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Note on Consistency models

① Diffusion models

$$dX_t = b(t, X_t) dt + \sigma(t) dB_t, \quad X_0 \sim P_{\text{data}}(\cdot) \quad (1)$$

time reversal:

$$d\bar{X}_t = \left(-b(T-t, \bar{X}_t) + \underbrace{\sigma^2(T-t)}_{S(T-t, \bar{X}_t)} \nabla \log p(T-t, \bar{X}_t) \right) dt + \sigma(T-t) d\bar{B}_t, \\ \bar{X}_0 \sim P_{\text{noise}}(\cdot) \quad (\text{e.g. stationary dist...}) \quad (2)$$

A more convenient ODE sampling/solving by matching the Fokker-Planck equation:

$$dX'_t = \left(b(t, X'_t) - \frac{1}{2} \sigma^2(t) \nabla \log p(t, X'_t) \right) dt \\ X'_0 \sim P_{\text{data}}(\cdot) \quad (3)$$

time reversal:

$$d\bar{X}'_t = \left[-b(T-t, \bar{X}'_t) + \frac{1}{2} \sigma^2(T-t) \nabla \log p(T-t, \bar{X}'_t) \right] dt \\ \bar{X}'_0 \sim P_{\text{noise}}(\cdot) \quad (4)$$

Disadvantage: slow sampling/generation
often requires 10~20 steps/iterations

④ Consistency models : allow one-step generation

To simplify the discussion (and for practical purposes),

consider $b \equiv 0$ and $\sigma(t) = \sqrt{2t}$ (VE)

(which can be easily extended to general settings).

ODE sampling :

$$d\bar{X}'_t = -t s(T-t, \bar{X}'_t) dt, \quad \bar{X}'_0 \sim P_{\text{noise}}(\cdot) \quad (5)$$

Fact : For each t , $\bar{X}'_t \stackrel{d}{=} \bar{X}_t$ (marginal dist. matches)

Consistency / ODE flow :

If $\bar{X}'_0 \sim p(t, \cdot)$ and dynamics (5)

then $\bar{X}'_{t-s} \sim p(s, \cdot)$ (and $\bar{X}'_t \sim P_{\text{data}}(\cdot)$)

Idea : Find the ODE flow $f(s, x)$ to (5)

↑ called the consistency fct.

So $Z \sim P_{\text{noise}}(\cdot)$ \swarrow one step!

Sample $F(T, Z) \approx P_{\text{data}}(\cdot)$

Function approximation $f_\theta(s, x)$.

(a) Consistency distillation (CD):

Pretrained score $S_\varphi(t, x)$:

① sample $X_{t_{n+1}} \sim P_{data}(\cdot) \otimes \mathcal{N}(0, t_{n+1}^2)$

② ODE approximation

$$X_{t_n} = X_{t_{n+1}} + (t_{n+1} - t_n) S_\varphi(t_{n+1}, X_{t_{n+1}})$$

③ minimize e.g.

$$\left| f_\theta(t_{n+1}, X_{t_{n+1}}) - f_\theta(t_n, X_{t_n}) \right|^2$$

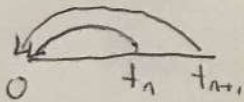
← in the paper

(Intuition: $f(t_{n+1}, X_{t_{n+1}}) = f(t_n, X_{t_n}) = f(0, X_0)$)

ODE flow

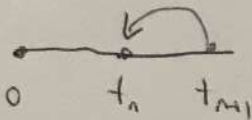
← boundary condition

$$f(0, x) = x$$



A slight modification to minimize

$$\left| f_\theta(t_{n+1} - t_n, X_{t_{n+1}}) - X_{t_n} \right|^2$$



(b) Consistency training (CT)

Similar to consistency distillation except
the way to "couple" $(X_{t_n}, X_{t_{n+1}})$.

(i) sample $(X_{t_n}, X_{t_{n+1}}) \sim x + (t_n, t_{n+1}) \mathcal{N}(0, 1)$. *

(ii) minimize

$$\left| f_{\theta}(X_{t_n}, t_n) - f_{\theta}(X_{t_{n+1}}, t_{n+1}) \right|^2$$

Advantage: no need to use "pretrained" $S_{\varphi}(t, x)$

Bad thing: Performance worse than CD!

Reason: the "consistency function" $f(t, x)$ is the
(reversed) ODE flow

So CD couples $(X_{t_n}, X_{t_{n+1}})$ in the correct way

while CT couples $(X_{t_n}, X_{t_{n+1}})$ in the "wrong" way

↑ ↳ Q: How wrong?

the marginal matches but the joint differs!

(5)

Another idea ^①: find $f(t, x)$ through PDE

We see that $f(t, x)$ is the (reversed) ODE flow and there is a connection between ODE flow and transport equation (characteristic).

$$df(t, x_t) = 0$$

$$\frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} dx_t = 0$$

\uparrow
 $-tS_\varphi(t, x_t) dt$

So f solves

$$\frac{\partial f}{\partial t} - tS_\varphi(t, x) \frac{\partial f}{\partial x} = 0$$

(6)

with boundary conditions.

Idea: Solve (6) using f_0 ?



Someone may have thought of this?

Another idea ^② (ad-hoc):

From the SDE sampling ^②, one can consider to find the "stochastic" flow $f(t, x, (B_t))$

$$f_0 = F_0(x, t) + G_0(x, t) N(0, 1)$$

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