Efficient and Optimal Modal-set Estimation using kNN graphs

Samory Kpotufe ORFE, Princeton University

Based on various results with Sanjoy Dasgupta, Kamalika Chaudhuri, Ulrike von Luxburg, Heinrich Jiang

Motivation:

Density-based Clustering: group points into high-density regions.



- Flexibility: can identify any number of rich structures in data.
- Clear ground truth: targets concrete mathematical objects.
- Many applications: medical imaging, text mining, speech, vision, ...

However: Heuristics work better than theoretical methods :(

We want a **practical** procedure with **theoretical** guarantees!

Motivation:

Density-based Clustering: group points into high-density regions.



- Flexibility: can identify any number of rich structures in data.
- Clear ground truth: targets concrete mathematical objects.
- Many applications: medical imaging, text mining, speech, vision, ...

However: Heuristics work better than theoretical methods :(We want a **practical** procedure with **theoretical** guarantees!

Motivation:

Density-based Clustering: group points into high-density regions.



- Flexibility: can identify any number of rich structures in data.
- Clear ground truth: targets concrete mathematical objects.
- Many applications: medical imaging, text mining, speech, vision, ...

However: Heuristics work better than theoretical methods :(

We want a **practical** procedure with **theoretical** guarantees!

Common idea: cluster data around high-density cores!

... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



DBSCAN: cores are Connected-Components of a level set λ of f. Problem: which level λ ?

・ロト ・ 理 ト ・ ヨ ト ・ ヨ ト ・ ヨ

Common idea: cluster data around high-density cores! ... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



DBSCAN: cores are Connected-Components of a level set λ of f. Problem: which level λ ?

Common idea: cluster data around high-density cores! ... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



DBSCAN: cores are Connected-Components of a level set λ of f. Problem: which level λ ?

Common idea: cluster data around high-density cores! ... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



DBSCAN: cores are Connected-Components of a level set λ of f. Problem: which level λ ?

Common idea: cluster data around high-density cores! ... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



DBSCAN: cores are Connected-Components of a level set λ of f. Problem: which level λ ? (we can get \neq results)

Common idea: cluster data around high-density cores! ... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



・ロト ・ 理 ト ・ ヨ ト ・ ヨ ト ・ ヨ

MEAN-SHIFT: cores are *point-modes* (maxima) of *f*. **Problem:** unstable for general maxima ... hard to analyze.

Common idea: cluster data around high-density cores! ... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



・ロト ・ 日 ・ ・ 日 ・ ・ 日 ・ ・ 日

MEAN-SHIFT: cores are *point-modes* (maxima) of *f*. **Problem:** unstable for general maxima ... hard to analyze

Common idea: cluster data around high-density cores! ... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



・ロト ・ 理 ト ・ ヨ ト ・ ヨ ト ・ ヨ

MEAN-SHIFT: cores are *point-modes* (maxima) of f. **Problem:** unstable for general maxima ... hard to analyze.

Common idea: cluster data around high-density cores! ... Suppose the data $\{X_i\}_1^n \sim_{i.i.d.}$ some density f



MEAN-SHIFT: cores are *point-modes* (maxima) of *f*. **Problem:** unstable for general maxima ... hard to analyze.

Practical and Optimal estimator of general maxima of density f.



Difficulty: unknown location, dimension, shape Side benefits: applies beyond clustering (e.g. manifold denoising).

Practical subroutines: we'll traverse a k-NN graph over $\{X_i\}$



Practical and Optimal estimator of general maxima of density f.



Difficulty: unknown location, dimension, shape

Side benefits: applies beyond clustering (e.g. manifold denoising).

Practical subroutines: we'll traverse a k-NN graph over $\{X_i\}$



Practical and Optimal estimator of general maxima of density f.



Difficulty: unknown location, dimension, shape Side benefits: applies beyond clustering (e.g. manifold denoising).

Practical subroutines: we'll traverse a k-NN graph over $\{X_i\}$



Practical and Optimal estimator of general maxima of density f.



Difficulty: unknown location, dimension, shape Side benefits: applies beyond clustering (e.g. manifold denoising).

