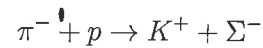


Final Exam

(F1)

1. A π^- meson strikes a proton and creates a K^+ meson and a Σ^- baryon:



The masses of these particles are $m_{\pi^-} = 140$, $m_p = 938$, $m_{\Sigma^-} = 1116$ and $m_{K^+} = 494$ all in units of MeV/c^2 . What minimum laboratory energy is required for the incoming π^- if the reaction is to take place? (The numerical values for the masses are provided for context. Only an algebraic solution is needed.) [20 points]

Use momentum fourvectors for each particle.

- four vectors for initial particles easy in lab system

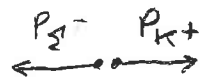
$$P_{\pi} = (m_{\pi} v \gamma_v, 0, 0, m_{\pi} c \gamma_v) \quad \text{choose } \hat{x} \parallel \vec{P}_{\pi}$$

$$P_p = (0, 0, 0, m_p c)$$

- four vectors for final particles easy in cm system.

$$P_{\Sigma^-} = (0, 0, 0, m_{\Sigma} c) \quad P_{K^+} = (0, 0, 0, m_K c)$$

(smallest total energy result when relative Σ^- & K^+ momentum in cm is zero



#1 continued

(F2)

Strategy since $P_{\pi} + P_p = P_{\Sigma} + P_K$

Their invariant lengths must be equal, and since they are frame-invariant they can be computed in different frames.

$$\begin{aligned} (P_{\pi} + P_p)^2 &= P_{\pi}^2 + P_p^2 + 2P_{\pi} \cdot P_p \\ &= -m_{\pi}^2 c^2 - m_p^2 c^2 - 2 \underbrace{m_{\pi} \gamma_v c}_{E_{\pi}/c} m_p c \end{aligned}$$

$$(P_{\Sigma} + P_K)^2 = -(m_{\Sigma} + m_K)^2 c^2$$

$$m_{\pi}^2 c^2 + m_p^2 c^2 + 2E_{\pi} m_p = (m_{\Sigma} + m_K)^2 c^2$$

$$E_{\pi} = \frac{(m_{\Sigma} + m_K)^2 c^2 - m_{\pi}^2 c^2 - m_p^2 c^2}{2m_p}$$

Intended to be an easy 20 points.

(F2)

#1 continued

Strategy since $P_\pi + P_p = P_\Sigma + P_K$
 Their invariant lengths must be equal,
 and since they are frame-invariant
 they can be computed in different frames.

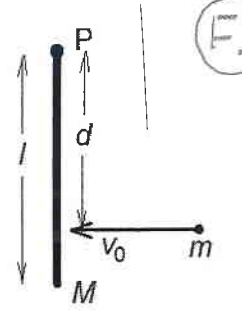
$$\begin{aligned} \bullet (P_\pi + P_p)^2 &= P_\pi^2 + P_p^2 + 2P_\pi \cdot P_p \\ &= -m_\pi^2 c^2 - m_p^2 c^2 - 2 \underbrace{m_\pi \gamma v}_E \cdot c \cdot m_p c \end{aligned}$$

$$\begin{aligned} \bullet (P_\Sigma + P_K)^2 &= -(m_\Sigma + m_K)^2 c^2 \\ m_\pi^2 c^2 + m_p^2 c^2 + 2E_\pi m_p &= (m_\Sigma + m_K)^2 c^2 \\ E_\pi &= \frac{(m_\Sigma + m_K)^2 c^2 - m_\pi^2 c^2 - m_p^2 c^2}{2m_p} \end{aligned}$$

Intended to be an easy 20 points.

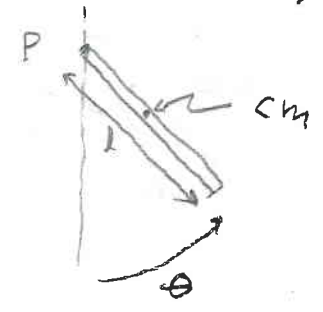
(F3)

2. A thin rod of length l and mass M swings without friction from a fixed pivot P . Initially the rod is vertical and at rest. A second small mass m moving horizontally to the left with velocity v_0 collides elastically with the rod at a distance d below P . After the collision m again moves horizontally but now to the right with velocity v' . The rod is initially at rest but immediately after the collision rotates around P with angular velocity Ω_0 .



