

6. Easy to transform velocities

(120)



Look at two events in Σ' along the particles trajectory:

$$(x'_1, t'_1) \text{ \& } (x'_1 + u'(t'_2 - t'_1), t'_2)$$

$$x_1 = \gamma(x'_1 + vt'_1) \quad x_2 = \gamma[x'_1 + u'(t'_2 - t'_1) + vt'_2]$$

$$t_1 = \gamma(t'_1 + \frac{v}{c^2}x'_1) \quad t_2 = \gamma[t'_2 + \frac{v}{c^2}(x'_1 + u'(t'_2 - t'_1))]$$

$$u = \frac{x_2 - x_1}{t_2 - t_1} = \frac{\gamma[u'(t'_2 - t'_1) + v(t'_2 - t'_1)]}{\gamma[t'_2 - t'_1 + \frac{vu'}{c^2}(t'_2 - t'_1)]}$$

$$\text{or } u = \frac{u' + v}{1 + \frac{vu'}{c^2}}$$

$$\text{as } u' \rightarrow c \quad u \rightarrow \frac{c + v}{1 + \frac{v}{c}} = c$$

$$\text{as } v \rightarrow c \quad u \rightarrow \frac{u' + c}{1 + \frac{u'}{c}} = c$$

October 29, 2020

(121)

8. Introduce 4x4 Lorentz transformation matrices

Use coordinates (x, y, z, ct) so they all have the same units

$$x = \gamma(x' + \frac{v}{c}ct')$$

$$ct = \gamma(ct' + \frac{v}{c}x') \quad \text{or} \quad \begin{pmatrix} x \\ ct \end{pmatrix} = \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} x' \\ ct' \end{pmatrix}$$

$$\beta = \frac{v}{c}, \quad \gamma = \frac{1}{\sqrt{1 - \beta^2}}$$

$\beta' = -\beta$ should be the inverse

$$x' = \gamma(x - \beta ct)$$

$$ct' = \gamma(ct - \beta x) \quad \begin{pmatrix} x' \\ ct' \end{pmatrix} = \begin{pmatrix} \gamma & -\beta\gamma \\ -\beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} x \\ ct \end{pmatrix}$$

check

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \stackrel{?}{=} \begin{pmatrix} \gamma & -\beta\gamma \\ -\beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix}$$

$$= \begin{pmatrix} \gamma^2 - \beta^2\gamma^2 & 0 \\ 0 & \gamma^2 - \beta^2\gamma^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\gamma^2(1 - \beta^2) = 1 \quad \text{since } \gamma^2 = \frac{1}{1 - \beta^2}$$

8. Introduce 4x4 Lorentz transformation matrices

Use coordinates (x, y, z, ct) so they all have the same units

$$x = \gamma(x' + \frac{v}{c} ct')$$

$$ct = \gamma(ct' + \frac{v}{c} x')$$

or
$$\begin{pmatrix} x \\ ct \end{pmatrix} = \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} x' \\ ct' \end{pmatrix}$$

$$\beta = \frac{v}{c}, \quad \gamma = \frac{1}{\sqrt{1-\beta^2}}$$

$\beta' = -\beta$ should be the inverse

$$x' = \gamma(x - \beta ct)$$

$$ct' = \gamma(ct - \beta x)$$

or
$$\begin{pmatrix} x' \\ ct' \end{pmatrix} = \begin{pmatrix} \gamma & -\beta\gamma \\ -\beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} x \\ ct \end{pmatrix}$$

check

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \stackrel{?}{=} \begin{pmatrix} \gamma & -\beta\gamma \\ -\beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix}$$

$$= \begin{pmatrix} \gamma^2 - \beta^2\gamma^2 & 0 \\ 0 & \gamma^2 - \beta^2\gamma^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\gamma^2(1-\beta^2) = 1 \quad \text{since} \quad \gamma^2 = \frac{1}{1-\beta^2}$$

Extend to four dimensions

$$\begin{pmatrix} x \\ y \\ z \\ ct \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & \beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \beta\gamma & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} x' \\ y' \\ z' \\ ct' \end{pmatrix}$$

Such a change in velocity is called a "boost".

