Continuous-time Markov chain models to estimate the premium for extended hedge fund lockups

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Abstract A *lockup period* for investment in a hedge-fund is a time period after making the investment during which an investor cannot freely redeem his investment. Since long lockup periods have recently been imposed, it is important to estimate the premium an investor should expect from extended lockups. For this, Derman et al. (Wilmott J. 1(5–6):263–293, 2009) proposed a parsimonious three-state discrete-time Markov Chain (DTMC) to model the state of a hedge fund, allowing the state to change randomly among the states "good," "sick" and "dead" every year. In this paper, we propose an alternative three-state absorbing continuous-time Markov Chain (CTMC) model, which allows state changes continuously in time instead of yearly. Allowing more dynamic state changes is more realistic, but the CTMC model requires new techniques for parameter fitting. We employ nonlinear programming to solve the new calibration equations. We show that the more realistic CTMC model is a viable alternative to the previous DTMC model for estimating the premium for extended hedge fund lockups.

Keywords Hedge fund · Continuous-time Markov chain · Lockup premium

1 Introduction

A *lockup period* for investment in a hedge-fund is a time period after making the investment during which an investor cannot freely redeem his investment. Hedge funds often require a lockup period in order to invest in illiquid assets (Aragon 2007). The importance of investment liquidity was highlighted by the recent financial crisis of 2007–2009 (Golts and Kritzman 2010; Al Janabi 2013).

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In recent years, there have been long lockup periods. Boyle et al. (2010) found that in the Hedge Fund Research database the average lockup period for funds with the lockup condition is one year, with the durations lasting from one to four years. Ang and Bollen (2009) also observed that typical lockup period is from one to three years. Long hedge fund lockups has continued during the recent financial crisis. Kazemi (2010) reported that, during the recent financial crisis, hedge funds with long lockup periods could avoid selling their assets at distressed prices. Also, Ben-David et al. (2012) found that hedge funds with short lockup periods are more likely to face selloffs caused by redemptions.

In an asset allocation problem, the risk of investing in a hedge fund under lockup condition requires appropriate additional returns for bearing the liquidity risk. Thus, it is important to estimate the premium for bearing extended hedge fund lockups. Derman et al. (2009) and Ang and Bollen (2009) applied stochastic models for the states of hedge funds to calculate the premium for an extended hedge fund lockup. We too wish to estimate the premium from extended hedge fund lockup. In doing so, just as Derman et al. (2009), we take the point of view of a manager of a fund of funds, who has to choose between two investments in similar funds in the same strategy category. Thus, we define the premium for extended hedge fund lockup as the annual fixed rate of return that compensates the difference of expected returns in two hedge-fund investments, with and without the extended lockup condition; see Sect. 3. This definition accounts for the lost gains due to the inability to rebalance the investment portfolio in hedge funds, but not for other lost investment opportunities, so this is a conservative estimate of the lockup premium. Investors can separately consider the cost of other lost investment opportunities. We believe that the lockup premium calculated here may be helpful for investors to see whether the shareholder restrictions caused by the extended lockup condition in hedge funds can be offset by the additional returns from the illiquid investment.

Since hedge funds are not required by regulatory authorities to report their returns, data on returns of hedge funds are relatively limited, compared to data for other securities. Thus, despite of the importance of extended hedge fund lockups, there has been limited research on the lockup premium for hedge fund investment; see Sect. 2.

1.1 The initial discrete-time model

Derman et al. (2009) (hereafter, DPW09) proposed a parsimonious discrete-time Markov chain (DTMC) model that can be calibrated to three observable performance measures from hedge fund returns: (i) the persistence factor, (ii) the death rate, and (iii) the volatility (as measured by the variance or standard deviation of annual returns). They fit the model to hedge-fund return data from the Tremont Advisory Shareholder Services (TASS) database, using data from 2001–2005. They then applied the fitted DTMC model to calculate the lockup premium.

The DTMC model in DPW09 is similar in spirit to previous DTMC models used in finance, such as the DTMC model of yearly bond credit rating migration given on pp. 626–627 of Hull (2003). In bond credit rating, there are easily identified states, namely, the different credit ratings, ranging from AAA to CCC and default. With these well-specified states, the transition probabilities are easy to estimate from the observed proportions of changes in historical data.

The DTMC model for hedge funds in DPW09 is less straightforward. As with bond ratings, the DTMC was used to model the "state" of the hedge fund, but the state is not so easy to define. However, the rules for hedge fund lockup suggest a simple framework: In DPW09, three states were postulated: good, sick, and dead. In a good state, the fund has an above-average return within the same strategy category of hedge funds for a given period, so



an investor wants to keep his investment in the fund. In a sick state, the fund shows below-average performance, so an investor in this fund would want to redeem his investment and reinvest in another hedge fund in a good state, if allowed. In a dead state, the investor suffers a low return due to poor performance, and the fund becomes extinct. However, in a dead state, the lockup condition becomes invalid and the investor receives the remaining balance from the dead fund. In a dead state, the investor can immediately invest in another fund, which we take to be in the good state. (The model can incorporate partial redemption of the investment from a dead fund by assigning an appropriate return value for a dead state.)

From the perspective of the lockup premium, the critical state is the sick state. There is no extra lockup penalty associated with a good fund or a dead fund, but there is with a sick fund. With the nominal one-year lockup, we assume that an investor will reinvest in a good fund every year, if the current fund is not judged to be in a good state. In contrast with an extended lockup period, the investor will not be able to reinvest when the fund is judged to be in a sick state. The investor must keep his investment in the sick fund. Meanwhile, the state of the sick fund will evolve in an uncertain manner. it may continue to produce mediocre returns and be judged sick, it may get worse and "die," or it may recover and become a good fund. The DTMC model was used to capture the likelihood of the different alternatives.

Of course, the state ("health") of a hedge fund cannot be directly observed, but symptoms are observed, notably the stream of returns. In DPW09 the state was estimated by the level of relative returns. Two thresholds were postulated: U and L, with U > L. A fund is judged to be in a good state if the relative returns are above U, in a sick state if the relative returns are in the interval (L, U), and in a dead state if the relative returns fall below L. Assuming that the three-state DTMC only can have one-step (one-year) transitions to a neighboring state, the DTMC has three parameters; the three transition probabilities $P_{G,S}$, $P_{S,G}$ and $P_{S,D}$. Since the true state is not observable, an indirect procedure was used to estimate the transition probabilities. To fit the parameters in the DTMC model based on the TASS hedge fund data, three important hedge-fund performance measures were used: the performance persistence factor, the death rate and the standard deviation of annual returns. The transition probabilities were determined by solving a system of equations.

DPW09 relied heavily on the persistence of hedge fund returns. A persistence level γ means that "for every 1 percentage point earned above the average in the current year, we expect to earn γ percentage points above the average in the next year." We acknowledge that the existence of persistence in hedge funds is controversial, but DPW09 found strong evidence based on the TASS hedge fund data. The persistence was estimated in DPW09 by doing a regression analysis on the hedge fund return data from the TASS database. They observed non-zero persistence for eight of the eleven hedge fund strategy categories with 95 % statistical significance; see Table 1 of DPW09. (The quality of the TASS data remains a concern, however.)

Persistence of hedge fund returns suggests that a sick fund tends to remain in a sick state in the next time period, making the option to redeem one's investment in such a fund meaningful. With the persistence of hedge fund returns, the empirically observed lockup premium, e.g. in Aragon (2007) may explain how the pricing of a sick fund in the lockup premium calculation can be reflected empirically.

Given the fitted DTMC model, the lockup premium was then calculated as the compensation for the restricted re-balancing opportunities from a sick state fund to a good state during the lockup period. Specifically, the calculation is done by comparing the expected return of the same hedge fund with and without the extended lockup condition. The lockup premium is the annual fixed rate of return that compensates the difference of expected returns in the two hedge-fund investments, with and without the extended lockup condition.



1.2 The proposed continuous-time model

Unfortunately, the DTMC model with yearly transitions has the limitation that the state of a hedge fund can only change once per year. Since transition was restricted to neighboring states, it requires at least two years for a fund to transition from good to sick and then sick to dead. That restriction would not cause a significant problem in the DTMC model if in fact the state of a hedge fund would only change to a neighboring state in one year. However, in reality, the fortune of hedge funds can change much more rapidly. Many hedge funds that made big gains before the financial crisis of 2007–2009 suddenly suffered severe losses during the crisis. In fact, many of them have still not yet fully recovered from those losses, even after 2–4 years (Ahmed 2011).

