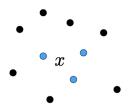
Understanding Thy Neighbors: Practical Perspectives from Modern Analysis



Sanjoy Dasgupta
CSE, UCalifornia, San Diego

Samory Kpotufe
ORFE, Princeton University

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Ubiquitous and Enduring in ML (implicit at times):

Traditional ML: Classification, Regression, Density Estimation, Bandits, Manifold Learning, Clustering ...

Modern ML: Matrix Completion, Inference on Graphs, Time Series Prediction ...

Of Practical Interest:

Which metric? Which values of k? Tradeoffs with big data?

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Closest neighbors of x should be mostly of similar type y=y(x) ...

Prediction: aggregate Y values in Neighborhood(x)

Similar Intuition: Classification Trees, RBF networks, Kernel machines

Results by various authors help formalize the above intuition

Posner, Fix, Hodges, Cover, Hart, Devroye, Lugosi, Hero, Nobel, Györfi, Kulkarni, Ben David, Shalev-Schwartz, Samworth, Gadat, H. Chen, Shah Kpotufe, von Luxburg, Hein, Chaudhuri, Dasgupta, Langford, Kakade, Beygelzimer, Lee, Grav. Andoni, Clarkson, Krauthgamer, Indyk. ...

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Cover both Statistical and Algorithmic Issues:

- 1 Statistical issues: how well can NN perform?
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 - For k-NN, what should k be?
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- Direct Euclidean
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- PART I: Basic Statistical Insights
- PART II: Refined Analysis and Implementation

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- Universality
- Behavior of k-NN Distances
- From Regression to Classification
- Classification is easier than regression
- Multiclass and Mixed Costs

k-NN as a universal approach:

it can fit anything, provided k grows (but not too fast) with sample size!

Let's make this precise in the context of regression ...

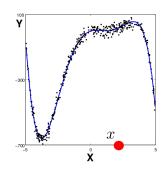
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i.i.d. Data:
$$\{(X_i, Y_i)\}_{i=1}^n$$
, $Y = f(X) + \text{noise}$

Learn: $f_k(x) = \text{avg } (Y_i) \text{ of } k\text{-NN}(x).$



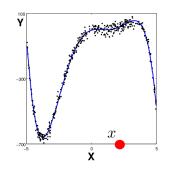
k-NN is universally consistent:

Suppose
$$\frac{k}{n} \to 0$$
 and $k \to \infty$, then $\mathbb{E} \left| f_k(X) - f(X) \right| \xrightarrow{n \to \infty} 0$



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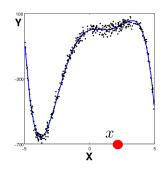


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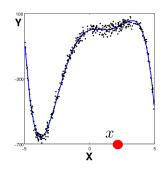


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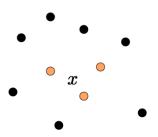


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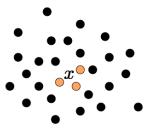
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- Suppose f is continuous, then we also get $\{f(X_{(i)})\}_1^k o f(x)$
- If $k \to \infty$, then $f_k(x) = \frac{1}{k} \sum (f(X_{(i)} + \text{noise}) \to f(x))$





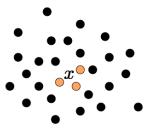
Consider the k-NN $\{X_{(i)}\}_1^k$ of some x

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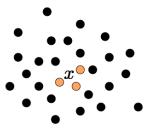
As $n \nearrow$, all $\{X_{(i)}\}_1^k$ move closer to x

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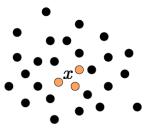
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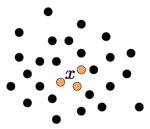
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Similar universality results for classification, density estimation, ...

Seminal results on k-NN consistency:

- [Fix, Hodges, 51]: classification + regularity, \mathbb{R}^d .
- [Cover, Hart, 65, 67, 68]: classification + regularity, any metric.
- [Stone, 77]: classification, universal, \mathbb{R}^d .
- [Devroye, Wagner, 77]: density estimation + regularity, \mathbb{R}^d .
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Main message: k should grow (not too fast) with n ... $(e.g. k \sim \log n)$

But we need a more refined picture ...

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PART I: Basic Statistical Insights

- Universality
- Behavior of k-NN Distances
- From Regression to Classification
- Classification is easier than regression
- Multiclass and Mixed Costs

Recall Intuition:

Closest neighbors of x should be mostly of similar type $y=y(x)\,\dots$

So we hope that $k extsf{-}\mathsf{NN}(x)$ are close to x ...

Formally: let $r_k(x) \equiv$ distance from x to k-th NN in i.i.d. $\{X_i\}_1^n$

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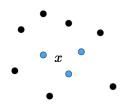
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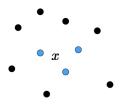


 $B_x \equiv B(x, r_k(x)) \equiv \text{smallest ball containing } k\text{-NN}(x)$

- Assume no ties: $P_n(B_x) = k/n$
- w.h.p. $P_n pprox P_X \implies P_X(B_x) pprox k/n$.

