Peter Wei

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♦ http://www.columbia.edu/~pw2428/

Ph.D. candidate in electrical engineering with experience in conducting original research and applying machine learning and AI techniques and algorithms to big data in real-time IoT systems and software systems.

Education

Columbia University (Expected Graduation May 2021)
Ph.D. Candidate, Electrical Engineering, GPA: 3.8, Presidential Fellowship
Carnegie Mellon University
M.S. Electrical and Computer Engineering, GPA: 3.7
B.S. Electrical and Computer Engineering, GPA: 3.9, University Honors

Technical Skills

Programming: Python, C/C++, Matlab, Golang, Swift, Android, HTML, JavaScript, x86 Assembly, Arduino Tools and Software: Hive SQL, MongoDB, Git, LaTeX, OpenCV, TensorFlow, SystemVerilog

Experience

Wish

Engineering Intern

- Implemented real-time user action logging and xgboost models to predict future merchandise profit.
- Designed daily tools to better analyze effects of new features on revenue and click through rate.

• Launched A/B testing experiments based on analysis of new user behavior with preliminary increases in new user GMV between 0.5 - 1%.

Intelligent and Connected Systems Laboratory, Columbia University Ph.D. Student

Analysis and Visualization of Personal Energy Consumption

- Deployed a web server for analyzing measured energy consumption data from a building sensor network.
- Designed a tripartite graph data structure and low runtime algorithms for computing energy consumption.
- Developed an iOS/Android application for visualizing real-time personal energy consumption.

Recommender System for Energy Savings

- Implemented a recommender system to output real-time energy saving recommendations using deep Q-Learning.
- Ran simulations and developed a mobile application for a focus group study to show potential energy savings.

The Robotics Institute, Carnegie Mellon University Graduate Research Assistant

- Developed an Android app module for logging car diagnostics data over Bluetooth.
- The module improved GPS localization accuracy through wheel RPM and accelerometer data.

iRobot Corporation Software Engineering Intern

- Designed and implemented a low-power sensing system for detecting floor types for the Roomba.
- Trained random forest and SVM classifiers to differentiate 3 types of surfaces with > 90% accuracy.
- System and experiments served as a precursor to the Carpet Boost technology in newer Roomba models.

GRASP Laboratory, University of Pennsylvania Undergraduate Research Assistant

- Implemented a heuristic search algorithm (D* Lite) for a mobile robot in an cluttered, unknown environment.
- Algorithm enabled real-time map updates as the robot traverses the environment.

2011-2015

New York, NY 2016-Present Pittsburgh, PA 2015-2016

Pittsburgh, PA

Spring 2016

Summer 2015

Philadelphia, PA Summer 2014

2016-Present

New York, NY

San Francisco, CA Summer 2019

Bedford, MA