To incorporate a rapid transition of a hedge fund state, we might try to allow a transition from a good state to dead state in one year in the DTMC model. Unfortunately, however the analysis in DPW09 does not permit that extension. Simple explicit formulas in the DTMC model would no longer hold. Furthermore, the calibration method for the DTMC model would no longer work, because the number of parameters in the Markov chain would increase without changing the number of equations to fit from data.

As a result, we are motivated to consider alternative models that allow the hedge fund state to change continuously in time. For that purpose, in this paper we propose to model the state of the hedge fund as an absorbing continuous-time Markov chain (CTMC) or, more specifically, an absorbing birth-and-death process. With the CTMC model, there are again three parameters, but now the parameters are the instantaneous transition rates to neighboring states: There are death rates μ_G and μ_S for transitioning from good to sick and from sick to dead, respectively. And there is a birth rate λ_S for transitioning from sick to good. The fund ceases to exist in a dead state, so the dead state is an absorbing state.

With the CTMC model, we still assume that the fund generates returns in discrete time. We use discrete time because the returns are reported infrequently. We assume that the investor will be able to redeem his investment from a dead fund at these reporting times, whenever the fund becomes dead. Thus, from the investor's perspective, there are only two relevant states at these reporting times: good and sick. Thus, the successive states at the return times becomes a two-state ergodic DTMC, whose transition probabilities are determined by the transient probabilities of the CTMC. We thus need to use the transient transition probabilities of the absorbing CTMC in order to determine the one-step transition probabilities of the ergodic DTMC. Given the ergodic DTMC, we can calculate the lockup premium, much as before; see Sect. 3.

Allowing state changes continuously in time is more realistic and allows greater flexibility in the model fitting. Even though we now allow the state of a hedge fund to change continuously, we still want to make the model just as parsimonious as the DTMC model, so that similar model calibration methods can be applied. In fact, the CTMC model actually uses the same three parameters as the DTMC model to calibrate the model from the data: persistence factors, variance of returns, and the death probability. However, new calibration methods are needed. We use the same measures of hedge fund performance. Just as in DPW09 and Derman et al. (2010), we rely heavily on the persistence of hedge fund returns. It turns out that we can again fit the three model parameters (now the three transition rates of the CTMC) to the persistence, the death probability and the annual return volatility. However, the fitting becomes more complicated. We are no longer able to obtain closed-form expressions for the parameters (the transition rates of the CTMC, as opposed to the transition probabilities of the DTMC in DPW09). Instead, we exploit nonlinear programming and an iterative algorithm to carry out the fitting. However, once this algorithm has



been developed, we are able to fit the parameters as easily and rapidly as before. Moreover, the flexibility provided by the CTMC allows us to fit to a wider range of parameters. For example, with the previous DTMC model, the death rate had to be less than 0.06; with the CTMC model, it can be as high as 0.13.

Overall, we show that the more realistic and flexible CTMC model is also a viable alternative to estimate the premium for extended lockup of hedge funds. The estimated lockup premium is thus presumably more accurate. However, in our numerical experiments we found that the computed lockup premium as a function of hedge fund performance measures does not differ greatly from the premium estimated by the DTMC model. We thus regard this paper as confirming that the previous more rudimentary DTMC model yields a reasonable approximation. Both highly stylized approaches seem appropriate given the quality of the data.

The new continuous-time model and calibration methodology are important contributions themselves. First, these new methods may be useful for similar investigations in the future. Second, these new methods may also help guide the development of more sophisticated methods in the future with more refined data.

1.3 The rest of the paper

The rest of the paper is organized as follows: We start in Sect. 2 by giving a literature review. Then in Sect. 3 we carefully define the lockup premium. The new Markov chain models are then defined in Sect. 4. In Sect. 5 we develop our new algorithms for fitting the parameters. We indicate how to calculate the lockup premium in Sect. 6. In Sect. 7 we perform sensitivity analysis, showing how the model parameters and the lockup premium depend on basic hedge fund performance measures. Finally, in Sect. 8 we draw conclusions.

2 Literature review

We will be brief in our literature review, because an extensive review was given in DPW09. We will emphasize recent contributions since DPW09.

First, it is good to put the definition of lockup premium in perspective with the broader literature on liquidity. Clearly, an investor under the lockup condition naturally should require compensation or additional return from his investment in hedge funds for limited rebalancing activities during the lockup period, which we define as the lockup premium. Our definition of the lockup premium corresponds to the liquidity premium in the asset pricing literature; see Longstaff (1995, 2001) and Browne et al. (2003). As stated in Sect. 1 of this paper and the above papers, the calculation of the premium can be done by comparing the expected returns in the two investments, with and without the liquidity condition. This approach of the liquidity premium calculation is also relevant for accounting regulation (FAS No. 157, "Fair Value Measurements") to discount illiquidity in a portfolio (Ang and Bollen 2009).

Similar to DPW09, Ang and Bollen (2009) propose a variant of a binomial lattice model to calculate the lockup premium as a function of the lockup period and notice period. They estimate the premium for a two-year lockup with a three-month notice period is approximately 1 %, which is also similar to our result. However, while their model allows a time-dependent default probability, their model assumes independence of increment returns. We think that independent increments may not hold, especially for an illiquid investment like a hedge fund. Our view is supported by e.g., Agarwal and Naik (2000), Edwards and Caglayan



(2001), Koh et al. (2003), Jagannathan et al. (2010), and DPW09 who all provide support the existence of persistence in hedge-fund returns in various ways. See, the discussion and the references in DPW09 and Derman et al. (2010) for the details. Recent studies like Boyson et al. (2010) which study downside correlations in hedge funds and Stoyanov et al. (2013) which point out autocorrelation in asset returns also support our view.

There also are a few purely empirical studies, without employing stochastic models. First, Aragon (2007) empirically compares the performance of hedge funds with and without the one-year lockup condition. The average difference between returns of the hedge funds with and without the lockup condition is estimated by 4 to 7 % in Aragon (2007). However, that study does not differentiate various lockup periods in the data and regards all different lockup periods as one year. Thus the estimated lockup premium is not a function of the lockup period. De Roon et al. (2009) also estimate the lockup premium empirically where an investor has a portfolio of stocks, bonds, and hedge funds. They estimate the three-month lockup costs the investor 4.11 % annually. However, just as Aragon (2007), they did not calculate the lockup premium for other lockup periods than three months.

3 Definition of the lockup premium

In this section, we carefully define the premium for extended hedge-fund lockups that we will use with our new Markov chain models. Since the hedge fund returns in the database are reported monthly at most, it is reasonable to consider a discrete process. We thus consider a discrete-time return stochastic process $B = \{B_i : i = 1, 2, 3, ...\}$. Each time period i in the process represents an *updating time* for the returns. We can study the model with different updating time period T_u for updates, if we wish. For example, $T_u = 0.25$ implies quarterly updating of the process B, while $T_u = 0.5$ represents semi-annual updating of returns. We assume that the number of updates in a year, $k = 1/T_u$, is always an integer, which usually is the case in practice. While $T_u = 1$ in the DTMC model, $1/T_u$ can be any integer in the CTMC model.

We let B_i represent a continuously compounded (random) rate of return for the ith updating period, by which we mean that e^{B_i} is the (random) value at the end of ith updating period ($i \cdot T_u$ year) of one dollar invested in this investment at the beginning of (i-1)th updating period ((i-1) · T_u year). (Notice that B_i depends on T_u in this definition. For example, B_i is an annually-updated return process when $T_u=1$, whereas B_i is a semi-annually updated return process when $T_u=0.5$.)