Now:
$$P_X(B_x) \equiv \int_{B_x} p_X(x') \, dx' \approx p_X(x) \cdot \int_{B_x} dx' \approx p_X(x) \cdot r_k(x)^d$$
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Therefore, w.h.p.,
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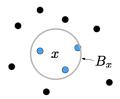


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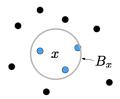


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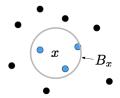
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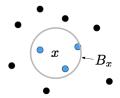
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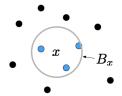
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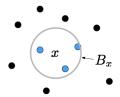
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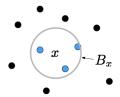
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$$P_X(B_x) \equiv \int_{B_x} p_X(x') dx' \approx p_X(x) \cdot \int_{B_x} dx' \approx p_X(x) \cdot r_k(x)^d$$
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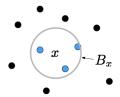
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- $r_k(x)$ \nearrow when local density $p_X(x)$ \searrow
- $r_k(x) \nearrow$ when input dimension $d \nearrow$ Use smaller k for higher dimensional data

Curse of dimension: For $r_k pprox \epsilon$ we need $n pprox (1/\epsilon)^d$

Fortunately, effective d can be small for high-dimensional $X \in {
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Effective d is whichever satisfies: $P_X(B(x,r)) = \ldots \approx c \cdot r^d$

d=d (metric ho; where X lies in ${
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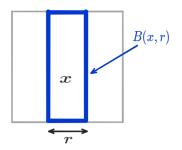
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Ex 1: Suppose $X \in \mathbb{R}^D$, but $\rho(x, x') \approx \rho(x_{(1)}, x'_{(1)})$...

 $P_X(B(x,r)) \approx r \implies \text{effective } d=1$

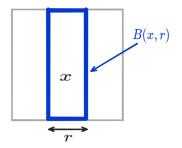
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$$B(x,r) \equiv \{x': \, \rho(x,x') \le r\}$$

$$P_X(B(x,r)) pprox r \implies$$
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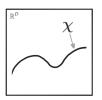
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Ex 2: Suppose $X \in \mathbb{R}^D$, but lies on a d-dimensional space \mathcal{X} ...



Consider B, of radius r, centered on \mathcal{X} :

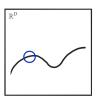
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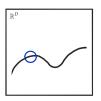
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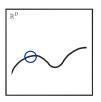
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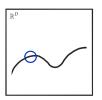
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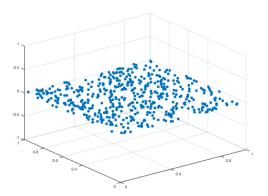


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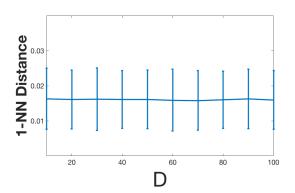
Thus we'd have $r_k(x) \approx (k/n)^{1/d}$, irrespective of $D \gg d$.

Quick Simulations:



Embed (d=2)-data into high-dimensional \mathbb{R}^D , $D \to \infty$

Quick Simulations:



Fix d = 2: average NN distances are stable as D varies

Refined analysis for $r_k(x)$:

[J. Costa, A. Hero 04], [R. Samworth 12]

Implications:

 $r_k(x)$ adaptive to $d \implies \mathsf{NN}$ methods adaptive to $d \dots$ (d-sparse documents, images, Robotics data on d-manifold

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Implications:

 $r_k(x)$ adaptive to $d \Longrightarrow NN$ methods adaptive to $d \ldots$ (d-sparse documents, images, Robotics data on d-manifold)

PART I: Basic Statistical Insights

- Universality
- Behavior of k-NN Distances
- From Regression to Classification
- Classification is easier than regression
- Multiclass and Mixed Costs

From bounds on $r_k(x)$ to error rates:

Program:

- 1. Regression bounds
- Reduce Classification to Regression

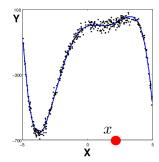
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Program:

- 1. Regression bounds
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Data:
$$\{(X_i, Y_i)\}_{i=1}^n$$
, $Y = f(X) + \text{noise}$

Learn: $f_k(x) = \text{avg } (Y_i) \text{ of } k\text{-NN}(x).$



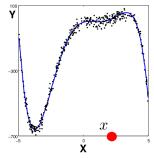
Ideal Metric
$$\rho$$
: $f(x) \approx f(x')$ if $\rho(x,x') \approx 0$... e.g., assume f is Lipschitz: $|f(x) - f(x')| \leq \lambda \cdot \rho(x,x')$

Performance Goal.