Practical subroutines: we'll traverse a k-NN graph over $\{X_i\}$



- How *k*-NN graphs relate to *f*. (groundwork) (with Chaudhuri, Dasgupta, von Luxburg, 2011, 2014)
- Estimating all modes of *f*. (first intuition ...) (with S. Dasgupta, 2014)
- Estimating all modal sets of *f*. (final intuition □) (with H. Jiang, 2017)

- How *k*-NN graphs relate to *f*. (groundwork) (with Chaudhuri, Dasgupta, von Luxburg, 2011, 2014)
- Estimating all modes of *f*. (first intuition ...) (with S. Dasgupta, 2014)
- Estimating all modal sets of *f*. (final intuition □) (with H. Jiang, 2017)

- How *k*-NN graphs relate to *f*. (groundwork) (with Chaudhuri, Dasgupta, von Luxburg, 2011, 2014)
- Estimating all modes of *f*. (first intuition ...) (with S. Dasgupta, 2014)
- Estimating all modal sets of *f*. (final intuition □) (with H. Jiang, 2017)

Characterize f by its *cluster-tree* [Hartigan 81]:



- [Cha., Das. 10]: first consistent estimator (extends single-linkage).
- [Kpo., vLux. 11]: Simple k-NN subgraphs + stronger consistency.

Characterize *f* by its *cluster-tree* [Hartigan 81]:



- [Cha., Das. 10]: first consistent estimator (extends single-linkage).
- [Kpo., vLux. 11]: Simple k-NN subgraphs + stronger consistency.

Characterize *f* by its *cluster-tree* [Hartigan 81]:



- [Cha., Das. 10]: first consistent estimator (extends single-linkage).
- [Kpo., vLux. 11]: Simple k-NN subgraphs + stronger consistency.

Characterize *f* by its *cluster-tree* [Hartigan 81]:



- [Cha., Das. 10]: first consistent estimator (extends single-linkage).
- [Kpo., vLux. 11]: Simple *k*-NN subgraphs + stronger consistency.









◆□▶ ◆圖▶ ◆臣▶ ◆臣▶ 三臣





◆□▶ ◆圖▶ ◆臣▶ ◆臣▶ ─ 臣



Theo. Let f uniformly cont. + mild conditions on $k = \Omega(\log n)$. Let C_1, C_2 be disjoint CCs of some $\{f \ge \lambda\}$. W.p $\to 1$, $C_1 \cap X^n$ and $C_2 \cap X^n$ are in disjoint CCs of a k-NN subgraph.

・ロット (雪) (日) (日) (日)



ヘロン 人間 とくほと 人口 と

Practical problem: spurious CCs due to data variability.



Practical problem: spurious CCs due to data variability. **Reconnect** using careful lookups to lower subgraphs. Consistency of *Reconnect* shown in [Cha., Das., Kpo., vLux. 14]

Many new refinements by various authors ...

S. Balakrishnan, L. Wasserman, A. Rinaldo, I. Steinwart, M. Belkin, Y.C. Chen, F. Chazal, J. Klëmëla, ...

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

- How k-NN graphs relate to f. (with Chaudhuri, Dasgupta, von Luxburg, 2011, 2014)
- Estimating all **modes** of f.

(with S. Dasgupta, 2014)

• Estimating all **modal sets** of *f*.

(with H. Jiang, 2017)



Rate-Optimal: single mode case ([S. Tsybakov, 90] ...). **Practical:** mean-shift (hard to analyze ... see [Genovesee, ... Wasserman et.al., 13], [Arias-Castro et.al., 13] on consistency) We derive a rate-optimal estimator based on *k*-NN graphs ...

(日)、



Rate-Optimal: single mode case ([S. Tsybakov, 90] ...). **Practical:** mean-shift (hard to analyze ... see [Genovesee, ... Wasserman et.al., 13], [Arias-Castro et.al., 13] on consistency) We derive a rate-optimal estimator based on *k*-NN graphs

・ロト ・ 理ト ・ ヨト ・ ヨト



Rate-Optimal: single mode case ([S. Tsybakov, 90] ...). **Practical:** mean-shift (hard to analyze ... see [Genovesee, ... Wasserman et.al., 13], [Arias-Castro et.al., 13] on consistency) We derive a rate-optimal estimator based on *k*-NN graphs ...

・ロト ・ 理 ト ・ ヨ ト ・ ヨ ト



Rate-Optimal: single mode case ([S. Tsybakov, 90] ...). **Practical:** mean-shift (hard to analyze ... see [Genovesee, ... Wasserman et.al., 13], [Arias-Castro et.al., 13] on consistency)

We derive a rate-optimal estimator based on k-NN graphs ...