We can combine with a rotation

$$\begin{pmatrix} x \\ y \\ z \\ ct \end{pmatrix} = \begin{pmatrix} R_{11} & R_{12} & R_{13} & 0 \\ R_{21} & R_{22} & R_{23} & 0 \\ R_{31} & R_{32} & R_{33} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x' \\ y' \\ z' \\ ct' \end{pmatrix}$$

to obtain a general Lorentz transformation matrix L

where

$$x_\mu = \sum_{\nu=1}^4 L_{\mu\nu} x'_\nu$$

with $x_4 = ct$ and $x'_4 = ct'$

x_μ and x'_μ are components of four-vectors

Extend to four dimensions

$$\begin{pmatrix} x \\ y \\ z \\ ct \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & \beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \beta\gamma & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} x' \\ y' \\ z' \\ ct' \end{pmatrix}$$

Such a change in velocity is called a "boost".

We can combine with a rotation

$$\begin{pmatrix} x \\ y \\ z \\ ct \end{pmatrix} = \begin{pmatrix} R_{11} & R_{12} & R_{13} & 0 \\ R_{21} & R_{22} & R_{23} & 0 \\ R_{31} & R_{32} & R_{33} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x' \\ y' \\ z' \\ ct' \end{pmatrix}$$

to obtain a general Lorentz transformation matrix L

where

$$x_\mu = \sum_{\nu=1}^4 L_{\mu\nu} x'_\nu$$

with $x_4 = ct$ and $x'_4 = ct'$

x_μ and x'_μ are components of four-vectors

9. Invariant length

Illustrate by ignoring y & z and using two dimensions

• Rotations: consider vectors \vec{A} & \vec{B}

$$\vec{A} = a_1 \hat{e}_1 + a_2 \hat{e}_2 = a'_1 \hat{e}'_1 + a'_2 \hat{e}'_2$$

$$\vec{B} = b_1 \hat{e}_1 + b_2 \hat{e}_2 = b'_1 \hat{e}'_1 + b'_2 \hat{e}'_2$$

use $A = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \quad A^t = (a_1, a_2)$

$$B = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \quad B^t = (b_1, b_2)$$

then $\vec{B} \cdot \vec{A} = B^t A$

$$= \begin{pmatrix} b_1 & b_2 \end{pmatrix}_{1 \times 2} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}_{2 \times 1} = b_1 a_1 + b_2 a_2$$

$$a'_i = \sum_{j=1}^2 M_{ij} a_j \quad \& \quad b'_i = \sum_j (M^t)_{ji} b_j$$

$$A' = M A$$

2x1 2x2 2x1

$$B' = B M^t$$

1x2 1x2 2x2

$$\vec{B}' \cdot \vec{A}' = (B')^t \cdot A' = \underbrace{B^t M^t}_{(B')^t} \underbrace{M A}_{A'}$$

9. Invariant length

Illustrate by ignoring y & z and using two dimensions

• Rotations: consider vectors \vec{A} & \vec{B}

$$\vec{A} = a_1 \hat{e}_1 + a_2 \hat{e}_2 = a'_1 \hat{e}'_1 + a'_2 \hat{e}'_2$$

$$\vec{B} = b_1 \hat{e}_1 + b_2 \hat{e}_2 = b'_1 \hat{e}'_1 + b'_2 \hat{e}'_2$$

use $A = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$ $A^t = (a_1, a_2)$

$$B = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \quad B^t = (b_1, b_2)$$

then $\vec{B} \cdot \vec{A} = B^t A$

$$= \underset{1 \times 2}{(b_1, b_2)} \underset{2 \times 1}{\begin{pmatrix} a_1 \\ a_2 \end{pmatrix}} = \underset{1 \times 2}{b_1 a_1 + b_2 a_2} \underset{1 \times 1}{1}$$

$$a'_i = \sum_{j=1}^2 M_{ij} a_j \quad \& \quad b'_i = \sum_j (M^t)_{ji} b_j$$

$$A' = \underset{2 \times 1}{M} \underset{2 \times 2}{A}$$

$$B' = \underset{1 \times 2}{B} \underset{2 \times 2}{M^t}$$

$$\vec{B}' \cdot \vec{A}' = (B')^t \cdot A' = \underbrace{B^t M^t}_{(B')^t} \underbrace{M A}_{A'}$$