Consequently, the (random) total value at the end of n years of one dollar invested in this investment at the beginning of the first year, V_{n,T_n} , is the $(n \cdot k)$ -fold product

$$V_{n,T_u} = e^{\sum_{i=1}^{n \cdot k} B_i}, (3.1)$$

where k is the number of updating (reporting) periods per year and n is the number of years. We let r_n be the deterministic value for which

$$e^{nr_n} = \mathbb{E}[V_{n,T_n}] \tag{3.2}$$

for V_{n,T_u} in (3.1); i.e., we let r_n be the constant rate of return, with continuous compounding, that yields the same expected value $\mathbb{E}[V_n]$ over n years. We call r_n simply the *rate of return* of this investment. What we have done follows common practice. We have "backed out" the



rate of return r_n from the expected cash value $\mathbb{E}[V_n]$. By (3.1) and (3.2), r_n can be expressed directly as

$$r_n = \frac{\log \mathbb{E}[V_n]}{n} = \frac{1}{n} \log \left(\mathbb{E}[e^{(\sum_{i=1}^{n \cdot k} B_i)}] \right), \tag{3.3}$$

where we use the natural logarithm (base e).

Now consider two different investment opportunities in hedge funds with the same strategy, but one with a conventional 1-year lockup and the other with an n-year lockup condition. Let B^1 be the return stochastic processes with the 1-year lockup condition; let B^2 be the return stochastic processes with the n-year lockup condition. Let the n-year lockup premium p_n be

$$p_n \equiv r_n^1 - r_n^2,\tag{3.4}$$

where r_n^i is the rate of return of B^i , defined as in (3.3), over an *n*-year horizon.

Instead of working with B_i directly, we focus on *relative return rates* for each fund strategy. To do so, we let $\alpha_i \equiv \mathbb{E}[B_i]$, the mean return rate for a particular hedge fund strategy within updating period of return i. This quantity is estimated by the mean of B_i over all funds within that strategy. Then the (random) relative return rate is

$$R_i \equiv B_i - \mathbb{E}[B_i] \equiv B_i - \alpha_i. \tag{3.5}$$

Combining equations (3.1) and (3.5), we see that the (random) total value at the end of year n from investor j is

$$V_{n,T_u}^j = \prod_{i=1}^{n \cdot k} e^{(\alpha_i + R_i)} = e^{(\sum_{i=1}^{n \cdot k} \alpha_i)} e^{(\sum_{i=1}^{n \cdot k} R_i^j)}$$
(3.6)

and the difference between the expected total returns is

$$\mathbb{E}[V_{n,T_{u}}^{1}] - \mathbb{E}[V_{n,T_{u}}^{2}] = e^{(\sum_{i=1}^{n-k} \alpha_{i})} (\mathbb{E}[e^{(\sum_{i=1}^{n-k} R_{i}^{1})}] - \mathbb{E}[e^{(\sum_{i=1}^{n-k} R_{i}^{2})}]). \tag{3.7}$$

Hence, the premium in (3.4) becomes

$$p_n \equiv r_{n,T_u}^1 - r_{n,T_u}^2 = \frac{1}{n} \left[\log \left(\mathbb{E} \left[e^{(\sum_{i=1}^{n-k} R_i^1)} \right] \right) - \log \left(\mathbb{E} \left[e^{(\sum_{i=1}^{n-k} R_i^2)} \right] \right) \right], \tag{3.8}$$

which is independent of the average rates α_i . We need a model that describe the behavior of R_i^j in (3.8).

4 The new Markov chain models

In this section, we propose a model that uses an absorbing CTMC to model the evolution of the fund state in time and an ergodic DTMC to model the state of the fund at the updating times (when returns are reported). (Since there is a positive probability of transition from good to sick in finite time and a positive probability of transition from sick to dead in finite time, the absorbing CTMC would eventually end up in the dead state with probability 1 (over an infinitely long horizon), whereas the ergodic DTMC has a proper limiting steady-state distribution.) In the CTMC model, a fund changes its state in continuous time, but the investment updates take place in discrete time. This leads us to an ergodic DTMC for investment update that is based on the CTMC; see Ross (2003) for background on both kinds of Markov chains.



4.1 The transition matrix of the absorbing CTMC

Just as in DPW09, our CTMC has three states for a hedge fund: good, sick and dead. Now we assume that transitions among these states occur according to a CTMC, specifically a birth-and-death process.

In the DTMC model in DPW09, a hedge fund in a good state cannot reach a dead state until two years. In contrast, with the CTMC model, a fund can be in a dead within one year. There is a cost, however: for the CTMC model, we are unable to fit the model parameters simply by explicitly solving three equations in three unknowns. Instead, we develop an algorithm to carry out the model fitting numerically. With our algorithm, the parameter fitting for the CTMC model is not substantially harder than for the DTMC model.

In our proposed CTMC model we replace the three-state absorbing DTMC in DPW09 by a two-state absorbing CTMC. The states now are G (Good) and S (Sick); we do not directly use the state D (Dead) here, but we will be able to account for it. As usual, we specify the CTMC by specifying its infinitesimal transition rate matrix Q. That means we specify the birth and death rates. Let μ_G be the death rate in G, the rate of transition down to state S from state S. Let S be the birth rate in state S, the rate of transition up to state S from state S. Let S be the death rate in state S, implicitly the rate of transition down to state S from state S. (The fund may leave state S to go to state S, but gets absorbed in S. We do not need to include the state S in our transition rate matrix.) Here is the infinitesimal transition matrix, with the parameters above:

$$Q = \frac{G}{S} \begin{pmatrix} -\mu_G & \mu_G \\ \lambda_S & -(\lambda_S + \mu_S) \end{pmatrix}. \tag{4.9}$$

We now want to derive the time-dependent transition probability matrix P(t) for this CTMC. It is well-known that P(t) is the solution to the matrix ordinary differential equation

$$P(t)' = P(t)Q, \quad P(0) = I,$$
 (4.10)

where I is the identity matrix, so that P(t) is the matrix exponential $P(t) = e^{tQ}$. If we diagonalize Q so that $Q = UDU^{-1}$, where D is a diagonal matrix and $UU^{-1} = I$, then we can write $P(t) = Ue^{tD}U^{-1}$; see Sect. 4.8 and the appendix of Karlin and Taylor (1975). Since D is a diagonal matrix, the ith diagonal element of etD is related to the corresponding diagonal element of D, i.e., $(e^{tD})_{i,i} = e^{D_{i,i}t}$ for t > 0. Let $\Lambda(t)$ be a diagonal matrix of the form

$$\Lambda(t) = \frac{G}{S} \begin{pmatrix} e^{\eta_G t} & 0\\ 0 & e^{\eta_S t} \end{pmatrix},\tag{4.11}$$

with the two parameters η_G and η_S being the eigenvalues of the matrix Q, while the columns of U are the associated right eigenvectors. The resulting formula for P(t) is

$$P(t) = U\Lambda(t)U^{-1}. (4.12)$$

The characterization (4.12) implies that $P_{i,j}(t) = A_{i,j}e^{\eta_1 t} + B_{i,j}e^{\eta_2 t}$ for $t \ge 0$ and all state pairs (i, j), where η_1 and η_2 are the eigenvalues of Q and $A_{i,j}$ and $B_{i,j}$ are appropriate constants. Since P(0) = I, we necessarily have $A_{i,i} + B_{i,i} = 1$ for i = 1, 2 and $A_{i,j} + B_{i,j} = 0$ for $i \ne j$. If $0 > \eta_1 > \eta_2$, then asymptotically $P_{i,j}(t) \sim A_{i,j}e^{-\eta_1 t}$ as $t \to \infty$, which means that the ratio approaches 1. As a consequence, necessarily $A_{i,j} > 0$ for all state pairs (i, j); $B_{i,j} = -A_{i,j}$ for $i \ne j$.



As usual, we find the eigenvalues of Q by finding the determinant of $\eta I - Q$. The characteristic polynomial as a function of the variable η is the quadratic equation

$$(\eta + \lambda_S + \mu_S)(\eta + \mu_G) - \lambda_S \mu_G = 0, \tag{4.13}$$

which has two strictly negative roots, as required for the formula in (4.11) to yield bonafide probabilities. In particular, solving the quadratic equation, we obtain

$$\eta = \frac{-(\lambda_S + \mu_S + \mu_G) \pm \sqrt{(\lambda_S + \mu_S + \mu_G)^2 - 4\mu_S \mu_G}}{2}.$$
 (4.14)

Since the term inside the square root can be rewritten as $(\mu_G - \mu_S)^2 + \lambda_S^2 + 2\mu_G\lambda_S + 2\lambda_S\mu_S$, it is nonnegative. The first term clearly dominates the square root in absolute value. So we indeed have two negative roots.