・ 日 ・ ・ 一 ・ ・ ・ ・ ・ ・ ・ ・ ・ ・
Estimating all modes of f: What was known



Rate-Optimal: single mode case ([S. Tsybakov, 90] ...). **Practical:** mean-shift (hard to analyze ... see [Genovesee, ... Wasserman et.al., 13], [Arias-Castro et.al., 13] on consistency) We derive a rate-optimal estimator based on *k*-NN graphs ...

• k-NN density rates:

asymptotic $1/\sqrt{k}$ rates (e.g. [Biau, ..., Devroye et.al., 11]). We show high-prob. finite sample rates.

• Single mode:

Common estimator in theory: $\hat{x} = \arg \max_{x \in \mathbb{R}^d} \hat{f}(x)$. Practical estimator: $\tilde{x} = \arg \max_{x \in X_{1:n}} \hat{f}(x)$. Consistency of \tilde{x} [Abraham, Biau, Cadre, 04] We show that \tilde{x} is also minimax-optimal.

• Multiple modes:

Practical procedures (e.g. meanshift) are hard to analyze. Our procedure recovers *just* modes at optimal rates.

- 日本 - 1 日本 - 日本 - 日本

• *k*-NN density rates:

asymptotic $1/\sqrt{k}$ rates (e.g. [Biau, ..., Devroye et.al., 11]). We show high-prob. finite sample rates.

• Single mode:

Common estimator in theory: $\hat{x} = \arg \max_{x \in \mathbb{R}^d} f(x)$. Practical estimator: $\tilde{x} = \arg \max_{x \in X_{1:n}} \hat{f}(x)$. Consistency of \tilde{x} [Abraham, Biau, Cadre, 04] We show that \tilde{x} is also minimax-optimal.

• Multiple modes:

Practical procedures (e.g. meanshift) are hard to analyze. Our procedure recovers *just* modes at optimal rates.

- 日本 - 1 日本 - 日本 - 日本

• k-NN density rates:

asymptotic $1/\sqrt{k}$ rates (e.g. [Biau, ..., Devroye et.al., 11]). We show high-prob. finite sample rates.

Single mode:

Common estimator in theory: $\hat{x} = \arg \max_{x \in \mathbb{R}^d} \hat{f}(x)$.

Practical estimator: $\tilde{x} = \arg \max_{x \in X_{1:n}} f(x)$. Consistency of \tilde{x} [Abraham, Biau, Cadre, 04] We show that \tilde{x} is also minimax-optimal.

• Multiple modes:

Practical procedures (e.g. meanshift) are hard to analyze.

• k-NN density rates:

asymptotic $1/\sqrt{k}$ rates (e.g. [Biau, ..., Devroye et.al., 11]). We show high-prob. finite sample rates.

• Single mode:

Common estimator in theory: $\hat{x} = \arg \max_{x \in \mathbb{R}^d} \hat{f}(x)$. Practical estimator: $\tilde{x} = \arg \max_{x \in X_{1:n}} \hat{f}(x)$. Consistency of \tilde{x} [Abraham, Biau, Cadre, 04] We show that \tilde{x} is also minimax-optimal.

• Multiple modes:

Practical procedures (e.g. meanshift) are hard to analyze. Our procedure recovers *just* modes at optimal rates.

• k-NN density rates:

asymptotic $1/\sqrt{k}$ rates (e.g. [Biau, ..., Devroye et.al., 11]). We show high-prob. finite sample rates.

• Single mode:

Common estimator in theory: $\hat{x} = \arg \max_{x \in \mathbb{R}^d} \hat{f}(x)$. Practical estimator: $\tilde{x} = \arg \max_{x \in X_{1:n}} \hat{f}(x)$. Consistency of \tilde{x} [Abraham, Biau, Cadre, 04] We show that \tilde{x} is also minimax-optimal.

• Multiple modes:

Practical procedures (e.g. meanshift) are hard to analyze.

• k-NN density rates:

asymptotic $1/\sqrt{k}$ rates (e.g. [Biau, ..., Devroye et.al., 11]). We show high-prob. finite sample rates.

• Single mode:

Common estimator in theory: $\hat{x} = \arg \max_{x \in \mathbb{R}^d} \hat{f}(x)$. Practical estimator: $\tilde{x} = \arg \max_{x \in X_{1:n}} \hat{f}(x)$. Consistency of \tilde{x} [Abraham, Biau, Cadre, 04] We show that \tilde{x} is also minimax-optimal.