Since $b'_1 a'_1 + b'_2 a'_2 = b_1 a_1 + b_2 a_2$

$$B'^t A' = B^t \underbrace{M^t M}_{\text{must} = I} A$$

$$M^t M = I \Rightarrow M^t = M^{-1} \text{ our old}$$

result that rotation matrices are orthogonal $\equiv M^t = M^{-1}$

• Boosts $L = \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \quad L^{-1} = \begin{pmatrix} \gamma & -\beta\gamma \\ -\beta\gamma & \gamma \end{pmatrix}$

$$L^t \neq L^{-1}$$

Introduce a new dot product

$$(B, A)_M \equiv \sum_{ij} B_i g_{ij} A_j = B^t G A$$

where $G = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$ g_{ij} is the metric tensor

require $(B, A) = (B', A')$

$$\underbrace{B^t}_{B'^t} \underbrace{G}_{L^t G L} \underbrace{A}_{L A'} = (B')^t G A'$$

requires $L^t G L = G$ } instead of $L^t L = I$

since $b_1 a_1 + b_2 a_2 = b_1 a_1 + b_2 a_2$ (124)

$$B'^t A' = B^t \underbrace{M^t M}_{\text{must} = I} A$$

$M^t M = I \Rightarrow M^t = M^{-1}$ our old result that rotation matrices are orthogonal $\equiv M^t = M^{-1}$

• Boosts $L = \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \quad L^{-1} = \begin{pmatrix} \gamma & -\beta\gamma \\ -\beta\gamma & \gamma \end{pmatrix}$

$$L^t \neq L^{-1}$$

Introduce a new dot product

$$(B, A)_M \equiv \sum_{ij} B_i g_{ij} A_j = B^t G A$$

where $G = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$ g_{ij} is the metric tensor

require $(B, A) = (B', A')$

$$\underbrace{B^t}_{B'^t L^t} G \underbrace{A}_{L A'} = (B')^t G A' \quad \left\{ \begin{array}{l} \text{instead of} \\ \text{requires } L^t G L = G \\ L^t L = I \end{array} \right.$$

$$G = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \text{Minkowski metric} \quad (125)$$

works!

$$\begin{aligned} \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} &= \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} \gamma & \beta\gamma \\ -\beta\gamma & -\gamma \end{pmatrix} \\ L^t \quad G \quad L^t & \\ &= \begin{pmatrix} \gamma^2 - \beta^2 \gamma^2 & 0 \\ 0 & \beta^2 \gamma^2 - \gamma^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = G \end{aligned}$$

The metric g_{ij} is not changed by Lorentz transformation

$$\gamma^2 - \beta^2 \gamma^2 = 1 \quad \Rightarrow \quad \gamma = \frac{\cosh w}{\frac{e^w + e^{-w}}{2}} \quad \beta\gamma = \frac{\sinh w}{\frac{e^w - e^{-w}}{2}}$$

Thus, we change to a moving system the Minkowski length does not change

$$x_M^2 = (x, ct) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ ct \end{pmatrix} = x^2 - ct^2$$

$$G = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \text{Minkowski metric} \quad (125)$$

works!

$$\begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} = \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} \gamma & \beta\gamma \\ -\beta\gamma & -\gamma \end{pmatrix}$$

$$\begin{matrix} L^t & & G & & L^t \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{matrix} = \begin{pmatrix} \gamma^2 - \beta^2\gamma^2 & 0 \\ 0 & \beta^2\gamma^2 - \gamma^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = G^v$$

The metric g_{ij} is not changed by Lorentz transformation

$$\gamma^2 - \beta^2\gamma^2 = 1 \quad \Rightarrow \quad \gamma = \frac{\cosh w}{\frac{e^w + e^{-w}}{2}} \quad \beta\gamma = \frac{\sinh w}{\frac{e^w - e^{-w}}{2}}$$