Now we find eigenvectors corresponding to the eigenvalues in (4.14). Given eigenvalues, the eigenvectors form the null space of $(Q - \eta I)$, i.e., a matrix U such that $(Q - \eta I)U = 0$. We arrange eigenvalues η_G , η_S as η matrix:

$$\eta = \begin{pmatrix} \eta_G \\ \eta_S \end{pmatrix} = \begin{pmatrix} \frac{-(\lambda_S + \mu_S + \mu_G) - \sqrt{(\lambda_S + \mu_S + \mu_G)^2 - 4\mu_S\mu_G}}{2} \\ \frac{-(\lambda_S + \mu_S + \mu_G) + \sqrt{(\lambda_S + \mu_S + \mu_G)^2 - 4\mu_S\mu_G}}{2} \end{pmatrix}. \tag{4.15}$$

Such an eigenvector matrix U, where the columns of U are eigenvectors of Q, can be easily found by algebraic manipulation or by a symbolic calculation package such as Mathematica. One such eigenvalue matrix is

$$U = \begin{pmatrix} \frac{(\lambda_S + \mu_S - \mu_G) - \sqrt{(\lambda_S + \mu_S + \mu_G)^2 - 4\mu_S \mu_G}}{2\lambda_S} & \frac{(\lambda_S + \mu_S - \mu_G) + \sqrt{(\lambda_S + \mu_S + \mu_G)^2 - 4\mu_S \mu_G}}{2\lambda_S} \\ 1 & 1 \end{pmatrix}. \quad (4.16)$$

Its inverse matrix is then

$$U^{-1} = \begin{pmatrix} -\frac{\lambda_{S}}{\sqrt{(\lambda_{S} + \mu_{S} + \mu_{G})^{2} - 4\mu_{S}\mu_{G}}} & \frac{\lambda_{S} + \mu_{S} - \mu_{G} + \sqrt{(\lambda_{S} + \mu_{S} + \mu_{G})^{2} - 4\mu_{S}\mu_{G}}}{2\sqrt{(\lambda_{S} + \mu_{S} + \mu_{G})^{2} - 4\mu_{S}\mu_{G}}} \\ \frac{\lambda_{S}}{\sqrt{(\lambda_{S} + \mu_{S} + \mu_{G})^{2} - 4\mu_{S}\mu_{G}}} & \frac{-\lambda_{S} - \mu_{S} + \mu_{G} + \sqrt{(\lambda_{S} + \mu_{S} + \mu_{G})^{2} - 4\mu_{S}\mu_{G}}}{2\sqrt{(\lambda_{S} + \mu_{S} + \mu_{G})^{2} - 4\mu_{S}\mu_{G}}} \end{pmatrix}. \tag{4.17}$$

Thus, we now have derived the components of P(t) in (4.12). We have derived P(t) as a nonlinear function of μ_G , λ_S and μ_S from (4.15)–(4.17).

4.2 The associated ergodic DTMC

We are now ready to specify the evolution of the hedge fund at successive updating times. We will characterize these transitions by an ergodic two-state DTMC, whose transition probabilities are obtained from the time-dependent transition probabilities of the absorbing CTMC developed above.

Since a dead fund is replaced immediately by a good fund at the updating time, we make an ergodic two-state DTMC with transition matrix

$$P = \frac{G}{S} \begin{pmatrix} 1 - P_{G,S}(T_u) & P_{G,S}(T_u) \\ 1 - P_{S,S}(T_u) & P_{S,S}(T_u) \end{pmatrix}. \tag{4.18}$$

We construct P in (4.18) by letting $P_{G,S} = P_{G,S}(T_u)$ and $P_{S,S} = P_{S,S}(T_u)$ and then making the DTMC ergodic by letting the row sums be 1. This procedure is tantamount to inserting an instantaneous transition from state D to G at time T_u , which is the time of a single transition in the DTMC. This transition probabilities are used to model the process R_i^j in (3.8).

As usual, the steady-state vector for this DTMC is obtained by solving the equation $\pi = \pi P$ for a probability vector $\pi \equiv (\pi_G, \pi_S)$. In this simple 2 × 2 case, we can give the steady-state probability vector π explicitly as

$$\pi \equiv (\pi_G, \pi_S) = \left(\frac{1 - P_{S,S}(T_u)}{1 - P_{S,S}(T_u) + P_{G,S}(T_u)}, \frac{P_{G,S}(T_u)}{1 - P_{S,S}(T_u) + P_{G,S}(T_u)}\right). \tag{4.19}$$

5 Parameter fitting in the CTMC model

Just as we fit the three parameters $p = P_{G,G}$, $q = P_{S,G}$ and $r = P_{S,S}$ in the DTMC transition matrix to performance measures estimated from the TASS data in DPW09, here instead we fit the three parameters λ_S , μ_S , and μ_G in the CTMC transition rate matrix (4.9) to the three hedge-fund performance measures.

5.1 The persistence and death fitting equations

The first performance measure for model fitting is the persistence factor of relative returns. As indicated in the introduction, a persistence level γ means that for every 1 percentage point earned above the average in the current year, we expect to earn γ percentage points above the average in the next year. We define a time period T_p to measure the persistence factor. For example, $T_p=1$ implies that the persistence factor is measured with annual relative returns whereas $T_p=0.5$ means that it is measured with semi-annual relative returns. Papers on persistence of hedge-fund returns use different measurement times ranging from one quarter to three years (see, Sect. 4 of DPW09 for the details). Thus, allowing variable T_p could be useful if one has different views of the measurement time for persistence. The time periods T_u and T_p can be different in our model, while they were both 1 in the DTMC model.

We let Y_G , Y_S , and Y_D represent the annual relative returns that an investor makes at each updating time from a good, sick, and dead fund, respectively. As before, we will take these as given parameters, based on the data, but we will also discuss how to get reasonable estimates of these values below.

We now proceed toward parameter fitting for this new model. We first define an equation that fits observed persistence within a specific strategy. As in DPW09, we allow different persistence factors in the states G and S. Paralleling (6.5)–(6.6) in DPW09, we obtain the new equations

$$\gamma_G \cdot Y_G = P_{G,G}(T_p) \cdot Y_G + P_{G,S}(T_p) \cdot Y_S + \left\{ 1 - P_{G,G}(T_p) - P_{G,S}(T_p) \right\} Y_D \tag{5.20}$$

and

$$\gamma_S \cdot Y_S = P_{S,G}(T_p) \cdot Y_G + P_{S,S}(T_p) \cdot Y_S + \left\{ 1 - P_{S,G}(T_p) - P_{S,S}(T_p) \right\} Y_D. \tag{5.21}$$

Both sides of the equations above represent expected relative returns, starting with a good or sick state. Both exploit the definition of persistence.



Fig. 1 Survival probability curves for the CTMC model with $\delta = 0.03, 0.06$, and 0.09 with $T_u = T_p = T_d = 1$. The parameters values $\mu_G, \lambda_S, \mu_S, Y_G, Y_S, Y_D$, and σ are from Table 1

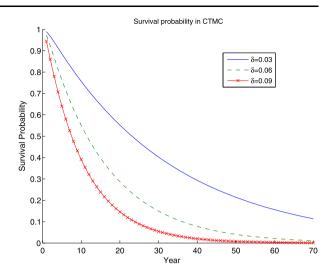


Table 1 Parameter values for the CTMC model as a function of δ with $Y_S = -0.15$, $Y_D = -0.20$, $\sigma = 0.1$, $\gamma_G = \gamma_S = 0.5$, $T_D = T_U = T_d = 1$

| δ | μ_G | λ_S | μ_S | Y_G | Y_S | Y_D | σ | ϵ |
|------|---------|-------------|---------|--------|-------|-------|--------|-------------------------|
| 0.00 | 0.2133 | 0.4798 | 0.0000 | 0.0667 | -0.15 | -0.20 | 0.1000 | 2.2626×10^{-7} |
| 0.03 | 0.2191 | 0.5533 | 0.1250 | 0.0684 | -0.15 | -0.20 | 0.1000 | 2.8191×10^{-7} |
| 0.06 | 0.2262 | 0.7025 | 0.3495 | 0.0699 | -0.15 | -0.20 | 0.1000 | 3.1488×10^{-7} |
| 0.09 | 0.2386 | 1.0980 | 0.8726 | 0.0713 | -0.15 | -0.20 | 0.1000 | 5.3025×10^{-6} |

Next, paralleling Eq. (6.4) in DPW09, we also have an equation based on the probability of the fund ceasing to exist (dying) within a specified time. Specifically, we introduce an equation giving the probability of death within the time period T_d , where T_d may differ from T_u and T_p ; i.e.,

$$\delta \equiv \delta(T_d) = \pi_G \left\{ 1 - P_{G,G}(T_d) - P_{G,S}(T_d) \right\} + \pi_S \left\{ 1 - P_{S,G}(T_d) - P_{S,S}(T_d) \right\}. \tag{5.22}$$

Notice that the new model is more flexible because the three times T_u , T_p , and T_d can be different.