• Multiple modes:

Practical procedures (e.g. meanshift) are hard to analyze. Our procedure recovers *just* modes at optimal rates.

• k-NN density rates:

asymptotic $1/\sqrt{k}$ rates (e.g. [Biau, ..., Devroye et.al., 11]). We show high-prob. finite sample rates.

• Single mode:

Common estimator in theory: $\hat{x} = \arg \max_{x \in \mathbb{R}^d} \hat{f}(x)$. Practical estimator: $\tilde{x} = \arg \max_{x \in X_{1:n}} \hat{f}(x)$. Consistency of \tilde{x} [Abraham, Biau, Cadre, 04] We show that \tilde{x} is also minimax-optimal.

Multiple modes:

Practical procedures (e.g. meanshift) are hard to analyze.

Our procedure recovers *just* modes at optimal rates.

• k-NN density rates:

asymptotic $1/\sqrt{k}$ rates (e.g. [Biau, ..., Devroye et.al., 11]). We show high-prob. finite sample rates.

• Single mode:

Common estimator in theory: $\hat{x} = \arg \max_{x \in \mathbb{R}^d} \hat{f}(x)$. Practical estimator: $\tilde{x} = \arg \max_{x \in X_{1:n}} \hat{f}(x)$. Consistency of \tilde{x} [Abraham, Biau, Cadre, 04] We show that \tilde{x} is also minimax-optimal.

Multiple modes:

Practical procedures (e.g. meanshift) are hard to analyze. Our procedure recovers *just* modes at optimal rates. Sub-Outline:

• *k*-NN density rates

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

- Single mode rates
- Multiple modes rates

k-NN density estimate:

Define $r_k(x) \equiv$ distance from x to its kth neighbor in $X_{1:n}$.

$$f_k(x) \triangleq \frac{k}{n \cdot \operatorname{vol}\left(B(x, r_k(x))\right)} = \frac{k}{n \cdot v_d \cdot r_k(x)^d}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへで

k-NN density estimate:

Define $r_k(x) \equiv$ distance from x to its kth neighbor in $X_{1:n}$.

$$f_k(x) \triangleq \frac{k}{n \cdot \operatorname{vol}\left(B(x, r_k(x))\right)} = \frac{k}{n \cdot v_d \cdot r_k(x)^d}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへで

Finite sample rates for f_k :

 $\mathsf{W}.\mathsf{p}>1-\delta\text{, simult. }\forall x\in\mathsf{supp}(f)\text{, }\forall\epsilon>0\text{,}$

$$\left(1 - \frac{C_{n,\delta}}{\sqrt{k}}\right)(f(x) - \epsilon) \le f_k(x) \le \left(1 + \frac{C_{n,\delta}}{\sqrt{k}}\right)(f(x) + \epsilon),$$

provided log $\mathbf{n} \lesssim \mathbf{k} \lesssim r(\epsilon, x)^d \cdot (\mathbf{f}(\mathbf{x}) - \epsilon) \cdot \mathbf{n}.$

 $r(\epsilon,x)\equiv \sup\,\{r: \text{ on } B(x,r), f(\cdot)\approx f(x)+\epsilon\}.$

 \therefore optimal (local) rates under smoothness conditions. If f is α -Hölder at x:

$$|f_k(x) - f(x)| = O\left(n^{-\alpha/(2\alpha+d)}\right), \quad \text{ for } k = \Theta(n^{2\alpha/(2\alpha+d)}).$$

・ロ・・日・・日・・日・・日・

Finite sample rates for f_k :

 $\mathsf{W}.\mathsf{p}>1-\delta\text{, simult. }\forall x\in\mathsf{supp}(f)\text{, }\forall\epsilon>0\text{,}$

$$\left(1 - \frac{C_{n,\delta}}{\sqrt{k}}\right)(f(x) - \epsilon) \le f_k(x) \le \left(1 + \frac{C_{n,\delta}}{\sqrt{k}}\right)(f(x) + \epsilon),$$

provided log $\mathbf{n} \lesssim \mathbf{k} \lesssim r(\epsilon, x)^d \cdot (\mathbf{f}(\mathbf{x}) - \epsilon) \cdot \mathbf{n}.$

 $r(\epsilon,x) \equiv \sup{\{r: \text{ on } B(x,r), f(\cdot) \approx f(x) + \epsilon\}}.$