- (a) The hanging rod can be described as a physical pendulum. Find the oscillation frequency of this pendulum in the small angle approximation. [5 points]
- (b) Find Ω_0 and v' . [25 points]
- (c) If θ is the angle between the rod and the vertical direction defined so that $\theta = 0$ before the collision, find the maximum value of θ during the subsequent motion. [5 points]
- (d) How long after the collision does θ first reach this maximum value? [5 points]

a) Standard "physical" pendulum problem

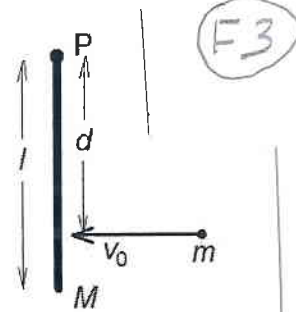


$$\begin{aligned} I_P \ddot{\theta} &= -Mg \frac{l}{2} \sin \theta \approx -Mg \frac{l}{2} \theta \\ \ddot{\theta} &= - \underbrace{\frac{Mgl}{2I}}_{\omega^2} \theta \end{aligned}$$

$$\begin{aligned} I_P &= I_{\text{about cm}} + I_{\text{cm about P}} \\ &= \frac{1}{12} Ml^2 + M \left(\frac{l}{2} \right)^2 = \frac{1}{3} Ml^2 \end{aligned}$$

$$\omega = \sqrt{\frac{Mgl}{2} \cdot \frac{3}{Ml^2}} = \sqrt{\frac{3g}{2l}}$$

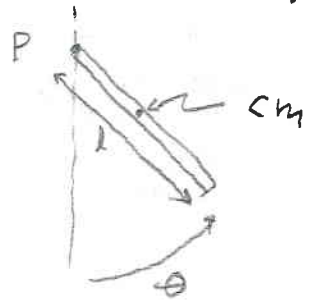
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F3

- (a) The hanging rod can be described as a physical pendulum. Find the oscillation frequency of this pendulum in the small angle approximation. [5 points]
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- (d) How long after the collision does θ first reach this maximum value? [5 points]

a) Standard "physical" pendulum problem



$$I_P \ddot{\theta} = -Mg \frac{l}{2} \sin \theta \approx -Mg \frac{l}{2} \theta$$

$$\ddot{\theta} = - \frac{Mgl}{2I} \theta = -\omega^2 \theta$$

$$I_P = I_{\text{about cm}} + I_{\text{cm about P}} = \frac{1}{12} Ml^2 + M \left(\frac{l}{2} \right)^2 = \frac{1}{3} Ml^2$$

$$\omega = \sqrt{\frac{Mgl}{2} \cdot \frac{3}{Ml^2}} = \sqrt{\frac{3g}{2l}}$$

#2 continued

F4

b) Conservation of angular momentum

$$mvd = mv'd + I\Omega_0 \rightarrow v - v' = \frac{I\Omega_0}{md} \quad \text{(A)}$$

Conservation of energy

$$\frac{1}{2}mv^2 = \frac{1}{2}mv'^2 + \frac{1}{2}I\Omega_0^2$$

Two equations and two unknowns, easiest to divide:

$$\frac{mv^2 - mv'^2}{mv d - mv' d} = \frac{I\Omega_0^2}{I\Omega_0} \rightarrow \frac{v+v'}{d} = \Omega_0 \quad \text{(B)}$$

add $\frac{A}{d} + B$: $\frac{2v}{d} = \left[\frac{I}{md^2} + 1 \right] \Omega_0$

$$\Omega_0 = \frac{2v}{d} \frac{1}{1 + \frac{1}{3} \frac{M}{m} \left(\frac{l}{d} \right)^2} \quad \text{(C)}$$

substitute C into B

$$v' = -v + \frac{2v}{1 + \frac{1}{3} \frac{M}{m} \left(\frac{l}{d} \right)^2} = \frac{-1 + \frac{1}{3} \frac{M}{m} \left(\frac{l}{d} \right)^2}{1 + \frac{1}{3} \frac{M}{m} \left(\frac{l}{d} \right)^2} v$$

c) $\theta(t) = A \sin \omega t$ $\dot{\theta}(0) = \frac{\omega A \cos(0)}{\Omega_0}$

$$\theta_{\text{max}} = A = \Omega_0 / \omega$$

d) time = $\frac{2}{4} = \frac{1}{4} \frac{2\pi}{\omega} = \frac{\pi}{2} \sqrt{\frac{2l}{3g}}$