Thus, we change to a moving system the Minkowski length does not change

$$x_M^2 = (x, ct) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ ct \end{pmatrix} = x^2 - ct^2$$

Try it out

$$\begin{aligned} x^2 - c^2 t^2 &= (\gamma x' + \gamma v t')^2 - c^2 (\gamma t' + \gamma \frac{v}{c^2} x')^2 \\ &= x'^2 \left[\gamma^2 - \frac{v^2}{c^2} \gamma^2 \right] - c^2 t'^2 \left[\gamma^2 - \frac{v^2}{c^2} \gamma^2 \right] \\ &= x'^2 - c^2 t'^2 \quad \checkmark \end{aligned}$$

In four dimension

$$\begin{pmatrix} \gamma & 0 & 0 & \beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \beta\gamma & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} \gamma & 0 & 0 & \beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \beta\gamma & 0 & 0 & \gamma \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

If a and b are four vectors locating two events, then the invariant distance between $x \neq y$

$$(a-b)^2 = (x_a - x_b)^2 + (y_a - y_b)^2 + (z_a - z_b)^2 - c^2 (t_a - t_b)^2$$

will be the same in all systems!

Try it out

$$\begin{aligned}
x^2 - c^2 t^2 &= (\gamma x' + \gamma v t')^2 - c^2 (\gamma t' + \gamma \frac{v}{c^2} x')^2 \\
&= x'^2 [\gamma^2 - \frac{v^2}{c^2} \gamma^2] - c^2 t'^2 [\gamma^2 - \frac{v^2}{c^2} \gamma^2] \\
&= x'^2 - c^2 t'^2 \quad \checkmark
\end{aligned}$$

In four dimension

$$\begin{pmatrix} \gamma & 0 & 0 & \beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \beta\gamma & 0 & 0 & \gamma \end{pmatrix}
\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}
\begin{pmatrix} \gamma & 0 & 0 & \beta\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \beta\gamma & 0 & 0 & \gamma \end{pmatrix}
=
\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

If a and b are four vectors locating two events, then the invariant distance between x and y

$$(a-b)^2 = (x_a - x_b)^2 + (y_a - y_b)^2 + (z_a - z_b)^2 - c^2 (t_a - t_b)^2$$

will be the same in all systems!

Much more interesting than the Euclidean - three kinds of separations

- ① $(a-b)^2 > 0$ a and b are space-like
(time order can change)
- ② $(a-b)^2 = 0$ a and b are light-like
(light can go from a to b)
- ③ $(a-b)^2 < 0$ a and b are time-like
(time order cannot be reversed)

Proof (Use $\vec{v} \parallel \hat{i}$)

$$\begin{aligned}
\Delta t &= t_a - t_b = \gamma(t'_a + \frac{v}{c^2} x'_a) - \gamma(t'_b + \frac{v}{c^2} x'_b) \\
&= \frac{\gamma}{c} [c \Delta t' + \beta \Delta x']
\end{aligned}$$

Much more interesting than the Euclidean - three kinds of separations

- ① $(a-b)^2 > 0$ a and b are space-like
(time order can change)
- ② $(a-b)^2 = 0$ a and b are light-like
(light can go from a to b)
- ③ $(a-b)^2 < 0$ a and b are time-like
(time order cannot be reversed)

Proof (Use $\vec{v} \parallel \hat{i}$)

$$\begin{aligned} \Delta t &= t_a - t_b = \gamma(t'_a + \frac{v}{c^2} x'_a) - \gamma(t'_b + \frac{v}{c^2} x'_b) \\ &= \frac{\gamma}{c} [c \Delta t' + \beta \Delta x'] \end{aligned}$$

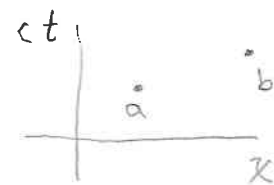
Examine

- ① a & b space-like

$$0 < (a-b)^2 = (x'_a - x'_b)^2 - c^2 (t'_a - t'_b)^2$$

$$\Rightarrow |x'_a - x'_b| > c |t'_a - t'_b|$$

and $\beta \Delta x'$ term can change the sign of $c \Delta t'$ term. Events a & b cannot be causally connected



$|\Delta x| > c |\Delta t| \Rightarrow$ not enough time for light to go from x_a to x_b

No information carrying signal can travel faster than light!