 \therefore optimal (local) rates under smoothness conditions. If f is α -Hölder at x:

$$|f_k(x) - f(x)| = O\left(n^{-\alpha/(2\alpha+d)}\right), \text{ for } k = \Theta(n^{2\alpha/(2\alpha+d)}).$$

◆□ > ◆□ > ◆□ > ◆□ > ◆□ > ◆□ >

Finite sample rates for f_k :

 $\mathsf{W}.\mathsf{p}>1-\delta\text{, simult. }\forall x\in\mathsf{supp}(f)\text{, }\forall\epsilon>0\text{,}$

$$\left(1 - \frac{C_{n,\delta}}{\sqrt{k}}\right)(f(x) - \epsilon) \le f_k(x) \le \left(1 + \frac{C_{n,\delta}}{\sqrt{k}}\right)(f(x) + \epsilon),$$

provided log $\mathbf{n} \lesssim \mathbf{k} \lesssim r(\epsilon, x)^d \cdot (\mathbf{f}(\mathbf{x}) - \epsilon) \cdot \mathbf{n}.$

 $r(\epsilon,x) \equiv \sup{\{r: \text{ on } B(x,r), f(\cdot) \approx f(x) + \epsilon\}}.$

 \therefore optimal (local) rates under smoothness conditions. If f is α -Hölder at x:

$$|f_k(x) - f(x)| = O\left(n^{-\alpha/(2\alpha+d)}\right), \quad \text{ for } k = \Theta(n^{2\alpha/(2\alpha+d)}).$$

Sub-Outline:

- k-NN density rates
- Single mode rates

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

• Multiple modes rates

Most commonly studied $\hat{x} = \arg \max_{x \in \mathbb{R}^d} f_n(x)$

Recursive estimates (One sample at a time)

[L. Devroye 79], [S. Tsybakov, 90 (optimal for Hölder classes.)]

Direct estimates (no density estimation)

 $\tilde{x} = \arg \max_{x \in X_{1:n}} f_k(x) = \arg \min_{x \in X_{1:n}} r_k(x).$ (Consistency, [Abraham, Biau, Cadre, 04]) Most commonly studied $\hat{x} = \arg \max_{x \in \mathbb{R}^d} f_n(x)$

Recursive estimates (One sample at a time)

[L. Devroye 79], [S. Tsybakov, 90 (optimal for Hölder classes.)]

- 日本 - 1 日本 - 日本 - 日本

Direct estimates (no density estimation)

 $ilde{x} = rg \max_{x \in X_{1:n}} f_k(x) = rg \min_{x \in X_{1:n}} r_k(x).$ (Consistency, [Abraham, Biau, Cadre, 04]) Most commonly studied $\hat{x} = \arg \max_{x \in \mathbb{R}^d} f_n(x)$

Recursive estimates (One sample at a time)

[L. Devroye 79], [S. Tsybakov, 90 (optimal for Hölder classes.)]

Direct estimates (no density estimation)

 $\tilde{x} = \arg \max_{x \in X_{1:n}} f_k(x) = \arg \min_{x \in X_{1:n}} r_k(x).$ (Consistency, [Abraham, Biau, Cadre, 04]) **A.1 (local):** $x = \arg \max f(x)$, $\exists \nabla^2 f$ on B(x), $\nabla^2 f(x) \prec 0$. **A.2 (global):** level sets of f have single CC.

Theorem. Let $\tilde{x} = \arg \max_{x \in X_{1:n}} f_k(x)$. W.h.p. we have $\|\tilde{x} - x\| \lesssim k^{-1/4}$, provided $\ln n \lesssim k \lesssim n^{4/(4+d)}$.

Constants depend on f(x) and $\nabla^2 f(x)$. (OPTIMAL, see Tsyb.90)

A.1 (local): $x = \arg \max f(x)$, $\exists \nabla^2 f$ on B(x), $\nabla^2 f(x) \prec 0$. A.2 (global): level sets of f have single CC.

Theorem. Let $\tilde{x} = \arg \max_{x \in X_{1:n}} f_k(x)$. W.h.p. we have $\|\tilde{x} - x\| \lesssim k^{-1/4}$, provided $\ln n \lesssim k \lesssim n^{4/(4+d)}$.