#2 continued

(F4)

b) Conservation of angular momentum

$$mvd = mv'd + I\Omega_0 \rightarrow v - v' = \frac{I\Omega_0}{md} \quad (A)$$

Conservation of energy

$$\frac{1}{2}mv^2 = \frac{1}{2}mv'^2 + \frac{1}{2}I\Omega_0^2$$

Two equations and two unknowns, easiest to divide:

$$\frac{mv^2 - mv'^2}{mvd - mv'd} = \frac{I\Omega_0^2}{I\Omega_0} \rightarrow \frac{v+v'}{d} = \Omega_0 \quad (B)$$

add $\frac{A}{d} + B$: $\frac{2v}{d} = \left[\frac{I}{md^2} + 1 \right] \Omega_0$

$$\Omega_0 = \frac{2v}{d} \frac{1}{1 + \frac{1}{3} \frac{M}{m} \left(\frac{l}{d}\right)^2} \quad (C)$$

substitute C into B

$$v' = -v + \frac{2v}{1 + \frac{1}{3} \frac{M}{m} \left(\frac{l}{d}\right)^2} = \frac{-1 + \frac{1}{3} \frac{M}{m} \left(\frac{l}{d}\right)^2}{1 + \frac{1}{3} \frac{M}{m} \left(\frac{l}{d}\right)^2} v$$

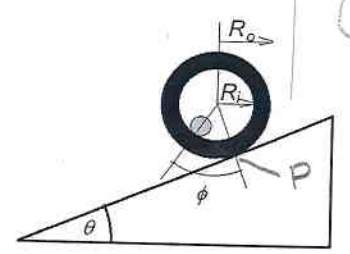
c) $\Theta(t) = A \sin \omega t$ $\dot{\Theta}(0) = \frac{\omega A \cos(0)}{\Omega_0}$

$$\Theta_{max} = A = \Omega_0 / \omega$$

d) time = $\frac{2}{4} = \frac{1}{4} \frac{2\pi}{\omega} = \frac{\pi}{2} \sqrt{\frac{2l}{3g}}$

(F5)

3. A cylindrical shell of mass M , outer radius R_o and inner radius R_i rolls without slipping on an inclined plane making an angle θ with the horizontal. A smaller solid cylinder of radius r and mass m slides without friction on the inner surface of the cylindrical shell.



- (a) If the inner cylinder is not present, find the acceleration of the center-of-mass of the cylindrical shell. [20 points]
- (b) Next include the inner cylinder in the problem and assume that the angle ϕ identified in the figure is chosen so that ϕ does not change as the two cylinders move down the plane. Again find the acceleration of the center-of-mass of the cylindrical shell. [Hint: treat the pair of cylinders as a single object while explaining why such a treatment is justified.] [10 points]
- (c) Determine the angle ϕ . [10 points]

a) Use point of contact P

$$I_P \ddot{\Theta} = Mg R_o \sin \theta$$

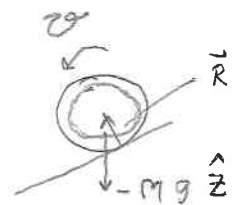
$$I_P = I_{cm} + MR^2$$

$$I_{cm} = \int_{R_i}^{R_o} r^2 2\pi r dr$$

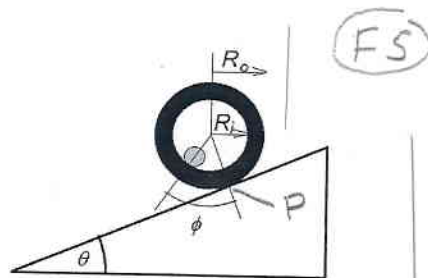
$$\rho = \frac{M}{\text{area}} = \frac{M}{\pi(R_o^2 - R_i^2)}$$

$$I_{cm} = \frac{2\pi}{4} (R_o^4 - R_i^4) \frac{M}{\pi(R_o^2 - R_i^2)} = \frac{1}{2} M (R_o^2 + R_i^2)$$

$$I_{cm} \rightarrow \begin{cases} \frac{1}{2} M R_o^2 & \text{for } R_i = 0 \\ M R_o^2 & \text{for } R_i = R_o \end{cases}$$



3. A cylindrical shell of mass M , outer radius R_o and inner radius R_i rolls without slipping on an inclined plane making an angle θ with the horizontal. A smaller solid cylinder of radius r and mass m slides without friction on the inner surface of the cylindrical shell.



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- (c) Determine the angle ϕ . [10 points]

a) Use point of contact P

$$I_P \ddot{\theta} = Mg R_o \sin \theta$$

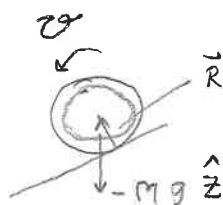
$$I_P = I_{cm} + MR^2$$

$$I_{cm} = \int_{R_i}^{R_o} \rho r^2 2\pi r dr$$

$$\rho = \frac{M}{\text{area}} = \frac{M}{\pi(R_o^2 - R_i^2)}$$

$$I_{cm} = \frac{2\pi}{4} (R_o^4 - R_i^4) \frac{M}{\pi(R_o^2 - R_i^2)} = \frac{1}{2} M (R_o^2 + R_i^2)$$

$$I_{cm} \rightarrow \begin{cases} \frac{1}{2} M R_o^2 & \text{for } R_i = 0 \quad \checkmark \\ M R_o^2 & \text{for } R_i = R_o \quad \checkmark \end{cases}$$