Data: $\{(X_i, Y_i)\}_{i=1}^n$, Y = f(X) + noise

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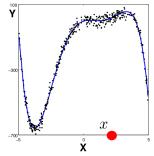
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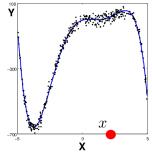
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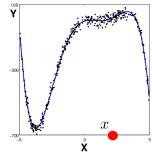
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Performance Goal:

Pick
$$k$$
 such that $||f_k - f||^2 \equiv \mathbb{E}_X |f_k(X) - f(X)|^2$ is small.

A simple fact:
$$\mathbb{E} |Z - c|^2 = \mathbb{E} |Z - \mathbb{E}Z|^2 + |c - \mathbb{E}Z|^2$$

So fix x, and fix $\{X_i\}$, and let $ilde{f}_k(x) = \mathbb{E}_{\{Y_i\}}f_k(x)$...

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$$\operatorname{Var}(f_k(x)) = \frac{1}{k^2} \sum_{X_i \in k - \operatorname{NN}(x)} \operatorname{Var}(Y_i) = \frac{\sigma_Y^2}{k}$$

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Pick $k = \Theta(n^{2/(2+d)})$ to get $\mathbb{E}[|f_k - f||^2 \lesssim n^{-2/(2+d)}]$, optimal

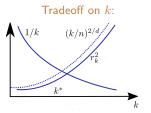
Observe in the C.V. wildle came outlier before

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Best choice of $k \nearrow$ as $n \nearrow$ and $d \searrow$

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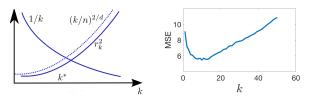


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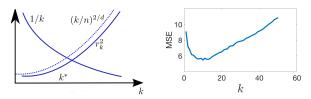
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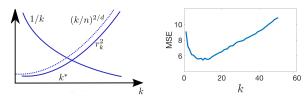
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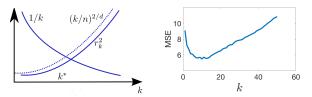
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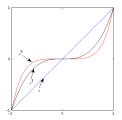
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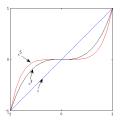
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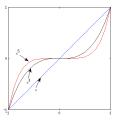
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(see e.g. [Györfi, Krzyżak, Walk, 02])



From bounds on $r_k(x)$ to error rates:

Program:

- 1. Regression bounds
- 2. Reduce Classification to Regression

Data:
$$\{(X_i, Y_i)\}_{i=1}^n$$
, $Y \in \{0, 1\}$.

Learn:
$$h_k(x) = \text{majority } (Y_i) \text{ of } k\text{-NN}(x).$$

Reduces to regression: let $f_k(x) = \operatorname{avg}\ (Y_i)$ of $k\operatorname{-NN}(x)$

... then:
$$h_k(x) \equiv \mathbb{1}\{f_k(x) \ge 1/2\}$$
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Performance Goal:

Pick k such that $err(h_k) \equiv \mathbb{P}(h_k(X) \neq Y)$ is small

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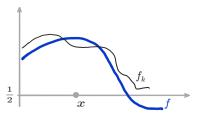
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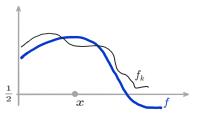
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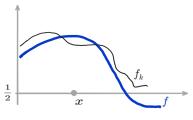
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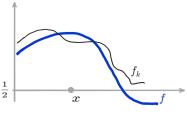
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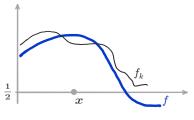


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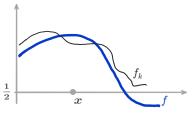
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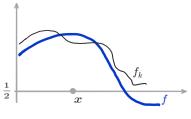
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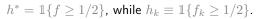
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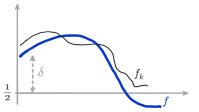
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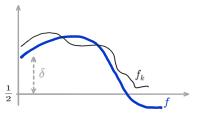


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Tsybakov's noise condition: $\mathbb{P}_X(|f-1/2|<\delta) \leq \delta^{eta}$

If
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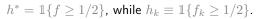


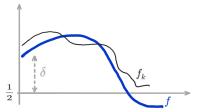


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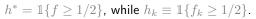


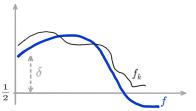


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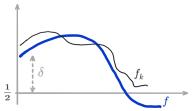


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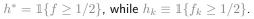


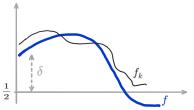


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- Lipschitzness: $||f(x) f(x')|| \le \rho(x, x')$
- Noise margin: At any x, we want $f^{(1)}(x) \gg f^{(2)}(x)$..

assume
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$$y \leftarrow \mathsf{Expected}\ \mathsf{cost}\ \mathsf{when}\ y\ \mathsf{is}\ \mathsf{wrong} \neq 1 - \mathbb{P}(Y = y)$$

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End of Part I