Constants depend on f(x) and $\nabla^2 f(x)$. (OPTIMAL, see Tsyb.90)

Proof idea:

There is a sample point at distance ≤ optimal rate.
∇² f(x) ≺ 0 : ∃ a level set A_x:

 $c ||x - x'||^2 \le f(x) - f(x') \le C ||x - x'||^2$

・ロト・日本・モト・モート ヨー うへで

Proof idea:

- There is a sample point at distance \leq optimal rate.
- $\nabla^2 f(x) \prec 0$: \exists a level set A_x :

$$c \|x - x'\|^2 \le f(x) - f(x') \le C \|x - x'\|^2.$$

・ロト・日本・モト・モート ヨー うへで

Proof idea:

- There is a sample point at distance \leq optimal rate.
- $\nabla^2 f(x) \prec 0$: \exists a level set A_x :

 $c \|x - x'\|^2 \le f(x) - f(x') \le C \|x - x'\|^2.$



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

 ${\small Sub-Outline:}$

- k-NN density rates
- Single mode rates

• Multiple modes rates

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

Setup:

Modes: $\mathcal{M} \equiv \{x : \exists r > 0, \forall x' \in B(x, r), f(x') < f(x)\}$. A.1 (local) $\forall x \in \mathcal{M}, \exists \nabla^2 f \text{ on } B(x), \nabla^2 f(x) \prec 0$. A.2 (global) Any CC of any level set of f contains a mode in \mathcal{M} .

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

ALGO: As f_k goes down, pick a new mode as a new *bump* appears.



Identifying CCs of level sets:

CCs of subgraphs of a k-NN graph [Chau., Das., Kpo., v Lux., 14] How to identify false modes in f_k ? Remove all *bumps* of height $\leq |f_k - f| \approx 1/\sqrt{k}$.

ALGO: As f_k goes down, pick a new mode as a new *bump* appears.



Identifying CCs of level sets:

CCs of subgraphs of a *k*-NN graph [Chau., Das., Kpo., v Lux., 14] How to identify false modes in f_k ? Remove all *bumps* of height $\leq |f_k - f| \approx 1/\sqrt{k}$.

ALGO: As f_k goes down, pick a new mode as a new *bump* appears.



Identifying CCs of level sets:

CCs of subgraphs of a k-NN graph [Chau., Das., Kpo., v Lux., 14] How to identify false modes in f_k ? Remove all *bumps* of height $\leq |f_k - f| \approx 1/\sqrt{k}$.

Identifying good modes



x is r-salient: separated from other modes by valley of thickness r.

Theorem. Suppose $x \in \mathcal{M}$ is *r*-salient. Let $n \ge N(x)$. W.h.p. $\exists \tilde{x} \in \mathcal{M}_n$ s.t.

 $\|\tilde{x} - x\| \lesssim k^{-1/4}$, provided $\ln n/r^4 \lesssim k \lesssim n^{4/(4+d)}$.

Constants depend on f(x) and $\nabla^2 f(x)$.

▲□▶ ▲圖▶ ▲厘▶ ▲厘▶ 厘 の��

Identifying good modes



x is r-salient: separated from other modes by valley of thickness r.

Theorem. Suppose $x \in \mathcal{M}$ is *r*-salient. Let $n \ge N(x)$. W.h.p. $\exists \tilde{x} \in \mathcal{M}_n$ s.t.

 $\|\tilde{x} - x\| \lesssim k^{-1/4}$, provided $\ln n/r^4 \lesssim k \lesssim n^{4/(4+d)}$.

Constants depend on f(x) and $\nabla^2 f(x)$.

Identifying good modes



x is r-salient: separated from other modes by valley of thickness r.

Theorem. Suppose $x \in \mathcal{M}$ is *r*-salient. Let $n \ge N(x)$. W.h.p. $\exists \tilde{x} \in \mathcal{M}_n$ s.t.

 $\|\tilde{x} - x\| \lesssim k^{-1/4}$, provided $\ln n/r^4 \lesssim k \lesssim n^{4/(4+d)}$.

Constants depend on f(x) and $\nabla^2 f(x)$.

Pruning bad modes

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Theorem 4. Suppose f is Lipschitz. Let $k \ge \ln n$. All modes in \mathcal{M}_n at f_k -level $\lambda > \lambda_k \approx 1/k$ can be assigned to *distinct* modes in \mathcal{M} at f-level $\approx \lambda$.

Outline:

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

- How k-NN graphs relate to f. (with Chaudhuri, Dasgupta, von Luxburg, 2011, 2014)
- Estimating all modes of f.

(with S. Dasgupta, 2014)

• Estimating all **modal sets** of *f*.

(with H. Jiang, 2017)

Estimating all modal sets of f.



Here: Regions of locally high-density ...