With Eq. (5.22), we can derive the survival probability from the CTMC model, which is closely related to the death probability. At time t, the *survival probability* of a fund is defined as

$$S(t) = P_{G,G}(t) + P_{G,S}(t) \quad \text{for } t \ge 0.$$
 (5.23)

Figure 1 displays the survival probabilities for the CTMC model with $\delta = 0.03$, 0.06 and 0.09 (and other parameter values from Table 1). The survival probability for $\delta = 0.09$ is possible only in the CTMC model, since for the DTMC model, r becomes negative when $\delta \approx 0.07$. As we see from Fig. 1, median fund life is less than 10 years for $\delta = 0.09$. Since this median hedge fund life is within the range of Rouah (2006) and Park (2007), it should be worth considering $\delta = 0.09$. We could not do this before in DPW09.



5.2 Solving the Three Equations in Three Unknowns

We now show how to solve the three equations (5.20), (5.21) and (5.22) for the three unknowns μ_G , μ_S and λ_S . Unfortunately, we have been unable to obtain explicit solutions for the desired parameters as we did in DPW09. Hence, we develop an effective numerical algorithm.

Suppose that we start with a candidate initial parameter triple $(\mu_G, \lambda_S, \mu_S)$. Given that parameter triple and the specified time t, we calculate the transition probabilities $P_{G,G}(t)$, $P_{G,S}(t)$, $P_{S,G}(t)$, and $P_{S,S}(t)$ in (4.12)–(4.14) by calculating the eigenvalues and eigenvectors of the infinitesimal matrix Q in (4.9). Afterwards we calculate the steady-state probability vector $\pi \equiv (\pi_G, \pi_S)$ in (4.19) of the two-state DTMC in (4.18). We then calculate the right-hand sides of the three equations (5.20)–(5.22). Our goal is to have three bonafide equations, where the two sides of the equations are equal, but in the iteration we will not achieve that. Based on the errors we see, we update the parameter triple $(\mu_G, \lambda_S, \mu_S)$ and repeat until the errors in the three equations (5.20)–(5.22) are negligible. Notice that T_u , T_u , and T_p are all constant so they do not add any complexity to the system of equations.

Since we are confronted with a three-dimensional iteration, we do not want to proceed in a haphazard way. Hence, we apply nonlinear programming to do this iteration. The idea is to find parameter triple (λ_S , μ_S , μ_G) minimizing errors between the right-hand and left-hand sides of Eqs. (5.20), (5.21) and (5.22). To formulate a minimization problem, we define three error functions ϵ_1 , ϵ_2 and ϵ_3 as a function of parameter triple (λ_S , μ_S , μ_G) as follows:

$$\epsilon_{1} \equiv \epsilon_{1}(\lambda_{S}, \mu_{S}, \mu_{G}) = \delta(T_{u}) - \pi_{G} \left\{ 1 - P_{G,G}(T_{d}) - P_{G,S}(T_{d}) \right\}$$

$$- \pi_{S} \left\{ 1 - P_{S,G}(T_{d}) - P_{S,S}(T_{d}) \right\},$$

$$\epsilon_{2} \equiv \epsilon_{2}(\lambda_{S}, \mu_{S}, \mu_{G}) = \gamma_{G} \cdot Y_{G} - P_{G,G}(T_{p}) \cdot Y_{G} - P_{G,S}(T_{p}) \cdot Y_{S}$$

$$- \left\{ 1 - P_{G,G}(T_{p}) - P_{G,S}(T_{p}) \right\} Y_{D},$$

$$\epsilon_{3} \equiv \epsilon_{3}(\lambda_{S}, \mu_{S}, \mu_{G}) = \gamma_{S} \cdot Y_{S} - P_{S,G}(T_{p}) \cdot Y_{G} - P_{S,S}(T_{p}) \cdot Y_{S}$$

$$- \left\{ 1 - P_{S,G}(T_{p}) - P_{S,S}(T_{p}) \right\} Y_{D}.$$

$$(5.24)$$

Our objective, then, is to find λ_S , μ_S and μ_G such that $\epsilon_1(\lambda_S, \mu_S, \mu_G) = \epsilon_2(\lambda_S, \mu_S, \mu_G) = \epsilon_3(\lambda_S, \mu_S, \mu_G) = 0$. To obtain values of ϵ_1 , ϵ_2 , and ϵ_3 for a given parameter triple of λ_S , μ_S and μ_G , we have to calculate $P_{G,G}(T)$, $P_{G,S}(T)$, $P_{S,G}(T)$, which are elements of P(t) matrix in (4.12). As indicated above, this involves finding eigenvalues and eigenvectors of Q matrix in (4.9). From (4.14), we derived eigenvalues as a function of λ_S , μ_S and μ_G . Given the eigenvalues, the eigenvectors can be calculated as in (4.16), but also in other ways. Since Q is only a 2 × 2 matrix, calculation of the eigenvectors for given eigenvalues can be done easily. One way is to use the Schur decomposition algorithm, as in Anderson et al. (1999), which is implemented in MATLAB as the eig function. Then $\Lambda(t)$ can be calculated easily from (4.11), so we can easily compute the U and Λ matrices numerically. The final step is to compute $P_{G,G}(t)$, $P_{G,S}(t)$ and $P_{S,G}(t)$ from $P(t) = U\Lambda(t)U^{-1}$.

We can obtain the desired parameter triple $(\lambda_S, \mu_S, \mu_G)$ by solving the following constrained minimization problem:



$$\min_{\lambda_S, \mu_S, \mu_G} \max\{|\epsilon_1|, |\epsilon_2|, |\epsilon_3|\}$$

s.t.

$$\epsilon_{1} = \delta(T_{u}) - \pi_{G} \left(1 - P_{G,G}(T_{u}) - P_{G,S}(T_{u}) \right) - \pi_{S} \left\{ 1 - P_{S,G}(T_{u}) - P_{S,S}(T_{u}) \right\},$$

$$\epsilon_{2} = \gamma_{G} \cdot Y_{G} - P_{G,G}(T_{p}) \cdot Y_{G} - P_{G,S}(T_{p}) \cdot Y_{S} - \left\{ 1 - P_{G,G}(T_{p}) - P_{G,S}(T_{p}) \right\} Y_{D},$$

$$\epsilon_{3} = \gamma_{S} \cdot Y_{S} - P_{S,G}(T_{p}) \cdot Y_{G} - P_{S,S}(T_{p}) \cdot Y_{S} - \left\{ 1 - P_{S,G}(T_{p}) - P_{S,S}(T_{p}) \right\} Y_{D}$$

$$\lambda_{S}, \mu_{S}, \mu_{G} \ge 0$$
(5.25)

With (5.25), we regard λ_S , μ_S and μ_G as the variables. Since the transition probabilities $P_{G,G}(t)$, $P_{G,S}(t)$ and $P_{S,G}(t)$ are functions of the BD rates λ_S , μ_S and μ_G through the eigenvalue and eigenvector calculation, we must regard (5.25) as a nonlinear programming (NLP) problem, for which it is natural to apply an iterative procedure. However, since we only have three variables, we are able to solve the NLP (5.25) easily. One effective way is to use Sequential Quadratic Programming (SQP), as in Schittkowski (1986). With SQP, at each iteration, an approximation is made of the Hessian of the Lagrangian function using a quasi-Newton updating method. That is then used to generate a QP subproblem whose solution is used to form a search direction for a line search procedure. This algorithm is implemented in MATLAB via the functions *fminsearch* and *fmincon*. Both functions solve (5.25) within seconds.

