# Electoral Ambiguity and Political Representation

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Ambiguity and Representation

### Motivation

How much discretion should elected representatives exercise?

- Delegate vs. Trustee models
  - James Madison and Edmund Burke

Our contribution

- Formal framework to study political representation
- Connection with electoral ambiguity
- What is the optimal level of discretion to allow?
- How much discretion emerges from electoral competition?

### Framework

- Hotelling-Downs tradition
- Candidates impose constraints on their post-election policies
- Can announce a single policy or be ambiguous (any policy set)
- Policy-relevant state learned after taking office
  - Ambiguous platforms allow adapting policy to the state
- Voters' tradeoff: policy adaptability vs. bias

### Preview of Results

- Optimal representation is *in between* delegate and trustee models
  - delegate only if candidate is very biased; trustee only if unbiased
  - familiar from literature on delegation
- Ambiguity: Intervals that bound policy in direction of bias
  - UK Conservatives promised to  $\uparrow$  funding for Dept Health by  $\geq \pounds 8B$
  - Romney 2012: social security reform would entail "no change for those at or near retirement"
  - Obama 2008: "no family making less than \$250K a year will see any form of tax increase"
- $\blacksquare$  Divergence: expected policy of the candidate R is to the right of the candidate L
- The elected candidate's platform is generally not voter-optimal
  - More moderate candidate wins, but with an overly ambiguous platform
  - Ambiguity correlated with success; but not causal

### Related Literature

- Optimal delegation
  - Principal-Agent settings, following Hölmstrom (1977)
  - Ours is a delegation game: 2 agents propose sets to a principal
  - We build on results from Alonso and Matouschek (2008)
- Ambiguity in politics
  - Downs (1957) noted "puzzle" of ambiguity
  - Explanations incl. risk loving prefs (Shepsle 1972, Aragones and Postlewaite 2002), behavioral characteristics, ...
  - Aragones and Neeman (2002): candidates value ambiguity.
     Difference: voters in our model also benefit from ambiguity

### Model

### Game Form

Two candidates,  $i \in \{L, R\}$ , and a representative/median voter

**1** Candidates simultaneously propose platforms  $A_i \subseteq \mathbb{R}$ 

- Require  $A_i$  to be closed
- Timing doesn't actually matter
- **2** State of the world  $\theta \in [-1, 1]$ , privately observed by elected candidate
- **3** Elected candidate then chooses policy action  $a_i \in A_i$ 
  - Commitment to platform

### Preferences

Voter's payoff:

$$u_0(a,\theta) = -(a-\theta)^2$$

■ Candidate *i*'s payoff when *e* is elected:

$$u_i(a, \theta, e) = \begin{cases} \phi - (a - b_i - \theta)^2 & \text{if } i = e, \\ -(a - b_i - \theta)^2 & \text{if } i \neq e, \end{cases}$$

where  $b_R \geq 0 \geq b_L$  and  $\phi \geq 0$ 

• biases are commonly known

### State Distribution

 $\blacksquare \ \theta \sim F(\cdot)$  with differentiable density  $f(\cdot) > 0$  on [-1,1]

Density is symmetric around 0 and doesn't change too fast:

$$-f(\theta) \le f'(\theta) \le f(\theta),$$

$$\frac{\mathrm{d}}{\mathrm{d}t}\mathbb{E}[\theta|\theta\geq t]<1 \text{ and } \frac{\mathrm{d}}{\mathrm{d}t}\mathbb{E}[\theta|\theta\leq t]<1.$$

log-concavity implies latter condition

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### Some Basics

Study Subgame Perfect Nash Equilibria

If *i* is elected with platform  $A_i$ , proper subgame with (essentially) unique eqm:  $a_i(\theta, A_i)$ 

Goal is to characterize eqm platforms and voter behavior. Terminology:

- $A_i$  is minimal if  $\text{Im}(a_i(\cdot, A_i)) = A_i$ 
  - No redundant policies
  - Without essential loss, focus on minimal platforms
- $A_i$  is ambiguous if  $|A_i| > 1$ 
  - Voter is unsure of final policy if and only if platform is ambiguous
- There is convergence if  $A_L = A_R$ 
  - Weak notion; compatible with different ex-post policies

# **Optimal Political Representation**

### Voter-optimal platforms

Define thresholds  $\bar{a}^0$  and  $\underline{a}^0$  by  $\bar{a}^0 = \mathbb{E}[\theta|\theta \ge \bar{a}^0 - b_R]$  and  $\underline{a}^0 = \mathbb{E}[\theta|\theta \le \underline{a}^0 - b_L]$  $\mathbf{a}^0 \le 1 + b_R, \downarrow \text{ in } b_R \in [0, 1], \text{ range } [0, 1], \text{ equals } 0 \text{ for } b_R \ge 1$ 

#### Proposition

The two candidates' respective voter-optimal platforms are

$$\begin{split} A_R^0 &:= \begin{cases} \{0\} & \text{if } b_R \ge 1, \\ [-1+b_R, \bar{a}^0] & \text{if } b_R \in [0,1). \end{cases} \\ A_L^0 &:= \begin{cases} \{0\} & \text{if } b_L \le -1, \\ [\underline{a}^0, 1+b_L] & \text{if } b_L \in (-1,0]. \end{cases} \end{split}$$

Interval with cap against bias (formally proved using AM 2008)

Ambiguity necessary to achieve optimal representation

delegate and trustee models as extremes

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### **Comparative Statics**

Let  $W_0(A_i, i)$  be voter's welfare when i is in office with platform  $A_i$ .