3 a) continued

$$I_P = I_{cm} + M R_o^2 = \frac{1}{2} M (3R_o^2 + R_i^2)$$

$$\ddot{x}_{cm} = R \ddot{\theta} = \frac{R_o}{I_P} Mg R_o \sin \theta$$

$$= \frac{2 R_o}{M (3R_o^2 + R_i^2)} Mg R_o \sin \theta$$

$$= \frac{2}{3 + (R_i/R_o)^2} g \sin \theta$$

b) Since inner cylinder slides w/o friction it exerts no torque about center of hollow cylinder. Don't use P but instead center of hollow cylinder



$$(M+m) \ddot{x} = Mg \sin \theta - F$$

$$I_{cm} \ddot{\theta} = R_o F$$

$$(M+m) \ddot{x} = (M+m) g \sin \theta - \frac{1}{2} M (R_o^2 + R_i^2) \frac{1}{R_o} \frac{\ddot{x}}{R_o}$$

$$\ddot{x} = \frac{(M+m) g \sin \theta}{\frac{3}{2} M + m + \frac{1}{2} M \left(\frac{R_i}{R_o}\right)^2}$$

3 a) continued

(F6)

$$I_p = I_{cm} + MR_o^2 = \frac{1}{2} M(3R_o^2 + R_i^2)$$

$$\ddot{x}_{cm} = R \ddot{\theta} = \frac{R_o}{I_p} Mg R_o \sin \theta$$

$$= \frac{2R_o}{M(3R_o^2 + R_i^2)} Mg R_o \sin \theta$$

$$= \frac{2}{3 + (R_i/R_o)^2} g \sin \theta$$

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$$(M+m)\ddot{x} = Mg \sin \theta - F$$

$$I_{cm} \ddot{\theta} = R_o F$$

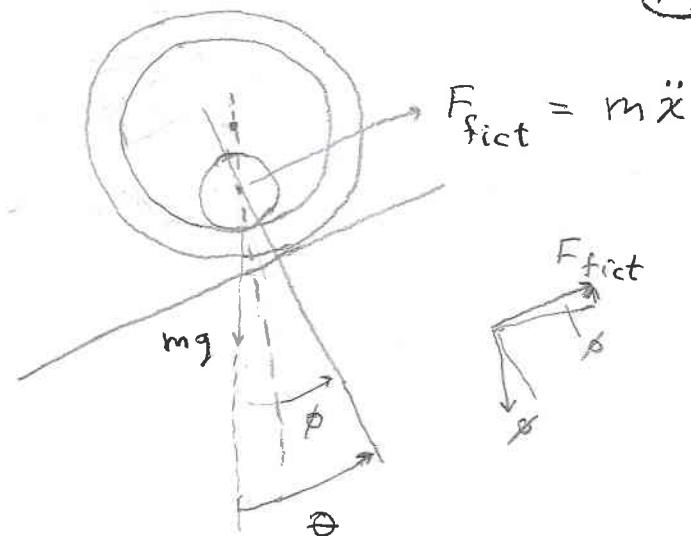
$$(M+m)\ddot{x} = (M+m)g \sin \theta - \frac{1}{2} M(R_o^2 + R_i^2) \frac{1}{R_o} \frac{\ddot{x}}{R_o}$$

$$\ddot{x} = \frac{(M+m)g \sin \theta}{\frac{3}{2}M + m + \frac{1}{2}M\left(\frac{R_i}{R_o}\right)^2}$$

3 continued

(F7)

c) Require components of \vec{F}_{fict} and $-mg \hat{z} \perp$ to ϕ direction cancel



$$mg \sin(\theta - \phi) = m\ddot{x} \cos \phi$$

$$g(\sin \theta \cos \phi - \cos \theta \sin \phi) = \ddot{x} \cos \phi$$

$$\sin \theta - \frac{\ddot{x}}{g} = \cos \theta \tan \phi$$

$$\tan \phi = \left[1 - \frac{\ddot{x}/g}{\sin \theta} \right] \tan \theta$$

$$= \left[1 - \frac{M+m}{\frac{3}{2}M + m + \frac{1}{2}M\left(\frac{R_i}{R_o}\right)^2} \right] \tan \theta$$

$$= \tan \theta \frac{\frac{1}{2}M \left[1 + \left(\frac{R_i}{R_o}\right)^2 \right]}{\frac{3}{2}M + m + \frac{1}{2}M\left(\frac{R_i}{R_o}\right)^2}$$