5.3 The variance and the return of a good fund

So far, we have assumed that the three returns Y_G , Y_S and Y_D in the three states can be specified in advance. We can specify one of these, which we take to be Y_G , by exploiting an equation for the variance of the relative annual returns in steady state. Since we are focusing on the relative returns, the variance σ^2 coincides with the second moment.

To express the steady state variance σ^2 , we need the steady-state probabilities. Given that π_G and π_S are the stationary probabilities for the transition matrix in (4.18), the stationary probability that the fund dies at the end of T_u years when it starts alive is

$$\pi'_{D} = \pi_{G} \left[-P_{G,G}(T_{u}) - P_{G,S}(T_{u}) \right] + \pi_{S} \left[1 - P_{S,G}(T_{u}) - P_{S,S}(T_{u}) \right]$$
 (5.26)

We then also define π'_G and π'_S accordingly, using (4.19):

$$\pi'_{G} = \pi_{G} \cdot P_{G,G}(T_{u}) + \pi_{S} \cdot P_{S,G}(T_{u})$$

$$\pi'_{S} = \pi_{G} \cdot P_{G,S}(T_{u}) + \pi_{S} \cdot P_{S,S}(T_{u})$$
(5.27)

where (π_G, π_S) is defined in (4.19).

We obtain an expression for the steady-state variance of returns by supposing that the returns in good, sick and dead states are the deterministic values Y_G , Y_S and Y_D , respectively. Thus, the variance satisfies the equation

$$\sigma^{2} = \pi'_{G} \cdot Y_{G}^{2} + \pi'_{S} \cdot Y_{S}^{2} + \pi'_{D} \cdot Y_{D}^{2}, \tag{5.28}$$

where π' is defined in (5.26) and (5.27).

We applied Eq. (5.28) to determine Y_G for given $Y_S \equiv -1.5\sigma$ and $Y_D \equiv -2.0\sigma$, just as DPW09. To do so, we simply iterate on the two parameters Y_G and σ^2 , using a simple



bisection search. As in Fig. 7 of DPW09, we found that there is a nearly linear positive relation between Y_G and σ^2 for given Y_S and Y_D . Thus, we are able to easily achieve any desired σ , such as $\sigma \approx 0.1$, by iterating Y_G .

While we can use judgment to specify the values of Y_S and Y_D to use as the returns in the sick and dead states, we can also define these relative returns by exploiting two thresholds U and L, as in DPW09. We can classify the fund as good, sick or dead if the relative return falls in the interval $[U, \infty)$, (L, U) or $(-\infty, L]$, respectively. With this classification, we can let Y_S and Y_D be the average returns in the sick and dead intervals. The fitting algorithm then provides an estimate of the parameters μ_G , μ_S , λ_S and Y_G as a function of the time parameters T_P , T_U and T_d , the persistence parameters Y_G and Y_S , the death parameter δ and the relative return parameters Y_S and Y_D . As we will illustrate, this provides an opportunity to do sensitivity analysis.

5.4 Application of the algorithm

Below are parameter values obtained using the NLP in (5.25) and iterating Y_G values. In Table 1, ϵ records the maximum absolute value of errors in Eqs. (5.20), (5.21) and (5.22), obtained where we elected to terminate the algorithm. We let $T_p = T_u = 1$ for simplicity but these may have any values, depending on the time measure from the data.

Unlike the DTMC model, where the parameter r becomes negative if δ exceeds 0.07 for the base-case parameter values, for the CTMC we can fit the model to δ up to around 0.13. When $\delta \approx 0.13$, we observe that the CTMC lockup premium becomes nearly 0.

6 The lockup premium calculation

Once we have fit all the parameters, we can calculate the lockup premium. Denote the initial state of a fund by S_0 . For a benchmark case (no extended lockup), at the end of each updating time (T_u), investor can redeem his money from sick fund and reinvest the money in the good fund. Thus all funds start with a good state in each time period. In this case, the fund's annual return up to n year is

$$\mathbb{E}\left[e^{\sum_{i=1}^{n \cdot k} R_i^1} | S_0 = G\right] = \left[P(T_u)_{G,G} \cdot e^{Y_G} + P(T_u)_{G,S} \cdot e^{Y_S} + P(T_u)_{G,D} \cdot e^{Y_D}\right]^{n \cdot k}. \tag{6.29}$$

Now we consider a fund in n-year lockup case. The fund's expected return up to n year if the fund is under n-year lockup is

$$\mathbb{E}\left[e^{\sum_{i=1}^{n\cdot k} R_i^2} | S_0 = G\right]. \tag{6.30}$$

Unlike (6.29), calculation of (6.30) is not immediate, but it can be done by a recursion. Recall that the transition probability in the CTMC model, P(t), is obtained in (4.18). Define

$$m(t,s) \equiv \mathbb{E}\left[e^{\sum_{i=1}^{t} R_i^2} | S_0 = G, S_t = s\right] \cdot P(t)_{G,s},$$
 (6.31)

where P(t) defined in (4.12) represents the probability of reaching S_t from G at time t.



Conditioning on the state of a fund at time t, (6.31) is obtained from the following recursion formulas:

$$m(t,G) = P(T_u)_{G,G} \cdot e^{Y_G} \cdot m(t-1,G) + P(T_u)_{S,G} \cdot e^{Y_G} \cdot m(t-1,S)$$

$$m(t,S) = P(T_u)_{G,S} \cdot e^{Y_S} \cdot m(t-1,G) + P(T_u)_{S,S} \cdot e^{Y_S} \cdot m(t-1,S) \quad \text{and}$$

$$m(t,D) = \left(1 - P(T_u)_{G,G} - P(T_u)_{G,S}\right) e^{Y_D} \cdot m(t-1,G)$$

$$+ \left(1 - P(T_u)_{S,G} - P(T_u)_{S,S}\right) e^{Y_D} \cdot m(t-1,S),$$

$$(6.32)$$

where $m(1, G) = P(T_u)_{G,G} \cdot e^{Y_G}$, $m(1, S) = P(T_u)_{G,S} \cdot e^{Y_S}$ and $m(1, D) = (1 - P(T_u)_{G,G} - P(T_u)_{G,S})e^{Y_D}$. Notice that, if a fund becomes dead before year n, it starts with a good state. Furthermore, the new good fund is now under 1-year lockup instead of n-year. Because of this, care must be taken for a sample path once a fund becomes dead. We finally have

$$\mathbb{E}\left[e^{\sum_{i=1}^{n\cdot k} R_i^2} | S_0 = G\right] = m(n \cdot k, G) + m(n \cdot k, S) + \sum_{t=1}^{n\cdot k} m(t, D) \left(P(T_u)_{G,G} e^{Y_G} + P(T_u)_{G,S} e^{Y_S}\right)^{n \cdot k - t}.$$
(6.33)

Finally, the premium is calculated from (3.8) given that $S_0 = G$.

7 Sensitivity analysis for the new Markov chain model

In this section we do sensitivity analysis on the three performance measures, γ (γ_G , γ_S), δ and σ , respectively. We also analyze the impact of time periods used to estimate the performance measures, i.e., the updating time (T_u), the time used to compute the persistence factor (T_p), and the time period for computing the probability of death (T_d) on the lockup premium.

7.1 How the lockup premium depends on three performance measures

We first study how much the lockup premium depends on the death probability δ . Then, we see how much the premium depends on the model parameters $\gamma(\gamma_G, \gamma_S)$ and σ . When changing one performance measure in the sensitivity analysis, we fix all other measures just as the benchmark case with $\delta = 0.03$ in Table 1.

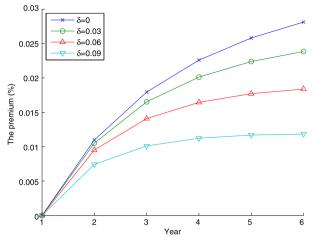
Table 1 shows the model parameters for $\delta = 0, 0.03, 0.06$, and 0.09 and Fig. 2 shows the lockup premium for different δ values. The figures show that as the death probability δ increases, the *n*-year lockup premium decreases. Notice that the CTMC model can incorporate the probability of death being 0.09 which is not possible in the DTMC model.

Table 2 shows the model parameters for $\gamma = 0.4, 0.5$, and 0.6 and Fig. 3(a) shows the lockup premium for $\gamma = 0.4, 0.5$, and 0.6. We observe that as the persistence factor γ increases, the *n*-year lockup premium increases.

