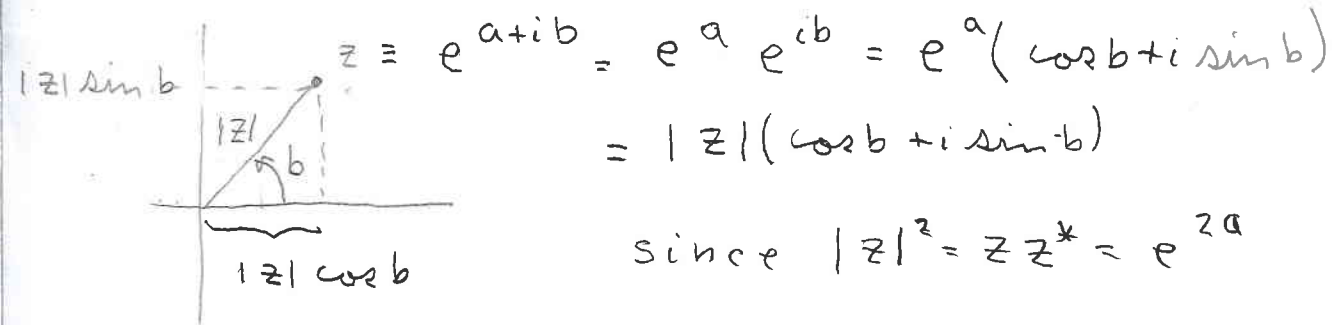
so

$$m \frac{d^2 x}{dt^2} = -\sigma \frac{dx}{dt} - kx$$

easily solved with complex numbers

(90)

Viewed in 2-dim plot



$$= |z|(\cos b + i \sin b)$$

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$$z_1 z_2 = |z_1| e^{i\theta_1} |z_2| e^{i\theta_2}$$

$$= |z_1| |z_2| e^{i\theta_1 + i\theta_2}$$

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$$m \frac{d^2x}{dt^2} = -\sigma \frac{dx}{dt} - kx \quad \text{easily solved with complex numbers}$$

(91)

Start with

$$m \frac{d^2x}{dt^2} + \sigma \frac{dx}{dt} + kx = 0 \quad \text{try } x(t) = A e^{\lambda t}$$

$$m \lambda^2 A e^{\lambda t} + \sigma \lambda A e^{\lambda t} + k A e^{\lambda t} = 0$$

$$\text{or } m \lambda^2 + \sigma \lambda + k = 0$$

$$\lambda^2 + \underbrace{\frac{\sigma}{m}}_{\gamma} \lambda + \underbrace{\frac{k}{m}}_{\omega_0^2} = 0$$

$$\lambda = \frac{-\gamma \pm \sqrt{\gamma^2 - 4\omega_0^2}}{2} = -\frac{\gamma}{2} \pm \sqrt{\left(\frac{\gamma}{2}\right)^2 - \omega_0^2}$$

Thus a general solution is

$$x(t) = A e^{-\frac{\gamma}{2}t} e^{+\sqrt{\left(\frac{\gamma}{2}\right)^2 - \omega_0^2}t} + B e^{-\frac{\gamma}{2}t} e^{-\sqrt{\left(\frac{\gamma}{2}\right)^2 - \omega_0^2}t}$$

- Since the equation is linear in $x(t)$ we can add two solutions and will still have a solution.
- While A & B may be complex since the equation has real coefficients, $x^*(t)$ will be a solution and $x(t) + x^*(t)$ a real solution