- ② a & b light-like

$$0 = (a-b)^2 = \Delta x^2 - c^2 \Delta t^2$$

$|\Delta x| = c \Delta t$ and light emitted by a can reach b time order can't be changed.

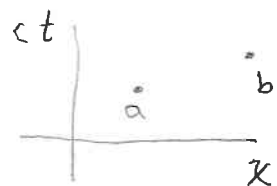
Examine

① a & b space-like

$$0 < (a-b)^2 = (x'_a - x'_b)^2 - c^2(t'_a - t'_b)^2$$

$$\Rightarrow |x'_a - x'_b| > c|t'_a - t'_b|$$

and $\beta \Delta x'$ term can change the sign of $c \Delta t'$ term. Events a & b cannot be causally connected



$|\Delta x| > c|\Delta t| \Rightarrow$ not enough time for light to go from x_a to x_b

No information carrying signal can travel faster than light!

② a & b light-like

$$0 = (a-b)^2 = \Delta x^2 - c^2 \Delta t^2$$

$|\Delta x| = c \Delta t$ and light emitted

by a can reach b time order can't be changed.

③ a and b time-like

$$0 > (a-b)^2 = (\Delta x')^2 - c^2(\Delta t)^2$$

$$|\Delta t| > \frac{1}{c} |\Delta x|$$

enough time for a signal slower than light to reach b from a

$$c \Delta t = \gamma (c |\Delta t'| + \beta |\Delta x'|)$$

$\beta |\Delta x'|$ term cannot change time order, a & b can be causally connected



- ① ACME acausal alarm company sees robbery underway at 1 AM
- ② send superluminal signal which reaches Police before 1 AM
- ③ quick acting police send super-luminal signal to patrol car.
- ④ robber arrested before crime

3 a and b time-like

$$0 > (a-b)^2 = (\Delta x')^2 - c^2(\Delta t)^2$$

$$|\Delta t| > \frac{1}{c} |\Delta x|$$

enough time for a signal slower than light to reach b from a

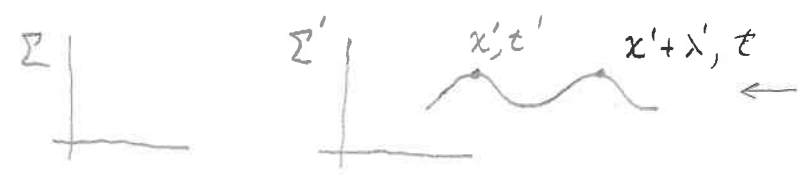
$$c\Delta t = \gamma(c|\Delta t'| + \beta|\Delta x'|)$$

$\beta|\Delta x'|$ term cannot change time order, a & b can be causally connected



- ① ACME acausal alarm company sees robbery underway at 1 AM
- ② send superluminal signal which reaches Police before 1 AM
- ③ quick acting police send super-luminal signal to patrol car.
- ④ robber arrested before crime

10. Doppler effect for light



Σ' labels these two events

$$x_1 = \gamma(x' + vt'), \quad t_1 = \gamma(t' + \frac{v}{c^2}x')$$

$$x_2 = \gamma(x' + \lambda' + vt'), \quad t_2 = \gamma(t' + \frac{v}{c^2}(x' + \lambda'))$$

$$\lambda = x_2 - x_1 + \underbrace{c(t_2 - t_1)}$$

since wave moved to the left by this amount between two measurements

$$= \gamma\lambda' + c\gamma\frac{v}{c^2}\lambda' = \frac{1}{\sqrt{1-v^2/c^2}} \lambda' (1 + \frac{v}{c})$$

$$= \sqrt{\frac{1+v/c}{1-v/c}} \lambda'$$

wave length of light from receding star is longer, $\lambda v = c \Rightarrow v$ smaller explains "red shift"