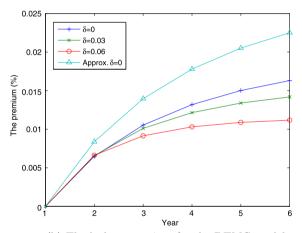
We next consider two separate persistence factors, γ_G and γ_S . The parameter values are given in Table 3 and the sensitivity of the lockup premium with respect to γ_G and γ_S is shown in Fig. 3(b). As γ_G increases and γ_S decreases, the fund in the state G tends to be in the same state while the fund in the S state tends to be in other states than the state S in the next time period. Since there is less chance of being in the state S, it is observed that the lockup premium decreases.



Fig. 2 The lockup premium for the CTMC model (a) and for the DTMC model (b) for $\delta = 0, 0.03, 0.06$, and 0.09. The parameter values come from Table 2. Panel (b) is re-reported from DPW09 for easy comparison



(a) The lockup premium for the CTMC model



(b) The lockup premium for the DTMC model

Table 2 Parameter value sets for γ ranging from 0.3 to 0.6

| γ | δ | μ_G | λ_S | μ_S | Y_G | Y_S | Y_D |
|-----|------|---------|-------------|---------|--------|-------|-------|
| 0.3 | 0.03 | 0.3750 | 0.9646 | 0.1184 | 0.0659 | -0.15 | -0.20 |
| 0.4 | 0.03 | 0.2868 | 0.7315 | 0.1210 | 0.0670 | -0.15 | -0.20 |
| 0.5 | 0.03 | 0.2204 | 0.5531 | 0.1240 | 0.0690 | -0.15 | -0.20 |
| 0.6 | 0.03 | 0.1642 | 0.4142 | 0.1317 | 0.0704 | -0.15 | -0.20 |

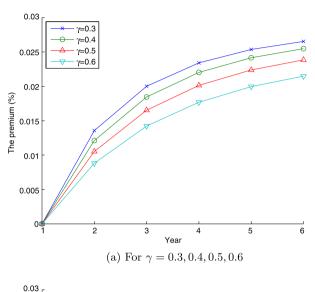
We lastly check the sensitivity of the lockup premium with respect to σ . Our TASS database analysis estimates σ of annual returns for each year is lower than 0.20 in most cases. We here highlight the sensitivity of the lockup premium for $\sigma=0.05, 0.10$, and 0.15 with $\gamma=0.5$. Table 4 provides the parameter value sets and Fig. 4 shows the corresponding lockup premiums. We see that the premium increases in σ .

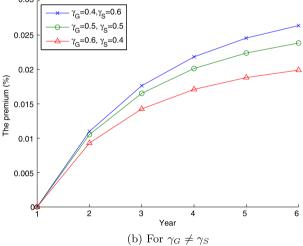


Table 3 Parameter value sets for γ_G and γ_S

| γ_G | γs | δ | μ_G | λ_S | μ_S | Y_G | Y_S | Y_D |
|------------|-----|------|---------|-------------|---------|--------|-------|-------|
| 0.4 | 0.6 | 0.03 | 0.2238 | 0.4430 | 0.1041 | 0.0585 | -0.15 | -0.20 |
| 0.5 | 0.5 | 0.03 | 0.2204 | 0.5531 | 0.1240 | 0.0690 | -0.15 | -0.20 |
| 0.6 | 0.4 | 0.03 | 0.1962 | 0.6807 | 0.1612 | 0.0768 | -0.15 | -0.20 |

Fig. 3 The lockup premium for the CTMC model (a) for $\gamma=0.3, 0.4, 0.5$ and 0.6 for other parameter values in Table 2 and (b) for $\gamma_G\neq\gamma_S$ for other parameter values in Table 3





7.2 How the lockup premium depends on the three time periods

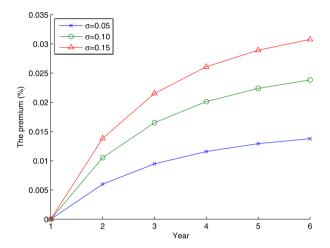
Calibration of the CTMC model is flexible, allowing the three key performance measures to be estimated with different time periods. Since the three measures can be estimated independently, allowing different time period for each measure could be helpful to an investor who has different views in these estimation time periods. In this section, we investigate how



| σ | δ | μ_G | λ_S | μ_S | Y_G | $Y_S = -1.5\sigma$ | $Y_D = -2.0\sigma$ |
|------|------|---------|-------------|---------|--------|--------------------|--------------------|
| 0.05 | 0.03 | 0.8434 | 0.3721 | 0.5025 | 0.0342 | -0.075 | -0.10 |
| 0.10 | 0.03 | 0.8434 | 0.3721 | 0.5025 | 0.0684 | -0.150 | -0.20 |
| 0.15 | 0.03 | 0.8434 | 0.3721 | 0.5025 | 0.1026 | -0.225 | -0.30 |

Table 4 Parameter value sets for $\sigma = 0.05, 0.10, 0.15$

Fig. 4 The lockup premium for the CTMC model for $\sigma=0.05, 0.10$, and 0.15. The parameter values come from Table 4



the lockup premium in the CTMC model depends on the three measurement times T_u , T_p , and T_d .

We first study how much the lockup premium depends on the updating period T_u . As T_u decreases, an investor can rebalance his portfolio of hedge funds more frequently. For a fixed lockup period, as T_u decreases, the investor has more updating frequencies in a year, which is restricted by the lockup condition. Thus if all the other parameter values are the same, the lockup premium may increase as T_u decreases. However, at the same time, the investor more frequently rebalances a fund in the state D with a fund in the state G, which may decrease the lockup premium. In Fig. 5, we numerically calculate the lockup premium up to six years for $T_u = 0.25, 0.5$, and 1 year. The parameter values are shown in Table 5. In order to compare the lockup premium for different T_u , we adjust annual relative return rates under good, sick, and dead states from ith to (i + 1)th updating time by multiplying T_u , i.e., $T_u Y_G$, $T_u Y_S$, and $T_u Y_D$. We then fit such parameters to the standard deviation of return for T_u , i.e., $\sigma \sqrt{T_u}$. Figure 5 shows that as the rebalance period increases, the lockup premium decreases. Thus it can be said that the investor requires more compensation for the lockup condition when there are more rebalancing opportunities that are missed because of the lockup period.

We also investigate the impact of T_p on the lockup premium. As T_p decreases, the persistence factor is observed in a shorter period. If the persistence factors are the same for different T_p , the impact of the persistence factor becomes higher with shorter T_p than with the longer one. Figure 6 shows that the lockup premium is increasing as T_p decreases, if γ remains the same for each T_p . Table 6 shows the parameter values.

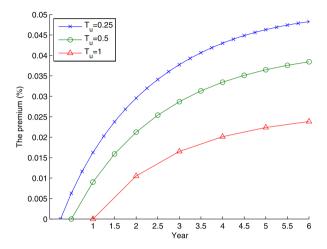
Lastly, we investigate how the lockup premium depends on T_d . If the death probability δ is the same for different T_d , the annual death probability with smaller T_d tends to produce



| T_u | μ_G | λ_S | μ_S | Y_G | $Y_S \equiv -1.5T_u \sigma \sqrt{T_u}$ | $Y_D \equiv -2.0T_u \sigma \sqrt{T_u}$ | $\sigma\sqrt{T_u}$ |
|-------|---------|-------------|---------|--------|--|--|--------------------|
| 0.25 | 0.5900 | 0.1084 | 0.0376 | 0.1068 | -0.038 | -0.05 | 0.0500 |
| 0.5 | 0.4358 | 0.2758 | 0.0531 | 0.0893 | -0.075 | -0.10 | 0.0708 |
| 1 | 0.2191 | 0.5533 | 0.1250 | 0.0684 | -0.150 | -0.20 | 0.1000 |

Table 5 Parameter value sets for $T_u = 0.25, 0.5, \text{ and } 1$

Fig. 5 The lockup premium for the CTMC model for $T_u = 0.25, 0.5$ and 1 years. The parameter values come from Table 5



more funds in state D for given time period. Figure 7 shows that the lockup premium is increasing as T_d increases. Table 7 shows the parameter values.