Point-modes (0-dimensional), and more general connected sets.

・ロト ・四ト ・ヨト ・ヨ

Related to topological data analysis Manifold + noise, low-dimensional ridge, ... etc

Estimating all modal sets of f.



Here: **Regions** of locally high-density ... Point-modes (0-dimensional), and more general connected sets.

- 日本 - 1 日本 - 日本 - 日本

Related to topological data analysis Manifold + noise, low-dimensional ridge, ... etc
Estimating all modal sets of f.



Here: **Regions** of locally high-density ... Point-modes (0-dimensional), and more general connected sets.

Related to topological data analysis

Manifold + noise, low-dimensional ridge, ... etc

Estimating general modal-sets M:

 $M \equiv$ Region of \mathbb{R}^d where f is locally maximal. $\widehat{M} \equiv$ samples x s.t. $|\max f_k - f_k(x)| \approx \max f_k / \sqrt{k}$.



Needs local pruning! (Else some \widehat{M} have wrong dimension).

◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 _ のへで

Estimating general modal-sets *M*:

 $M \equiv$ Region of \mathbb{R}^d where f is locally maximal. $\widehat{M} \equiv$ samples x s.t. $|\max f_k - f_k(x)| \approx \max f_k / \sqrt{k}$.



Needs local pruning! (Else some \widehat{M} have wrong dimension).

▲□▶ ▲圖▶ ▲匡▶ ▲匡▶ ― 臣 … のへで

Estimating general modal-sets *M*:

 $M \equiv$ Region of \mathbb{R}^d where f is locally maximal. $\widehat{M} \equiv$ samples x s.t. $|\max f_k - f_k(x)| \approx \max f_k/\sqrt{k}$.



Needs local pruning! (Else some \widehat{M} have wrong dimension).

Estimating general modal-sets *M*:

 $M \equiv$ Region of \mathbb{R}^d where f is locally maximal. $\widehat{M} \equiv$ samples x s.t. $|\max f_k - f_k(x)| \approx \max f_k/\sqrt{k}$.



Needs local pruning! (Else some \widehat{M} have wrong dimension).

・ロト ・ 母ト ・ ヨト ・ ヨト

Key change in analysis:

f might not be smooth at boundary of M

However, if f is uniformly continuous on some B(M, r), then for all $x \in B(M, r)$,

$L(d(x,M)) \le f_M - f(x) \le U(d(x,M))$

for some $L(\cdot), U(\cdot)$ increasing on $[0, \infty)$, 0 at 0.

Key change in analysis:

f might not be smooth at boundary of M

However, if f is uniformly continuous on some B(M,r), then for all $x \in B(M,r)$,

 $L(d(x,M)) \le f_M - f(x) \le U(d(x,M))$

for some $L(\cdot), U(\cdot)$ increasing on $[0, \infty)$, 0 at 0.

Key change in analysis:

f might not be smooth at boundary of M

However, if f is uniformly continuous on some B(M,r), then for all $x\in B(M,r),$

 $L(d(x,M)) \le f_M - f(x) \le U(d(x,M))$

for some $L(\cdot), U(\cdot)$ increasing on $[0, \infty)$, 0 at 0.



Theorem. The following holds w.h.p. Suppose M is r-salient. Let $n \ge N(M, r)$. We recover an \widehat{M} s.t.

$$\begin{split} &d_{\mathsf{Hausdorff}}(\widehat{M}, M) \lesssim L^{-1}(f_M/\sqrt{k}), \\ &\text{provided log } \mathbf{n}/L^2(r) \lesssim \mathbf{k} \lesssim \left(U^{-1}(f_M/\sqrt{k})\right)^d \cdot \mathbf{n}. \end{split}$$



Theorem. The following holds w.h.p. Suppose M is r-salient. Let $n \ge N(M, r)$. We recover an \widehat{M} s.t.