#### Proposition

- For any  $i \in \{L, R\}$  and  $b_i$  with  $|b_i| \in (0, 1)$ ,
  - **1**  $A_i^0$  is decreasing in  $|b_i|$ .
  - **2**  $W_0(A_i^0, i)$  is decreasing in  $|b_i|$ ;
  - 3  $\mathbb{E}[a_L(\theta, A_L^0)] < 0 < \mathbb{E}[a_R(\theta, A_R^0)]$ , with

$$\lim_{b_i \to 0} \mathbb{E}[a_i(\theta, A_i^0)] = \lim_{|b_i| \to 1} \mathbb{E}[a_i(\theta, A_i^0)] = 0.$$

In expectation, policy moved in direction of candidate's bias
Nb: Var[a<sub>i</sub>(θ, A<sup>0</sup><sub>i</sub>)] = 0 when |b<sub>i</sub>| = 1 but is maximal when b<sub>i</sub> = 0

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## Equilibrium Ambiguity and Representation

# Solving for Equilibrium

#### Lemma

In any equilibrium in which R wins with pos prob, he plays a pure strategy, choosing a platform  $A_i^*$  such that either

• 
$$A_R^* = \{a_R^*\}$$
 with  $a_R^* \ge 0$ , or

•  $A_R^* = [-1 + b_R, \bar{a}_R^*]$  with  $\bar{a}_R^* \in [\bar{a}^0, 1 + b_R]$ .

#### (Analogous for L.)

- Key insight: unless losing for sure, a candidate must use a pairwise Pareto optimal platform
  - Maximize some convex combination of voter and candidate's utilities
  - Isomorphic to earlier problem, with suitably scaled down bias
  - Set consists of intervals if  $|b_i| < 1$
- Pure strategies from eqm considerations
  - discontinuous gain from winning (even if  $\phi=0)$

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# Equilibrium Characterization (1)

#### Proposition

An equilibrium exists. Assume (wlog)  $b_R \leq -b_L$ .

**1** If  $b_R = 0$ : in any eqm, an elected i has  $b_i = 0$  and  $A_i^* = A_i^0 = [-1, 1]$ .

**2** If 
$$b_R \ge 1$$
: in any eqm,  $A_i^* = A_i^0 = \{0\}$ .

**3** If  $b_R = -b_L \in (0,1)$ : in any eqm,  $A_i^* = A_i^0$ , where

$$A_L^0 = [\underline{a}^0, 1 + b_L]$$
 and  $A_R^0 = [-1 + b_R, \overline{a}^0].$ 

- In all these ["special"?] cases, voter-optimal platforms emerge.
- In part 3: expected policy divergence, non-monotonic in candidate polarization
- Nb: Voter strategy not pinned down

# Equilibrium Characterization (2)

Proposition (Asymmetric candidates)

Assume  $b_R < (0, \min\{-b_L, 1\}).$ 

4 If  $W_0(A_L^0, L) > W_0(\mathbb{R}, R)$ : Unique eqm.

$$A_L^* = A_L^0$$
 and  $A_R^* = [-1+b_R, \overline{a}_R^*],$ 

where  $\overline{a}_R^* \in (\overline{a}^0, 1 + b_R)$  s.t.  $W_0(A_L^0, L) = W_0(A_R^*, R)$ . The voter elects R.

**5** If  $W_0(A_L^0, L) \leq W_0(\mathbb{R}, R)$ : unique eqm outcome. In any eqm,

 $A_R^* = [-1 + b_R, 1 + b_R]$  and the voter elects R.

If one candidate is more ambiguous (and wins with pos prob), he wins

but ambiguity does not cause success

■ Winning candidate is over-ambiguous; competition → efficiency

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### Discussion

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- Commitment
  - Key assm: Allow policy sets, but no state-contingent promises.
    - In our view, reasonable
  - If candidates can only choose singletons, converge to 0.
     Lower welfare (strictly when b<sub>L</sub>, b<sub>R</sub> ∈ (−1, 1)).
  - With state-contingent promises,  $a(\theta) = \theta$ . Higher welfare.
- Heterogeneous voters
  - Let voter v have payoff  $u_v(a, \theta) = -(a v \theta)^2$ .
  - Logic carries over with median voter v = 0.
- Non-deterministic elections
  - With valence shocks, both candidates can win, never get voter-optimal platforms, but converge to them as  $\phi \to \infty$ .
  - Valence sym. distributed and large  $\phi$ : less-biased candidate wins more often and is more ambiguous.

### Conclusions

### Recap

- Formal framework to study classical question in political representation
- Optimal representation usually in between "delegate" and "trustee" relationship
- Divergence and ambiguity beneficial for welfare when candidates not too polarized.
- Advantaged candidates are overly ambiguous, yet win anyway.
- Non-monotonic relationship between polarization in candidates and the action they take.