7.3 Comparison of the CTMC and the DTMC models

In this section, we compare the lockup premium in the CTMC model (Fig. 2) to the one in the DTMC model (Fig. 8(a) of DPW09).

First, we observe that the lockup premiums in the DTMC model and the CTMC model have similar values. However, we also observe that the lockup premium in the CTMC model is slightly larger than for the DTMC model under the same performance measures and lockup period.

We compare the transition probabilities in the DTMC and CTMC models under the same performance measures and measurement times (benchmark case) in order to understand this difference. We see that the transition probabilities from the state G to G in both models are almost the same (0.850 in the DTMC model, 0.846 in the CTMC model) and so are the transition probabilities from G to G. The probabilities from G to G are also similar (0.358 in the DTMC model and 0.365 in the CTMC model). However, the difference in transition probabilities from G to G (0.493 in the DTMC model and 0.543 in the CTMC model) is relatively bigger than the differences in other probabilities. Thus, a fund in the state G is more likely to stay in G in the next time period in the CTMC model than in the DTMC model, which makes the lockup premium slightly bigger in the CTMC model.

The transition probability from the state S to the state D in the DTMC model (0.132) is bigger than that (0.092) in the CTMC model. Recall that once a fund becomes dead in the state D, the lockup condition is not valid any more and the fund is replaced with a fund in



| T_p | μ_G | λ_S | μ_S | Y_G | $Y_S \equiv -1.5T_u \sigma$ | $Y_D \equiv -2.0T_u \sigma$ |
|-------|---------|-------------|---------|--------|-----------------------------|-----------------------------|
| 0.25 | 0.8163 | 2.0287 | 0.1103 | 0.0156 | -0.15 | -0.20 |
| 0.5 | 0.4182 | 1.0431 | 0.1148 | 0.0322 | -0.15 | -0.20 |
| 1 | 0.2191 | 0.5533 | 0.1250 | 0.0667 | -0.15 | -0.20 |

Table 6 Parameter value sets for $T_p = 0.25, 0.5, \text{ and } 1$

Fig. 6 The lockup premium for the CTMC model for $T_p=0.25, 0.5$ and 1 years. The parameter values come from Table 6

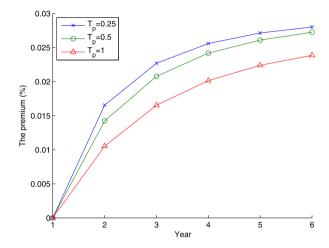
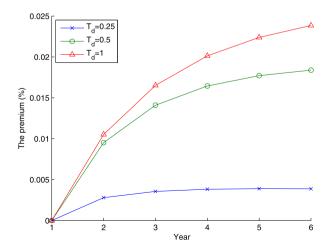


Table 7 Parameter value sets for $T_d = 0.25, 0.5, \text{ and } 1$

| T_d | μ_G | λ_S | μ_S | Y_G | $Y_S \equiv -1.5T_u \sigma$ | $Y_D \equiv -2.0T_u \sigma$ |
|-------|---------|-------------|---------|--------|-----------------------------|-----------------------------|
| 0.25 | 0.2744 | 3.5967 | 3.3273 | 0.0726 | -0.15 | -0.20 |
| 0.5 | 0.2262 | 0.7022 | 0.3491 | 0.0699 | -0.15 | -0.20 |
| 1 | 0.2191 | 0.5533 | 0.1250 | 0.0684 | -0.15 | -0.20 |

Fig. 7 The lockup premium for the CTMC model for $T_d=0.25, 0.5$ and 1 years. The parameter values come from Table 7





the state G, decreasing the lockup premium. This can also increase the lockup premium in the CTMC model.

Comparing the three equations (5.20)–(5.22) that are used to parameter fitting in the CTMC model to (6.4)–(6.6) in DPW09 in the DTMC model, we see that the difference is additional terms in (5.20) and (5.22) that incorporate the transition from G to D in one time period. As a result of these additional terms, the transition probability from S to S is larger and the transition probability from S to D is smaller in the CTMC model than in the DTMC model. We thus conclude that the lockup premium in the CTMC model increases slightly by allowing the transition from G to D in one year, which is caused by allowing the transition from the state G to the state D within one time period. We, however, observe that the difference of the lockup premium in the DTMC model and in the CTMC model can be as high as one percentage point (e.g. four-year lockup premium with S = 0.03) and can be even higher than one percentage point for the premium for five-year lockup or longer.

8 Conclusion

In this paper, we have developed new Markov chain models to calculate the premium from extended hedge-fund lockups. As in our previous paper DPW09, we use a highly stylized three-state model to represent the state of a hedge fund, using the states "good," "sick" and "dead." Since investors can redeem their investment (or part of it) and reinvest if the fund dies, the important state for extended hedge fund lockup is the sick state.

We define the lockup premium as a compensation to the investor for the opportunity cost of restricted re-balancing activities; see Sect. 3. In order to calculate the lockup premium, we compare two identical hedge funds with and without extended lockups. The premium is the fixed annual rate of return that makes the expected returns of the two funds the same.

The new CTMC model for the state of a hedge fund allows the fund state to change continuously in time. The previous DTMC model in DPW09 required transitions from good to dead to take at least two years. With the new CTMC model, that restriction is removed. The CTMC model also provides increased flexibility in modeling and performance-measure estimation. First, the CTMC model allows flexible performance measure estimation, e.g., semi-annually or quarterly from the data. Second, the CTMC model allows wider ranges of acceptable performance measures than the DTMC model does.

In Sect. 4 we gave an explicit representation of the ergodic two-state DTMC model based on the three CTMC model parameters μ_G , μ_S and λ_S . In order to calibrate these three parameters, in Sect. 5 we developed a nonlinear programming algorithm, which can be easily solved numerically with MATLAB. In order to calibrate the standard deviation of returns, σ , we used an efficient iterative search algorithm. Thus we succeeded in developing an efficient algorithm to carry out the model fitting. The model fitting yields the parameters μ_G , μ_S , λ_S and Y_G plus the premium for extended lockup as a function of the time parameters T_p , T_u and T_d , the persistence parameters γ_G and γ_S , the death parameter δ and the relative return parameters γ_S and γ_S , where the parameters γ_S and γ_S , δ , and δ can be estimated from historical data, as we illustrated by applying the TASS data. We then can compute the premium for extended lockup as a function of the number δ of years of extended lockup and again the time parameters γ_S , γ_S , and γ_S , the death parameters γ_S and the relative return parameters γ_S and γ_S , the death parameters γ_S and the relative return parameters γ_S and γ_S .

We then conducted sensitivity analysis to show how the premium for extended lockup depends on the variables. The sensitivity analysis quantifies how the lockup premium increases as a function of the persistence factor γ and the standard deviation σ , but decreases



as a function of the death probability δ . We also have examined how the lockup premium depends on different values of measurement times, T_u , T_p and T_d . We conclude that the impact of three performance measures— δ , γ and σ —have a significant impact on the lockup premium just as we saw for the DTMC models in DPW09. Also, we conclude that while the impact of T_p are relatively smaller on the lockup premium, the impact of T_u and T_d can be significant.

The numerical values of the lockup premium with the new Markov chain models are very similar to those for the previous DTMC model. We thus conclude that the more rudimentary DTMC model does not suffer greatly from its restriction to yearly updating. A slight increase in the lockup premium in the new model can be caused by allowing the transition from good to sick within one year. However, the difference of the lockup premium in the DTMC model and in the CTMC model can be as high as one percentage point or even higher than that (e.g. for four-year lockup premium with $\delta=0.03$), which can significantly change investment decision in practice.

Our approach in this paper may also be useful to study the appropriate premium for an extended lockup in other investment opportunities, provided that they have the good-sick-dead structure treated here. For example, the methods here may be useful to study private equity funds, where limited partners are expected to maintain their interest in the fund until it is unwound, typically over a ten-year life. The papers by Wu and Olson (2010a, 2010b) suggest that there may possibly be applications more broadly in enterprise risk management, where vendor selection may be binding for a long period. As a topic for future research, it may be interesting to adjust our model to incorporate regime-switching models based on continuous-time Markov chain to capture volatile state transitions; see Wahab and Lee (2011), Aigner et al. (2012) and the references therein for regime-switching models.

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