 $d_{\text{Hausdorff}}(\widehat{M}, M) \lesssim L^{-1}(f_M/\sqrt{k}),$ provided log $\mathbf{n}/L^2(r) \lesssim \mathbf{k} \lesssim \left(U^{-1}(f_M/\sqrt{k})\right)^d \cdot \mathbf{n}.$



Theorem. The following holds w.h.p. Suppose M is r-salient. Let $n \ge N(M, r)$. We recover an \widehat{M} s.t.

$$\begin{split} &d_{\mathsf{Hausdorff}}(\widehat{M},M) \lesssim L^{-1}(f_M/\sqrt{k}), \\ &\text{provided log } \mathbf{n}/L^2(r) \lesssim \mathbf{k} \lesssim \left(U^{-1}(f_M/\sqrt{k})\right)^d \cdot \mathbf{n}. \end{split}$$



Theorem. The following holds w.h.p. Suppose M is r-salient. Let $n \ge N(M, r)$. We recover an \widehat{M} s.t.

$$\begin{split} &d_{\mathsf{Hausdorff}}(\widehat{M},M) \lesssim L^{-1}(f_M/\sqrt{k}), \\ &\text{provided log } \mathbf{n}/L^2(r) \lesssim \mathbf{k} \lesssim \left(U^{-1}(f_M/\sqrt{k})\right)^d \cdot \mathbf{n}. \end{split}$$

Clustering procedure:

QuickShift ++

- Estimate modal-sets M_1, M_2, \ldots, M_K ;
- Assign every point x (by gradient ascent) to some M_i : Follow sample path $x_0 \rightarrow x_1 \rightarrow x_2 \dots \rightarrow M_t$, $\dots x_{t+1} \equiv$ closest point to x_t s.t. $f(x_{t+1}) > f(x_t)$

Clustering procedure:

QuickShift ++

- Estimate modal-sets M_1, M_2, \ldots, M_K ;
- Assign every point x (by gradient ascent) to some M_i : Follow sample path $x_0 \to x_1 \to x_2 \ldots \rightsquigarrow M_i$,

... $x_{t+1} \equiv \text{closest point to } x_t \text{ s.t. } f(x_{t+1}) > f(x_t)$

Clustering procedure:

QuickShift ++

- Estimate modal-sets M_1, M_2, \ldots, M_K ;
- Assign every point x (by gradient ascent) to some M_i: Follow sample path x₀ → x₁ → x₂... → M_i, ... x_{t+1} ≡ closest point to x_t s.t. f(x_{t+1}) > f(x_t)

More experiments on UCI datasets:

| Data/ Algo | DBSCAN | MnShift | QkShift | QkShift++ |
|-------------|--------|---------|---------|-----------|
| seeds | 0.4473 | 0.7319 | 0.6715 | 0.7261 |
| | 0.4429 | 0.6769 | 0.6360 | 0.7085 |
| phonemes | 0.6333 | 0.5732 | 0.7653 | 0.7663 |
| | 0.7280 | 0.5396 | 0.7954 | 0.8019 |
| banknote | 0.5584 | 0.2434 | 0.3318 | 0.6152 |
| | 0.4594 | 0.2351 | 0.3397 | 0.4866 |
| images | 0.3313 | 0.3497 | 0.4077 | 0.5359 |
| | 0.5264 | 0.4656 | 0.5364 | 0.6456 |
| letters | 0.0460 | 0.1506 | 0.1335 | 0.2128 |
| | 0.2338 | 0.3457 | 0.3706 | 0.4122 |
| page blocks | 0.0132 | 0.0028 | 0.0925 | 0.4727 |
| | 0.0578 | 0.0526 | 0.0397 | 0.2192 |

Clustering scores are: Mutual information, and Rand-Index.

Sensitivity to tuning parameters.



(Blue) Mutual Information score, (Red) Rand-index score

▲□▶ ▲□▶ ▲注▶ ▲注▶ ……注: のへ(?).

We've started investigating related applications ...

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

- Medical imaging (detecting low-d structures).
- Image segmentation (detecting object boundaries).
- Internet of Things (outlier detection).

We've started investigating related applications ...

- Medical imaging (detecting low-*d* structures).
- Image segmentation (detecting object boundaries).
- Internet of Things (outlier detection).

Unsupervised Image Segmentation



Figure: Best tradeoff between over and under segmentation.

- Adaptive (data-driven) choices of hyperparameters.
- High-dimensional clustering: Feature selection, spectral and projection methods.

That's all. Thanks!

▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ ―臣 … のへで

- Adaptive (data-driven) choices of hyperparameters.
- High-dimensional clustering: *Feature selection, spectral and projection* methods.

That's all. Thanks!

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

- Adaptive (data-driven) choices of hyperparameters.
- High-dimensional clustering: Feature selection, spectral and projection methods.

That's all. Thanks!

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

- Adaptive (data-driven) choices of hyperparameters.
- High-dimensional clustering: Feature selection, spectral and projection methods.

That's all. Thanks!

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